

**EECS 142**



Integrated Circuits for Communication

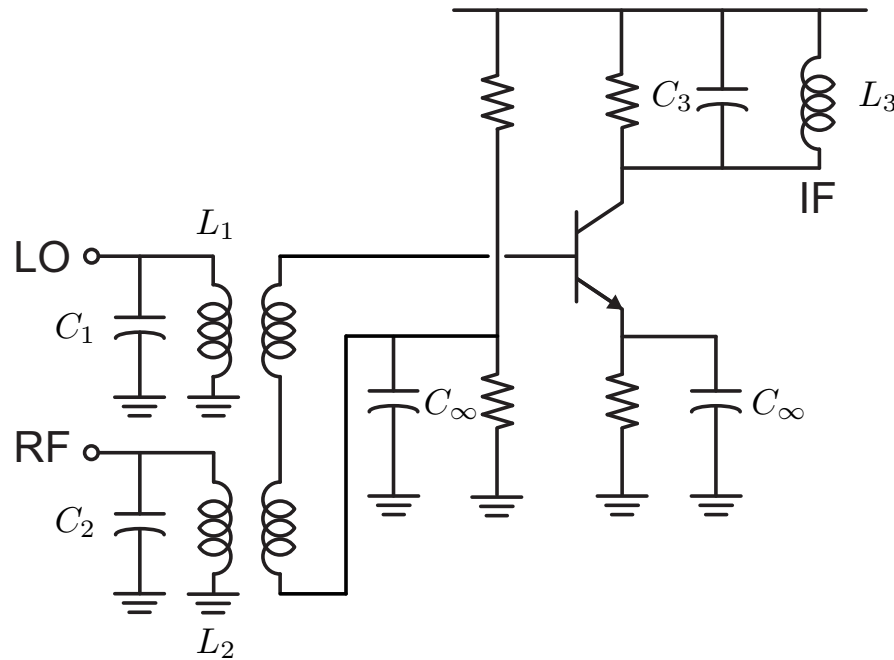
## ***Lecture 17: BJT/FET Mixers/Mixer Noise***

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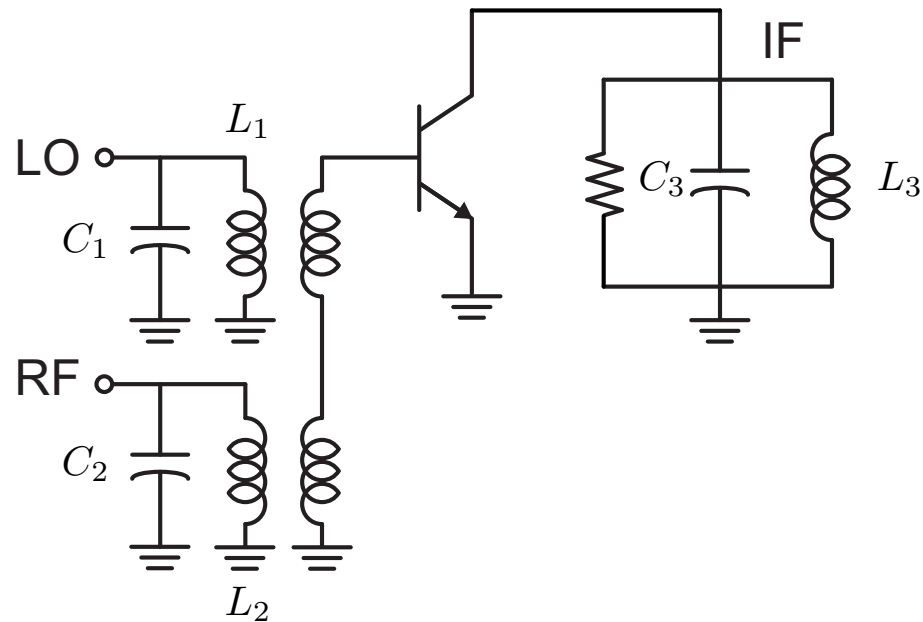
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# A BJT Mixer



- The transformer is used to sum the LO and RF signals at the input. The winding inductance is used to form resonant tanks at the LO and RF frequencies.
- The output tank is tuned to the IF frequency.
- Large capacitors are used to form AC grounds.

# AC Eq. Circuit



• The AC equivalent circuit is shown above.

# BJT Mixer Analysis

- When we apply the LO alone, the collector current of the mixer is given by

$$I_C = I_Q \left( 1 + \frac{2I_1(b)}{I_0(b)} \cos \omega t + \frac{2I_2(b)}{I_0(b)} \cos 2\omega t + \dots \right)$$

- We can therefore define a time-varying  $g_m(t)$  by

$$g_m(t) = \frac{I_C(t)}{V_t} = \frac{qI_C(t)}{kT}$$

- The output current when the RF is also applied is therefore given by  $i_C(t) = g_m(t)v_s$

$$i_C = \frac{qI_Q}{kT} \left( 1 + \frac{2I_1(b)}{I_0(b)} \cos \omega t + \frac{2I_2(b)}{I_0(b)} \cos 2\omega t + \dots \right) \times \hat{V}_s \cos \omega_s t$$

