

\* Component of  $F$  due to correlated noise of  $\hat{v}_g$  to  $\hat{v}_d$

$$\overline{v_s^2} = 4kTR_s \Delta f$$

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$$\overline{\hat{v}_d^2} = 4kT \frac{r_{gm}}{\alpha} \Delta f$$

$$\overline{\hat{v}_g^2} = 4kT \frac{g_{gs}}{\alpha} \Delta f$$

$$g_{gs} = \frac{w^2 c_{gs}^2}{5g_{d0}} = \alpha \frac{w^2 c_{gs}^2}{5 \cdot g_{m}}$$

$$\sqrt{\overline{\hat{v}_g^2} \cdot \overline{\hat{v}_d^2}} = 4kT \sqrt{\frac{\delta \cdot r}{\alpha}} g_m \alpha \frac{1}{5g_m} - w c_{gs} \Delta f$$

$$= 4kT w c_{gs} \sqrt{\frac{\delta \cdot r}{5}} \Delta f$$

$\Rightarrow$  correlated noise

$$= \left( \frac{wT}{j\omega} \right) \left( 4kT w c_{gs} \sqrt{\frac{\delta \cdot r}{5}} \right) \cdot \frac{c}{2} \Delta f$$

$\Rightarrow$  component of  $F$  due to correlated noise

$$= \frac{\left( \frac{wT}{j\omega} \right) 4kT w c_{gs} \sqrt{\frac{\delta \cdot r}{5}} \cdot \frac{c}{2} \Delta f}{4R_s^2 \left( \frac{wT}{\omega} \right)^2 \cdot 4kTR_s \Delta f}$$

$$= \left( \frac{3}{j\omega T} \right) 2c \frac{R_s w c_{gs}}{5} \sqrt{\frac{\delta \cdot r}{5}}$$

$$= \left( \frac{3}{j\omega T} \right) 2k \frac{1}{2Q} \sqrt{\frac{\delta \cdot r}{5}}$$

$$F \Big|_{\text{due to correlated } \hat{v}_g} = \frac{|k|}{Q} \left( \frac{w}{\omega T} \right) \sqrt{\frac{\delta \cdot r}{5}}$$

(\*)