

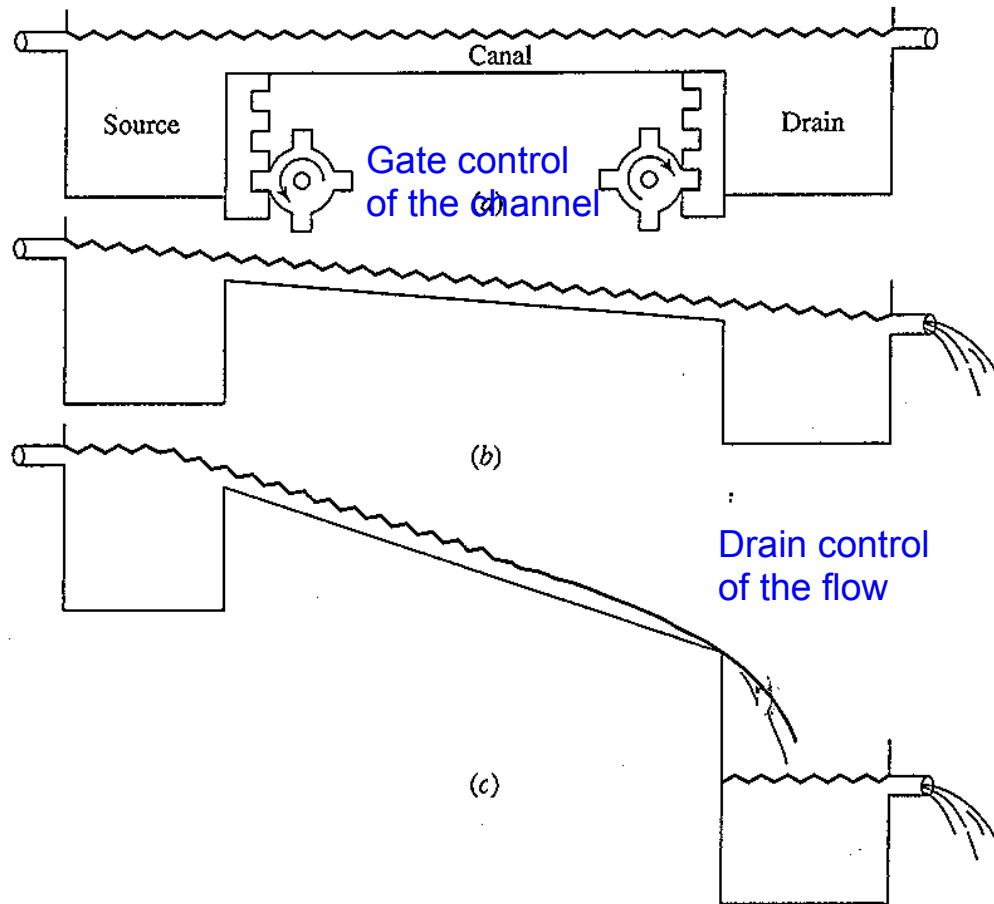
ECE 5205 Spring 2014

# MOSFET OPERATION Part 1

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# Fluid Analogy to MOSFET Operation



- When the source and drain are level, there is no flow  $V_{DS}=0$
- Whatever depth in the canal can be varied by the gear and track ( $V_{GS}$ )
- When the drain is lower than the source, water flows along the canal
- The flow is limited by the channel capacity, lowering the drain further only increases the height of the waterfall at its edge