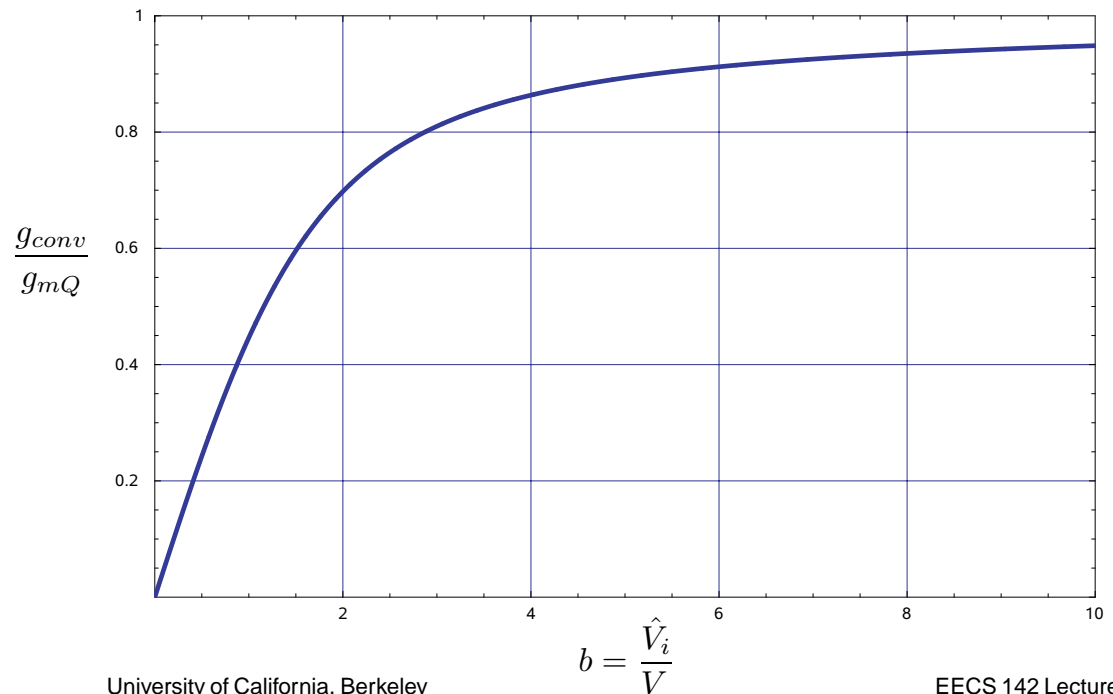
# BJT Mixer Analysis (cont)

- The output at the IF is therefore given by

$$i_C|_{\omega_{IF}} = \hat{V}_s \underbrace{\frac{qI_Q}{kT}}_{g_{mQ}} \frac{I_1(b)}{I_0(b)} \cos(\underbrace{\omega_0 - \omega_s}_{\omega_{IF}})t$$

- The conversion gain is given by

$$g_{conv} = g_{mQ} \frac{I_1(b)}{I_0(b)}$$



# LO Signal Drive

- For now, let's ignore the small-signal input and determine the impedance seen by the LO drive. If we examine the collector current

$$I_C = I_Q \left( 1 + \frac{2I_1(b)}{I_0(b)} \cos \omega t + \frac{2I_2(b)}{I_0(b)} \cos 2\omega t + \dots \right)$$

- The base current is simply  $I_C/\beta$ , and so the input impedance seen by the LO is given by

$$\begin{aligned} Z_i|_{\omega_0} &= \frac{\hat{V}_o}{i_{B,\omega_0}} = \frac{\beta \hat{V}_o}{i_{C,\omega_0}} = \frac{\beta \hat{V}_o}{I_Q \frac{2I_1(b)}{I_0(b)}} = \frac{\beta b V_t}{I_Q \frac{2I_1(b)}{I_0(b)}} \\ &= \frac{b}{2} \frac{\beta}{g_{mQ}} \frac{I_0(b)}{I_1(b)} = \frac{\beta}{G_m} \end{aligned}$$

# RF Signal Drive

- The impedance seen by the RF signal source is also the base current at the  $\omega_s$  components. Typically, we have a high-Q circuit at the input that resonates at RF.

$$i_B(t) = \frac{i_C(t)}{\beta}$$

$$= \frac{1}{\beta} \frac{qI_Q}{kT} \left( \hat{V}_s \cos \omega_s t + \frac{2I_1(b)}{I_0(b)} \cos(\omega_0 \pm \omega_s)t + \dots \right)$$

- The input impedance is thus the same as an amplifier

$$R_{in} = \frac{\hat{V}_s}{|\text{component in } i_B \text{ at } \omega_s|} = \beta \frac{kT}{qI_Q} = \frac{\beta}{g_{mQ}}$$

# Mixer Analysis: General Approach

- If we go back to our original equations, our major assumption was that the mixer is a linear time-varying function relative to the RF input. Let's see how that comes about

$$I_C = I_S e^{v_{BE}/V_t}$$

where

$$v_{BE} = v_{in} + v_o + V_A$$

or

$$I_C = I_S e^{V_A/V_t} \times e^{b \cos \omega_0 t} \times e^{\frac{\hat{V}_s}{V_t} \cos \omega_s t}$$

- If we assume that the RF signal is weak, then we can approximate  $e^x \approx 1 + x$



# General Approach (cont)

- Now the output current can be expanded into

$$I_C = I_Q \left( 1 + \frac{2I_1(b)}{I_0(b)} \cos \omega t + \frac{2I_2(b)}{I_0(b)} \cos 2\omega t + \dots \right) \\ \times \left( 1 + \frac{\hat{V}_s}{V_t} \cos \omega_s t \right)$$

- In other words, the output can be written as

$$= \text{BIAS} + \text{LO} + \text{Conversion Products}$$

- In general we would filter the output of the mixer and so the  $LO$  terms can be minimized. Likewise, the RF terms are undesired and filtered from the output.

# Distortion in Mixers

- Using the same formulation, we can now insert a signal with two tones

$$v_{in} = \hat{V}_{s1} \cos \omega_{s1} t + \hat{V}_{s2} \cos \omega_{s2} t$$

$$I_C = I_S e^{V_A/V_t} \times e^{b \cos \omega_0 t} \times e^{\frac{\hat{V}_{s1}}{V_t} \cos \omega_{s1} t + \frac{\hat{V}_{s2}}{V_t} \cos \omega_{s2} t}$$

