

2/27/14

①

MRF SEMANTICS

① I-map

→ Same concept & definition as BNs

$I(G) = \{ \text{Set of independence assumptions encoded in } G \}$
 $= \{ (X \perp Y | Z) : X \text{ \& } Y \text{ are separated in } G \text{ given } Z \}$

Now, G is an I-map of P
iff $I(G) \subseteq I(P)$

② P-MAP

G is a P-map of P iff $I(G) = I(P)$

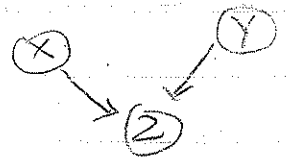
G encodes exactly the independencies in P
No more, no less

Do P-maps exist $\forall P$? No!

Consider $I(P) = \{ (X \perp Y) \}$

Note $(X \perp Y | Z) \notin I(P)$

Such a distribution has a P-map in BNs:



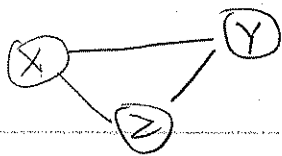
But can't represent this as a MN:

→ attempt #1 $\begin{matrix} X & Y \\ \searrow & \swarrow \\ & Z \end{matrix}$ but $X \perp Z \in I(G)$

⇒

$\notin I(P)$
 G is not an I-map

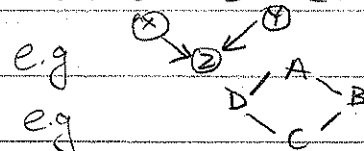
→ attempt #2



$ICG = \emptyset$ so G is an I-map
but not a P-map

So overall, there are distributions P that have

→ P-maps in BNs but not in MNs



→ P-maps in MNs but not in BNs

e.g.

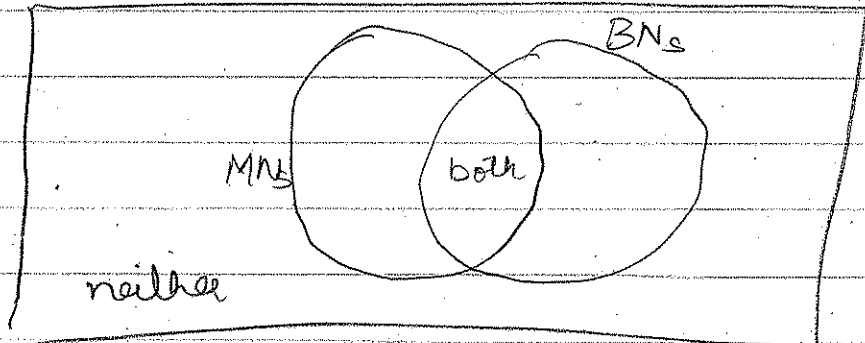
→ P-maps in both BNs & MNs

e.g. $X - Y$
 $X \rightarrow Y$
 $X \leftarrow Y$

→ P-maps in neither BNs nor MN!

[Trickier to construct but exist; see HW]