# MOSFET Operation

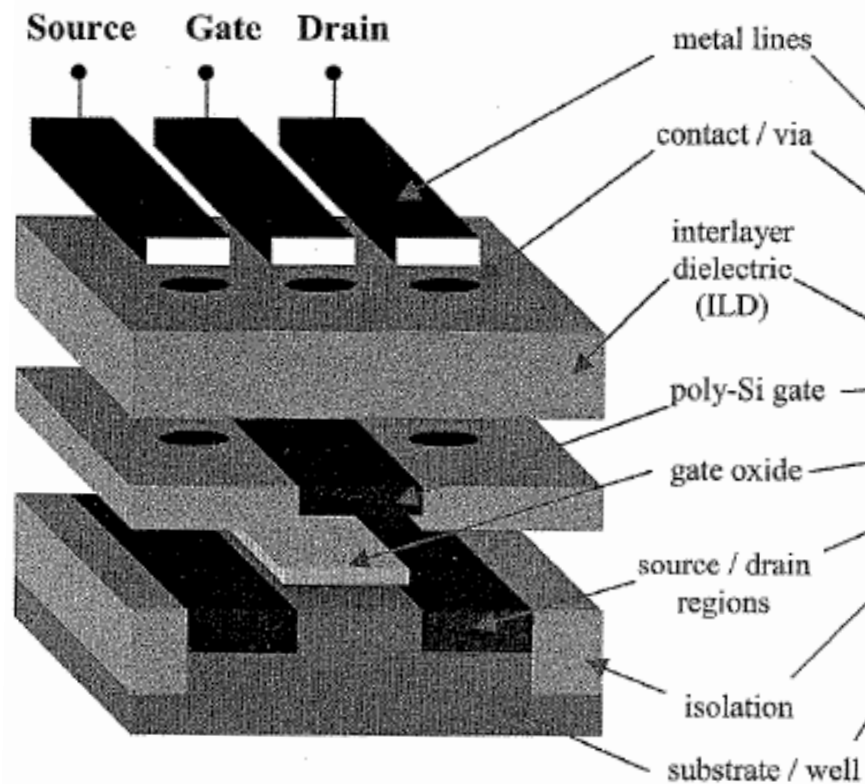
## Contents Part 1

- Overview ( MOSFET Current Regimes )
- Inversion charge in a MOSFET
- Pao-Sah Double Integral Model
- Gradual channel approximation
- Charge-Sheet Approximation
- MOSFET I-V Characteristics
- Subthreshold Current
- Subthreshold Swing – a critical issue today

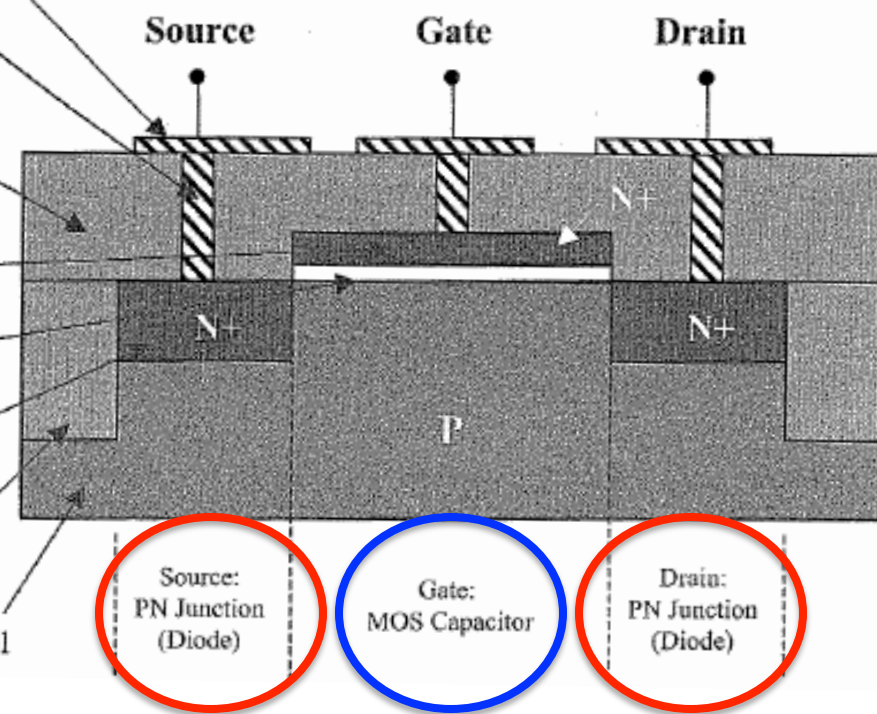
# MOSFET - Layer/Feature ID

## Metal-Oxide-Semiconductor Field-Effect Transistor

Top & Cross-Section View  
(Layered)