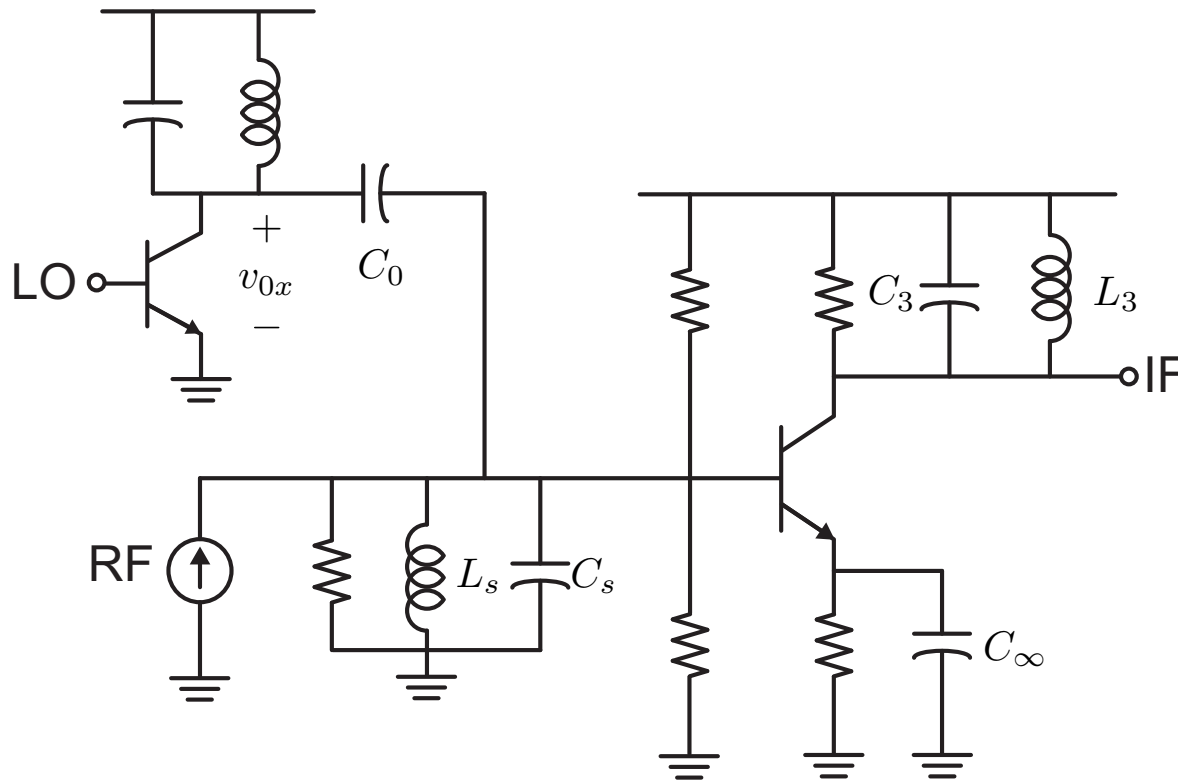
- The final term can be expanded into a Taylor series

$$I_C = I_S e^{V_A/V_t} \times e^{b \cos \omega_0 t} \times$$

$$(1 + \frac{\hat{V}_{s1}}{V_t} \cos \omega_{s1} t + \frac{\hat{V}_{s2}}{V_t} \cos \omega_{s2} t + \frac{1}{2} \left( \frac{\hat{V}_{s1}}{V_t} \cos \omega_{s1} t \right)^2 + \frac{1}{2} \left( \frac{\hat{V}_{s2}}{V_t} \cos \omega_{s2} t \right)^2 + \dots)$$

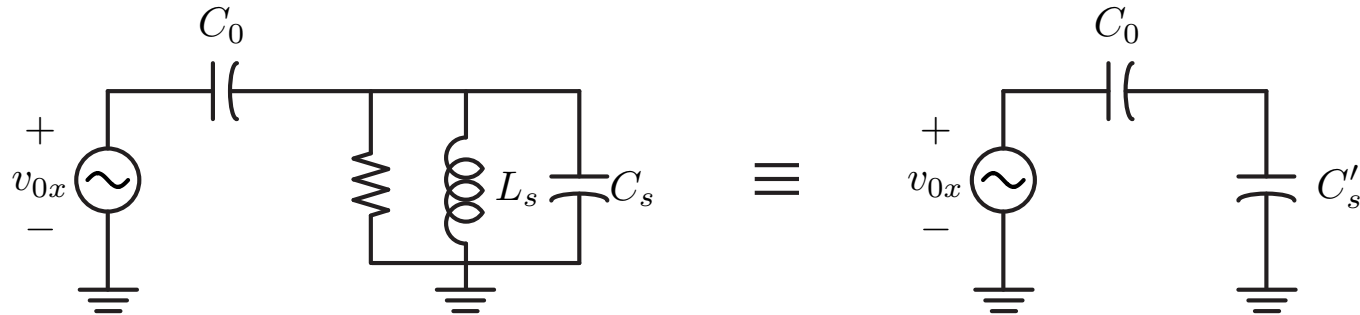
- The square and cubic terms produce  $IM$  products as before, but now these products are frequency translated to the IF frequency

# Another BJT Mixer



- The signal from the LO driver is capacitively coupled to the BJT mixer

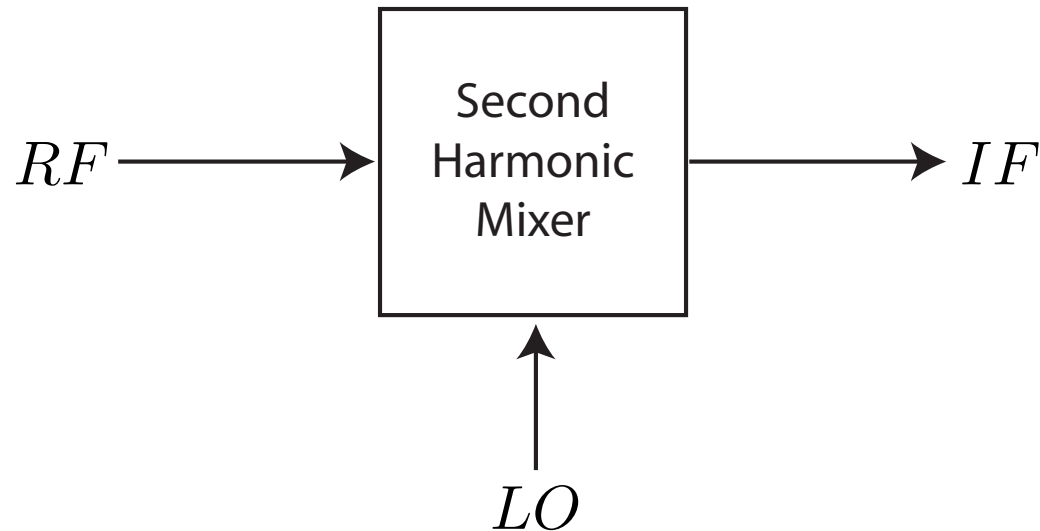
# LO Capacitive Divider



- Assume that  $\omega_{LO} > \omega_{RF}$ , or a high side injection
- Note beyond resonance, the input impedance of the tank appears capacitive. Thus  $C'_s$  is the effective capacitance of the tank. The equivalent circuit for the LO drive is therefore a capacitive divider

$$v_o = \frac{C_o}{C_o + C'_s} v_{ox}$$

# Harmonic Mixer



- We can use a harmonic of the LO to build a mixer.
- Example, let  $LO = 500\text{MHz}$ ,  $RF = 900\text{MHz}$ , and  $IF = 100\text{MHz}$ .
- Note that  $IF = 2LO - RF = 1000 - 900 = 100$