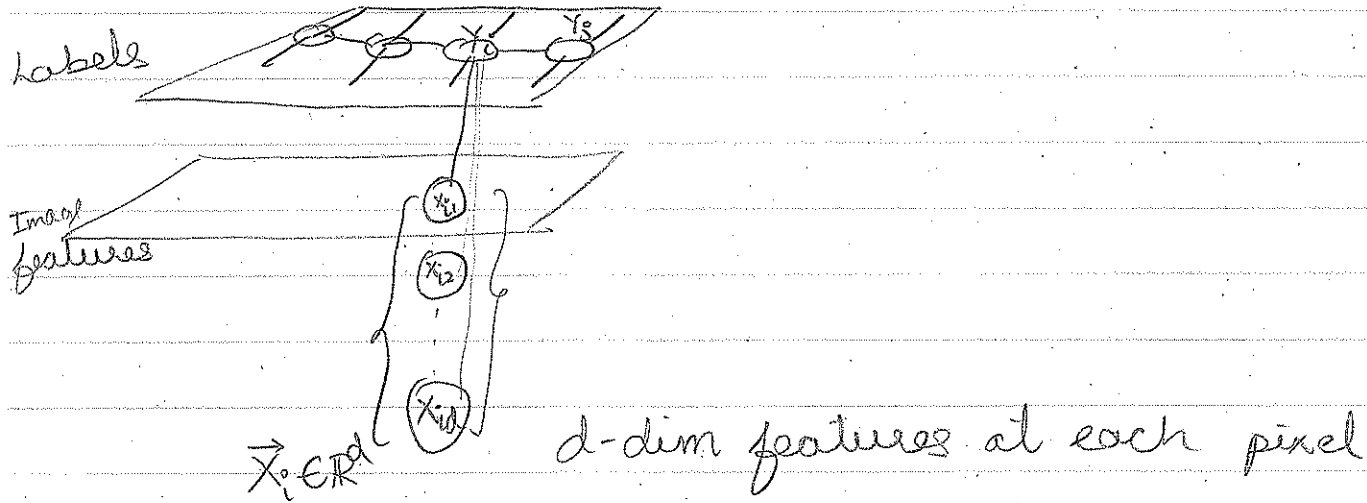
"Qualitative" Venn diagram



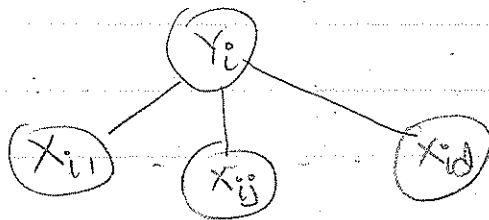
All distributions

③ Conditional Random Fields

Consider an image labeling task



If there was only 1 pixel in the image:



Looks like NB [Actually make the same assumptions]

Recall that NB models $P(x_{i1}, \dots, x_{id}, y_i)$

↳ Logistic Regression models $P(y_i | x_{i1}, \dots, x_{id})$

The conversion from MRFs to CRFs is analogous

MRFs model the joint distribution

$$P(\vec{x}_1, \dots, \vec{x}_n, y_1, \dots, y_n) = \frac{1}{Z} \underbrace{\prod_{i,d} \Phi_i(x_{id}, y_i) \prod_{i,j} \Phi_{ij}(y_i, y_j)}_{\text{Pairwise MRF}}$$

Notice $\Phi(\vec{x}_i, y_i) \neq \Phi(x_{id}, y_i)$
 $= \underbrace{\Phi(x_{i1}, \dots, x_{id}, y_i)}_{\text{High-Order Factor}} \underbrace{\phantom{\Phi(x_{i1}, \dots, x_{id}, y_i)}}_{\text{Pairwise-factor}}$

Notice $Z = \sum_{\substack{x_{i1}, \dots, x_{id} \\ i \in \{1, \dots, n\}}} \sum_{y_1, \dots, y_n} \prod_i \prod_d (\cdot) \prod_{i,j} (\cdot)$

assuming discrete features

or $\int_{x_{i1}} \dots \int_{x_{id}} \dots$ if continuous

CRFs only compute

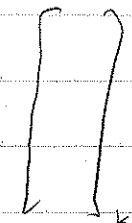
$$Z(\vec{x}_1, \dots, \vec{x}_n) = \sum_{y_1, \dots, y_n} \prod_i \prod_d \Phi_{id}(x_{id}, y_i) \prod_{i,j} \Phi_{ij}(y_i, y_j)$$

Z as a function of input
 Different for each image!

Now $P(y_1, \dots, y_n | \vec{x}_1, \dots, \vec{x}_n) = \frac{1}{Z(\vec{x}_1, \dots, \vec{x}_n)} \prod (\cdot)$
 CRF!

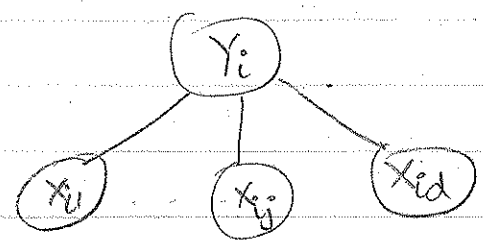
3

So why should you care?