# Harmonic Mixer Analysis

- The  $n$ th harmonic conversion transconductance is given by

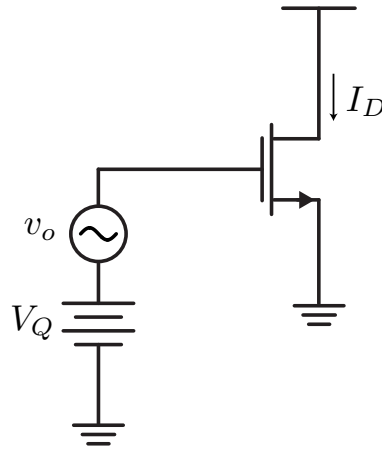
$$g_{conv,n} = \frac{|\text{IF current out}|}{|\text{input signal voltage}|} = \frac{g_n}{2}$$

- For a BJT, we have

$$g_{conv,n} = g_{mQ} \frac{I_n(b)}{I_0(b)}$$

- The advantage of a harmonic mixer is the use of a lower frequency LO and the separation between LO and RF.
- The disadvantage is the lower conversion gain and higher noise.

# FET Large Signal Drive

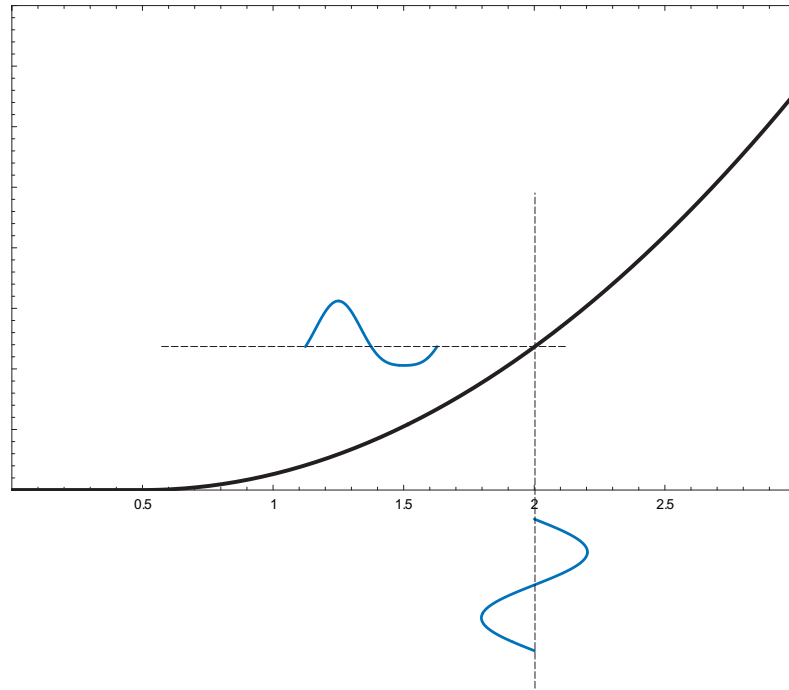


- Consider the output current of a FET driven by a large LO signal

$$I_D = \frac{\mu C_{ox}}{2} \frac{W}{L} (V_{GS} - V_T)^2 (1 + \lambda V_{DS})$$

- where  $V_{GS} = V_A + v_{LO} = V_A + V_o \cos \omega_0 t$ . Here we implicitly assume that  $V_o$  is small enough such that it does not take the device into cutoff.

# FET Large Signal Drive (cont)



- That means that  $V_A + V_0 \cos \omega_0 t > V_T$ , or  $V_A - V_0 > V_T$ , or equivalently  $V_0 < V_A - V_T$ . Under such a case we expand the current

$$I_D \propto ((V_A - V_T)^2 + V_0 \cos^2 \omega_0 t + 2(V_A - V_T)V_0 \cos \omega_0 t)$$



# FET Current Components

- The  $\cos^2$  term can be further expanded into a DC and second harmonic term.
- Identifying the quiescent operating point

$$I_Q = \frac{\mu C_{ox}}{2} \frac{W}{L} (V_A - V_T)^2 (1 + \lambda V_{DS})$$

$$I_D = I_{DQ} + \mu C_{ox} \frac{W}{L} \left( \underbrace{\frac{1}{4} V_0^2}_{\text{bias point shift}} + \underbrace{(V_A - V_T) V_o \cos \omega_0 t}_{\text{LO modulation}} + \underbrace{\frac{V_0^2}{4} \cos^2 \omega_0 t}_{\text{LO 2nd harmonic}} \right) (1 + \lambda V_{DS})$$

# FET Time-Varying Transconductance

- The transconductance of a FET is given by (assuming strong inversion operation)

$$g(t) = \frac{\partial I_D}{\partial V_{GS}} = \mu C_{ox} \frac{W}{L} (V_{GS} - V_T)(1 + \lambda V_{DS})$$

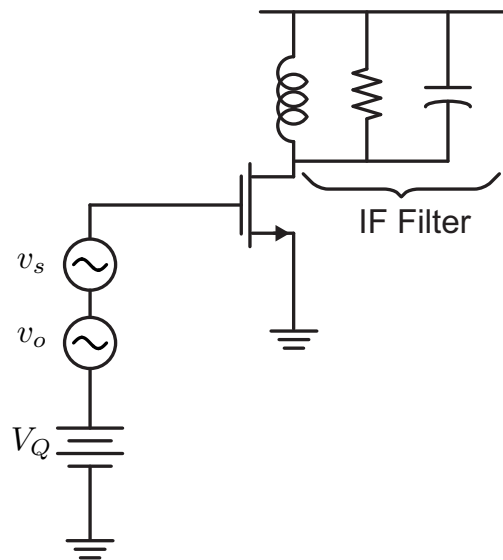
$$V_{GS}(t) = V_A + V_0 \cos \omega_0 t$$

$$g(t) = \mu C_{ox} \frac{W}{L} (V_A - V_T + V_0 \cos \omega_0 t)(1 + \lambda V_{DS})$$

$$g(t) = g_{mQ} \left( 1 + \frac{V_0}{V_A - V_T} \cos \omega_0 t \right) (1 + \lambda V_{DS})$$

- This is an almost ideal mixer in that there is no harmonic components in the transconductance.

# MOS Mixer



● We see that we can build a mixer by simply injecting an  $LO + RF$  signal at the gate of the FET (ignore output resistance)

$$i_0 = g(t)v_s = g_{mQ} \left( 1 + \frac{V_0}{V_A - V_T} \cos \omega_0 t \right) V_s \cos \omega_s t$$

$$i_0|_{IF} = \frac{g_{mQ}}{2} \frac{V_0}{V_A - V_T} \cos(\omega_0 \pm \omega_s)t V_s$$

$$g_c = \frac{i_0|_{IF}}{V_s} = \frac{g_{mQ}}{2} \frac{V_0}{V_A - V_T}$$

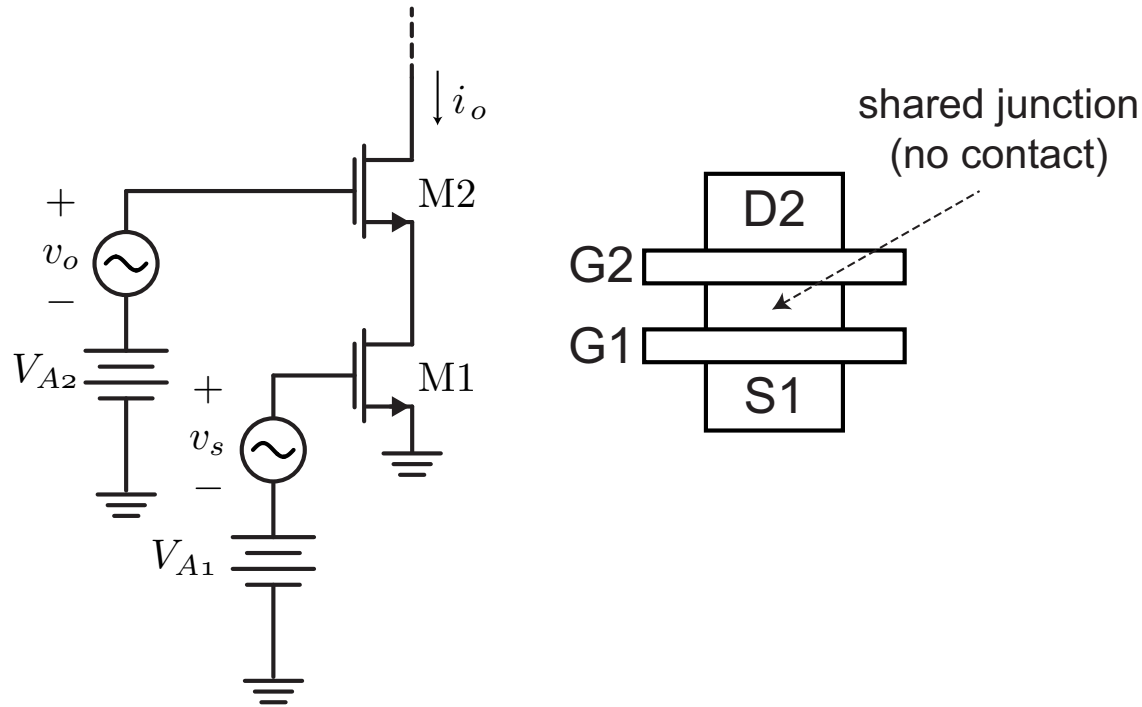
# MOS Mixer Summary

- But  $g_{mQ} = \mu C_{ox} \frac{W}{L} (V_A - V_T)$

$$g_c = \frac{\mu C_{ox}}{2} \frac{W}{L} V_0$$

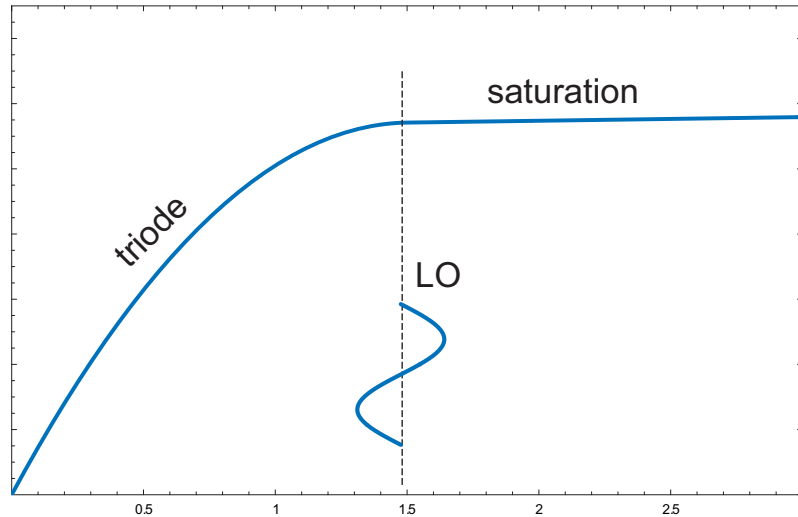
- which means that  $g_c$  is independent of bias  $V_A$ . The gain is controlled by the LO amplitude  $V_0$  and by the device aspect ratio.
- Keep in mind, though, that the transistor must remain in forward active region in the entire cycle for the above assumptions to hold.
- In practice, a real FET is not square law and the above analysis should be verified with extensive simulation. Sub-threshold conduction and output conductance complicate the picture.