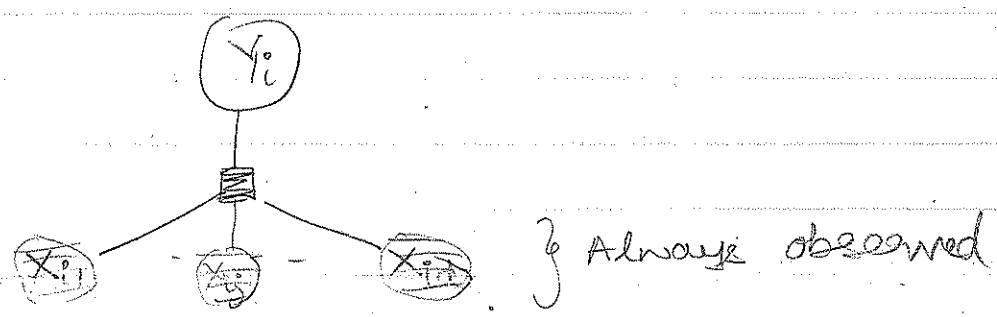
Because note: $\Phi_{id}(x_{id} = \bar{x}_{id}, Y_i) =$ 
Node potential over Y_i

Moreover $\Phi_i(\vec{X}_i = \vec{x}_i, Y_i) \equiv$ also just a node potential

So an MRF (just like NB) was forced to make restrictive assumptions



But a CRF (just like a LR) can extract arbitrary information from \vec{X}_i



In fact $\Phi_i(Y_i)$ can look at features for the ENTIRE image

$\Phi_i(Y_i) \equiv \Phi(Y_i, \vec{X}_1, \dots, \vec{X}_n)$
still a node potential

④ Log-Linear Models

$$\text{Consider an MRF/CRF: } P(Y_1, \dots, Y_n) = \frac{1}{Z} \prod_c \Phi_c(Y_c)$$

Notice that $\Phi_c(Y_c)$ is always > 0
 \Rightarrow I can express it as $e^{\log \Phi_c(Y_c)}$

$$\text{We define } E_c(Y_c) = -\log \Phi_c(Y_c)$$

↳
"energy" term

$$\begin{aligned} \text{So } P(Y_1, \dots, Y_n) &\propto e^{-\sum_c E_c(Y_c)} \\ &= \frac{1}{Z} e^{-\sum_c E_c(Y_c)} \\ &= \frac{1}{Z} e^{-\sum_c E_c(Y_c) - \log Z} \\ &= e \end{aligned}$$

$$\sum_c E_c(Y_c) = \sum_i E_i(Y_i) + \sum_{i,j} E_{ij}(Y_i, Y_j)$$

↑
for pairwise MRFs

↳ Energy function: term comes from statistical physics

$$\text{Also } \operatorname{argmax}_{Y_1, \dots, Y_n} P(Y_1, \dots, Y_n) = \operatorname{argmin}_{Y_1, \dots, Y_n} \sum_c E_c(Y_c)$$

MAP Inference \equiv Energy Minimization

(4)

Now in log-space, it is common to represent

$$E_c(Y_c) = \underbrace{\vec{w}_c^T}_{\text{weigh}} \underbrace{\vec{f}(Y_c)}_{\text{feature}}$$

log-linear model $P(Y_1, \dots, Y_n) \propto e^{-\sum_c w_c^T f_c(Y_c)}$

Example of \vec{w}_c & \vec{f}_c ?

→ MRF: $\vec{f}_c(Y_c) \equiv$ indicator vector for state

$$\text{ex } f_i(Y_i) = \begin{bmatrix} 1[\![Y_i=0]\!] \\ 1[\![Y_i=1]\!] \end{bmatrix}$$

Now $E_i(Y_i=0) = [w_0 \ w_1] \begin{bmatrix} 1 \\ 0 \end{bmatrix} = w_0$

$$E_i(Y_i=1) = [w_0 \ w_1] \begin{bmatrix} 0 \\ 1 \end{bmatrix} = w_1$$

→ CRF: $f_i(Y_i) = \begin{bmatrix} 1[\![Y_i=0]\!] \cdot \Phi(\vec{x}) \\ 1[\![Y_i=1]\!] \cdot \Phi(\vec{x}) \end{bmatrix}_{2d \times 1}$ $\Phi(x) \in \mathbb{R}^d$

↙ some feature of data

$$\vec{w}_i = \begin{bmatrix} \vec{w}_{i0} \in \mathbb{R}^d \\ \vec{w}_{i1} \in \mathbb{R}^d \end{bmatrix}$$

$$E_i(Y_i=0) = \vec{w}_{i0}^T \Phi(\vec{x}) = \text{Score of category 0} = \text{Energy}$$

$$E_i(Y_i=1) = \vec{w}_{i1}^T \Phi(\vec{x}) = \text{Score of category 1} = \text{Energy}$$