# “Dual Gate” Mixer



- The “dual gate” mixer, or more commonly a cascode amplifier, can be turned into a mixer by applying the LO at the gate of  $M2$  and the RF signal at the gate of  $M1$ . Using two transistors in place of one transistor results in area savings since the signals do not need to be combined with a transformer or capacitively .

# Dual Gate Mixer Operation

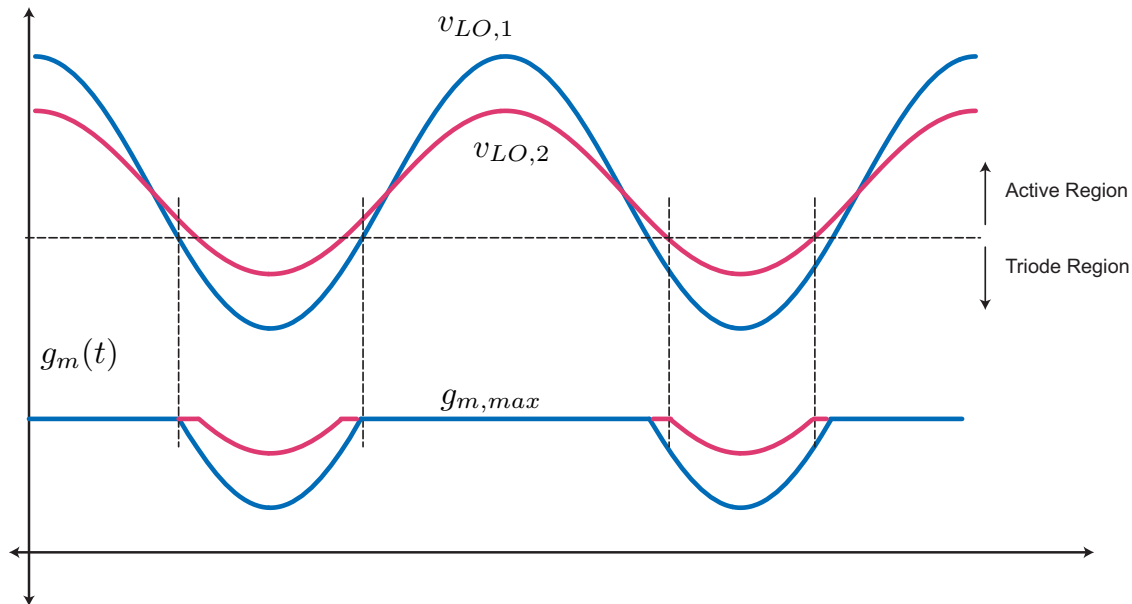


- Without the LO signal, this is simply a cascode amplifier. But the LO signal is large enough to push M1 into triode during part of the operating cycle.
- The transconductance of  $M1$  is therefore modulated periodically

$$g_m|_{\text{sat}} = \mu C_{ox} \frac{W}{L} (V_{GS} - V_T)$$

$$g_m|_{\text{triode}} = \mu C_{ox} \frac{W}{L} V_{DS}$$

# Dual Gate Waveforms



- $V_{GS2}$  is roughly constant since  $M1$  acts like a current source.

$$V_{D1} = v_{LO} - V_{GS2} = V_{A2} + V_0 \cos \omega_0 t - V_{GS2}$$

$$g(t) = \begin{cases} \mu C_{ox} \frac{W}{L} (V_{GS1} - V_T) & V_{D1} > V_{GS} - V_T \\ \mu C_{ox} (V_{A2} - V_{GS2} - |V_0 \cos \omega_0 t|) & V_{D1} < V_{GS} - V_T \end{cases}$$

# Realistic Waveforms

- A more sophisticated analysis would take sub-threshold operation into account and the resulting  $g(t)$  curve would be smoother. A Fourier decomposition of the waveform would yield the conversion gain coefficient as the first harmonic amplitude.



# Mixer Analysis: Time Domain

- A generic mixer operates with a periodic transfer function  $h(t + T) = h(t)$ , where  $T = 1/\omega_0$ , or  $T$  is the LO period. We can thus expand  $h(t)$  into a Fourier series

$$y(t) = h(t)x(t) = \sum_{-\infty}^{\infty} c_n e^{j\omega_0 n t} x(t)$$

- For a sinusoidal input,  $x(t) = A(t) \cos \omega_1 t$ , we have

$$y(t) = \sum_{-\infty}^{\infty} \frac{c_n}{2} A(t) \left( e^{j(\omega_1 + \omega_0 n)t} + e^{j(-\omega_1 + \omega_0 n)t} \right)$$

- Since  $h(t)$  is a real function, the coefficients  $c_{-k} = c_k$  are even. That means that we can pair positive and negative frequency components.

# Time Domain Analysis (cont)

- Take  $c_1$  and  $c_{-1}$  as an example

$$\begin{aligned} &= c_1 \frac{e^{j(\omega_1 + \omega_0)t} + e^{j(-\omega_1 + \omega_0)t}}{2} A(t) + c_1 \frac{e^{j(\omega_1 - \omega_0)t} + e^{j(-\omega_1 - \omega_0)t}}{2} A(t) \\ &= c_1 A(t) \cos(\omega_1 + \omega_0)t + c_1 A(t) \cos(\omega_1 - \omega_0)t + \dots \end{aligned}$$

- Summing together all the components, we have

$$y(t) = \sum_{-\infty}^{\infty} c_n \cos(\omega_1 + n\omega_0)t$$

- Unlike a perfect multiplier, we get an infinite number of frequency translations up and down by harmonics of  $\omega_0$ .

# Frequency Domain Analysis

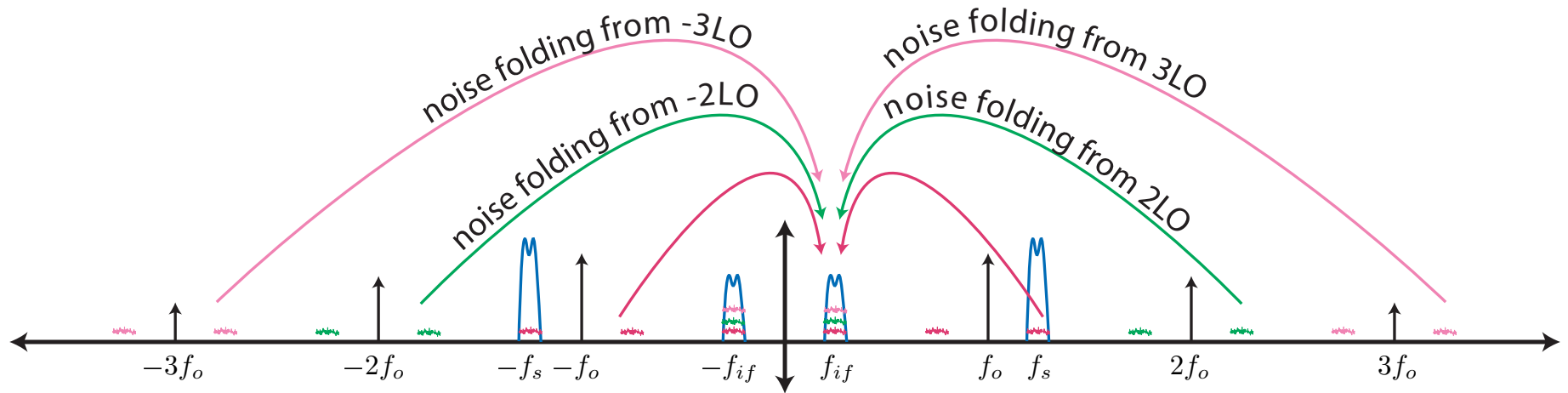
- Since multiplication in time,  $y(t) = h(t)x(t)$ , is convolution in the frequency domain, we have

$$Y(f) = H(f) * X(f)$$

- The transfer function  $H(f) = \sum_{-\infty}^{\infty} c_n \delta(f - nf_0)$  has a discrete spectrum. So the output is given by

$$\begin{aligned} Y(f) &= \int_{-\infty}^{\infty} \sum_{-\infty}^{\infty} c_n \delta(\sigma - nf_0) X(f - \sigma) d\sigma \\ &= \sum_{-\infty}^{\infty} c_n \int_{-\infty}^{\infty} \delta(\sigma - nf_0) X(f - \sigma) d\sigma \end{aligned}$$

# Frequency Domain (cont)



- By the frequency sifting property of the  $\delta(f - \sigma)$  function, we have

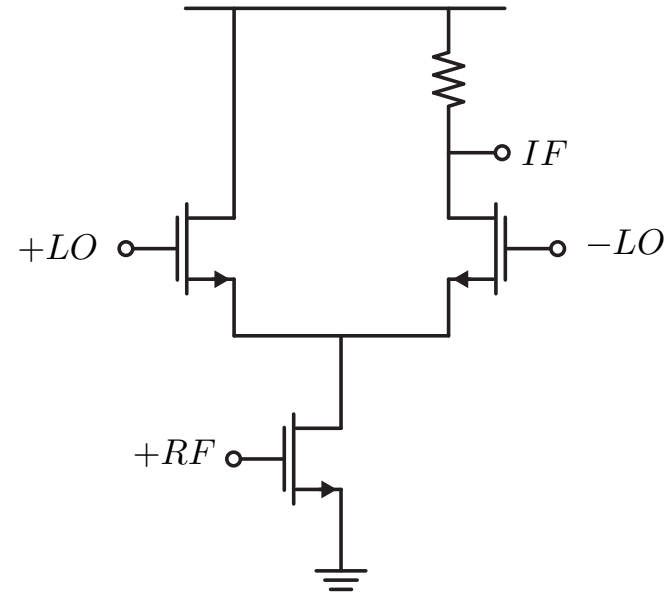
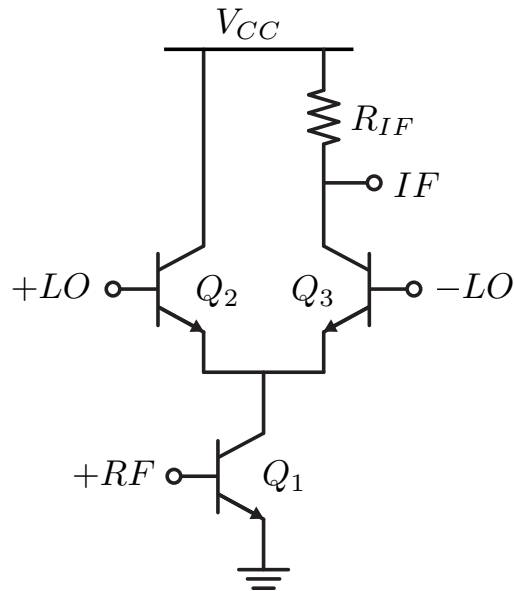
$$Y(f) = \sum_{-\infty}^{\infty} c_n X(f - n f_0)$$

- Thus, the input spectrum is shifted by all harmonics of the LO up and down in frequency.

# Noise/Image Problem

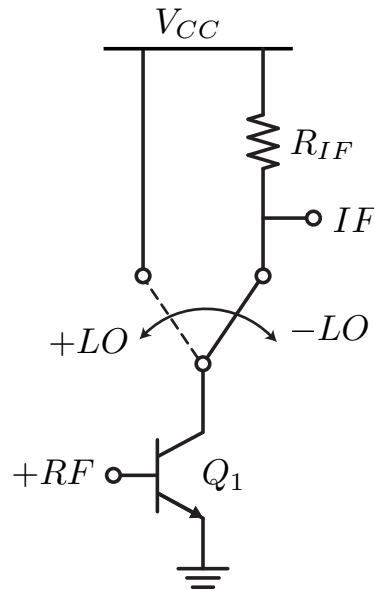
- Previously we examined the “image” problem. Any signal energy a distance of  $IF$  from the LO gets downconverted in a perfect multiplier. But now we see that for a general mixer, any signal energy with an IF of any harmonic of the LO will be downconverted !
- These other images are easy to reject because they are distant from the desired signal and a image reject filter will be able to attenuate them significantly.
- The noise power, though, in all image bands will fold onto the IF frequency. Note that the noise is generated by the mixer source resistance itself and has a white spectrum. Even though the noise of the antenna is filtered, new noise is generated by the filter itself!

# Current Commutating Mixers



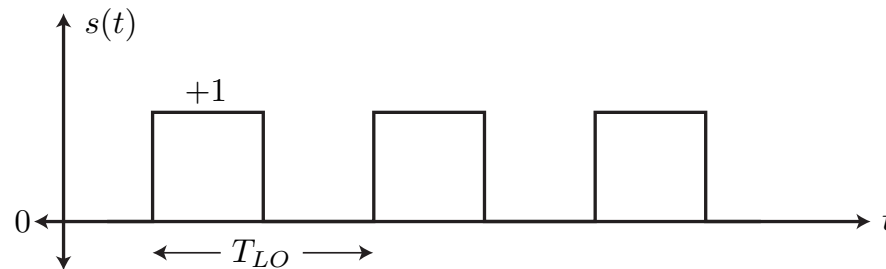
- A popular alternative mixer topology uses a differential pair LO drive and an RF current injection at the tail. In practice, the tail current source is implemented as a transconductor.
- The LO signal is large enough to completely steer the RF current either through  $Q_1$  or  $Q_2$ .

# Current Commutating Mixer Model



- If we model the circuit with ideal elements, we see that the current  $I_{C1}$  is either switched to the output or to supply at the rate of the LO signal.
- When the LO signal is positive, we have a cascode dumping its current into the supply. When the LO signal is negative, though, we have a cascode amplifier driving the output.

# Conversion Gain



- We can now see that the output current is given by a periodic time varying transconductance

$$i_o = g_m(t)v_s = g_m Q s(t)v_s$$

- where  $s(t)$  is a square pulse waveform (ideally) switching between 1 and 0 at the rate of the LO signal. A Fourier decomposition yields

$$i_o = g_m Q v_s \left( 0.5 + \frac{2}{\pi} \cos \omega_0 t - \frac{2}{\pi} \frac{1}{3} \cos 3\omega_0 t + \dots \right)$$



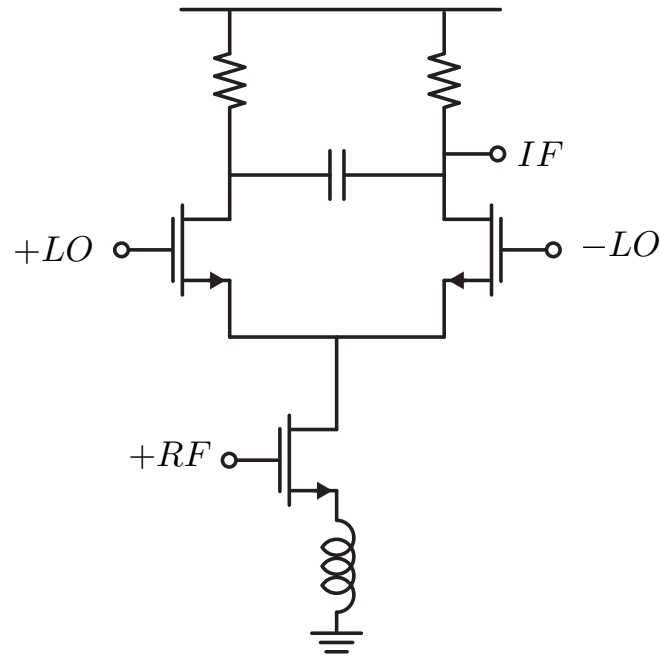
# Conversion Gain (cont)

- So the RF signal  $v_s$  is amplified (feed-thru) by the DC term and mixed by all the harmonics

$$\frac{i_o}{V_s} = \frac{g_m Q}{2} \left( \frac{1}{2} \cos \omega_s t + \frac{2}{\pi} \cos(\omega_0 \pm \omega_s) t - \frac{2}{3\pi} \cos(3\omega_0 \pm \omega_s) t + \dots \right)$$

- The primary conversion gain is  $g_c = \frac{1}{\pi} g_m Q$ .
- Since the role of  $Q1$  (or  $M1$ ) is to simply create an RF current, it can be degenerated to improve the linearity of the mixer. Inductance degeneration can be employed to also achieve an impedance match.
- MOS version acts in a similar way but the conversion gain is lower (lower  $g_m$ ) and it requires a larger  $LO$  drive.

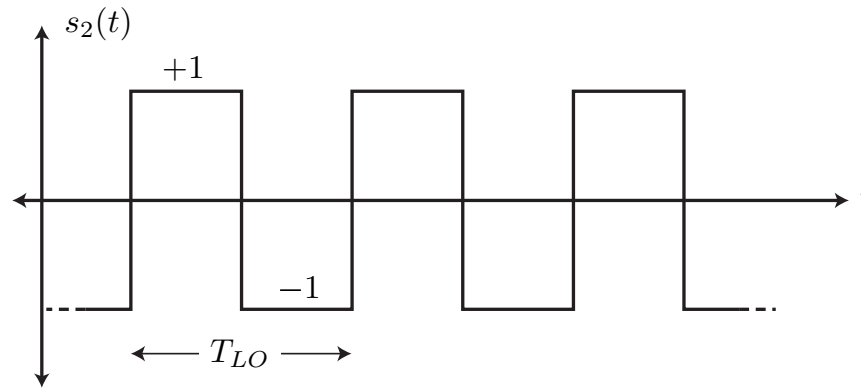
# Differential Output



- This block is commonly known as the Gilbert Cell
- If we take the output signal differentially, then the output current is given by

$$i_o = g_m(t)v_s = g_{mQ}s_2(t)v_s$$

# Differential Output Gain



- The pulse waveform  $s_2(t)$  now switches between  $\pm 1$ , and thus has a zero DC value

$$s_2(t) = \frac{4}{\pi} \cos \omega_0 t - \frac{1}{3} \frac{4}{\pi} \cos 3\omega_0 t + \dots$$

- The lack of the DC term means that there is ideally no RF feedthrough to the IF port. The conversion gain is doubled since we take a differential output  $g_c/g_{mQ} = \frac{2}{\pi}$