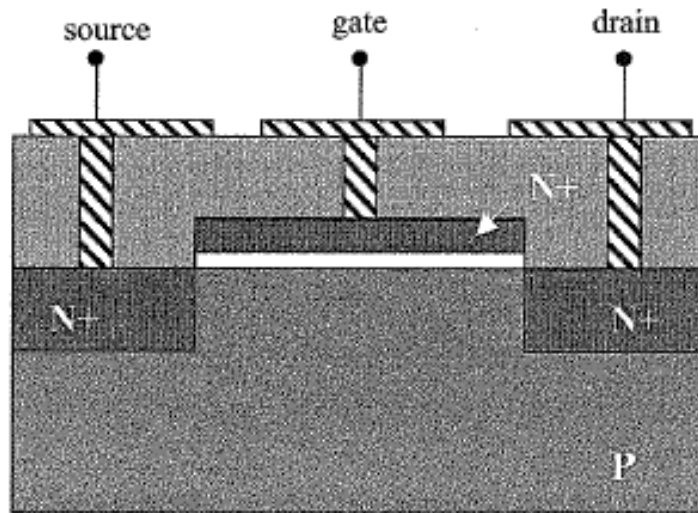


Source-to-Drain  
Cross-Section



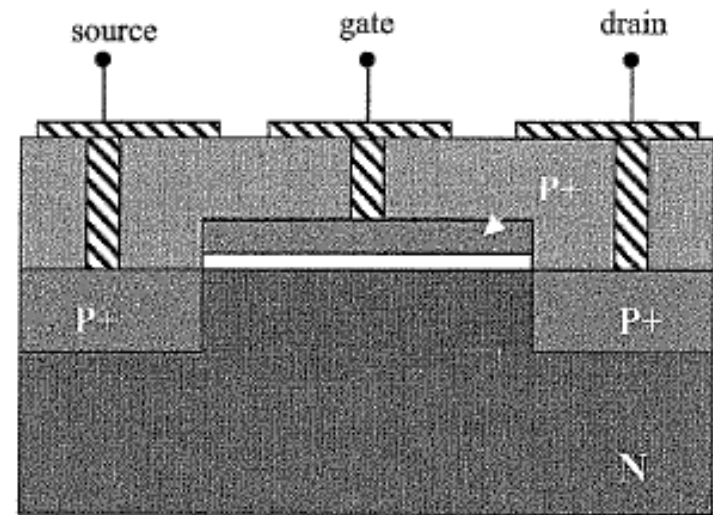
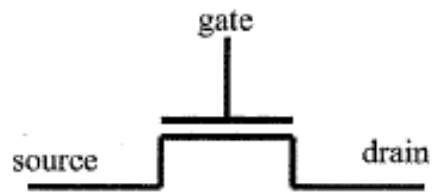
# MOSFET - Two Types

device  
structure

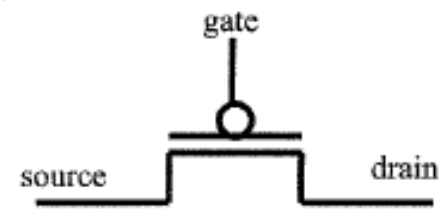


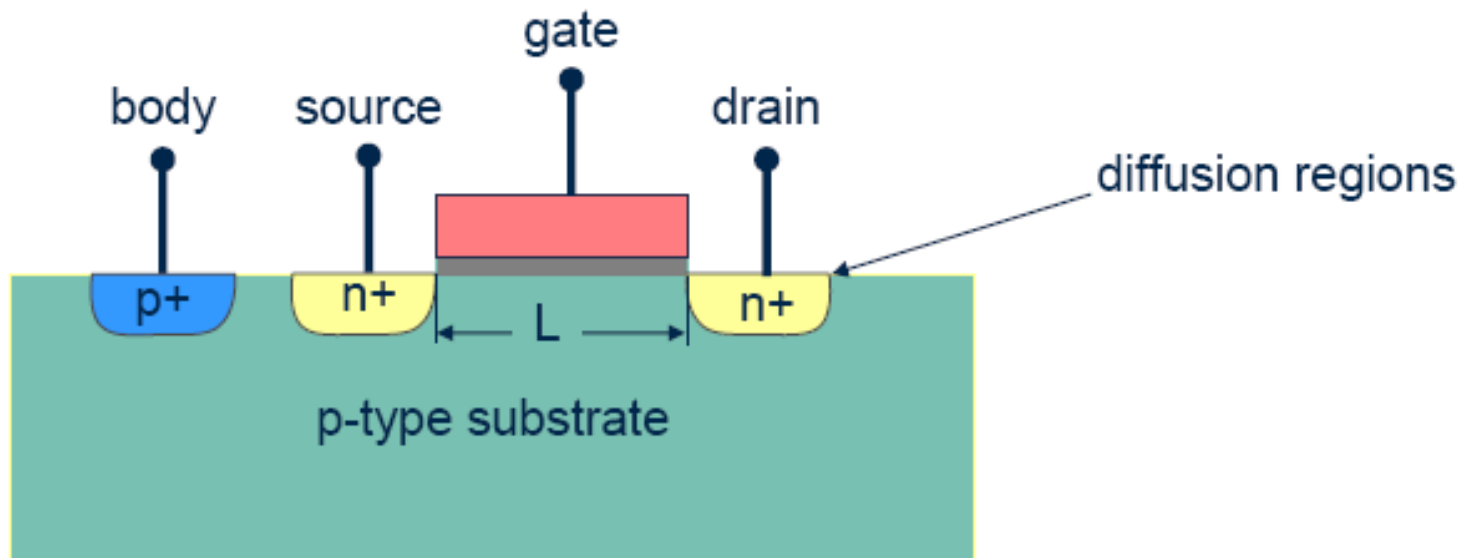
**N-Channel Transistor**

circuit  
symbol

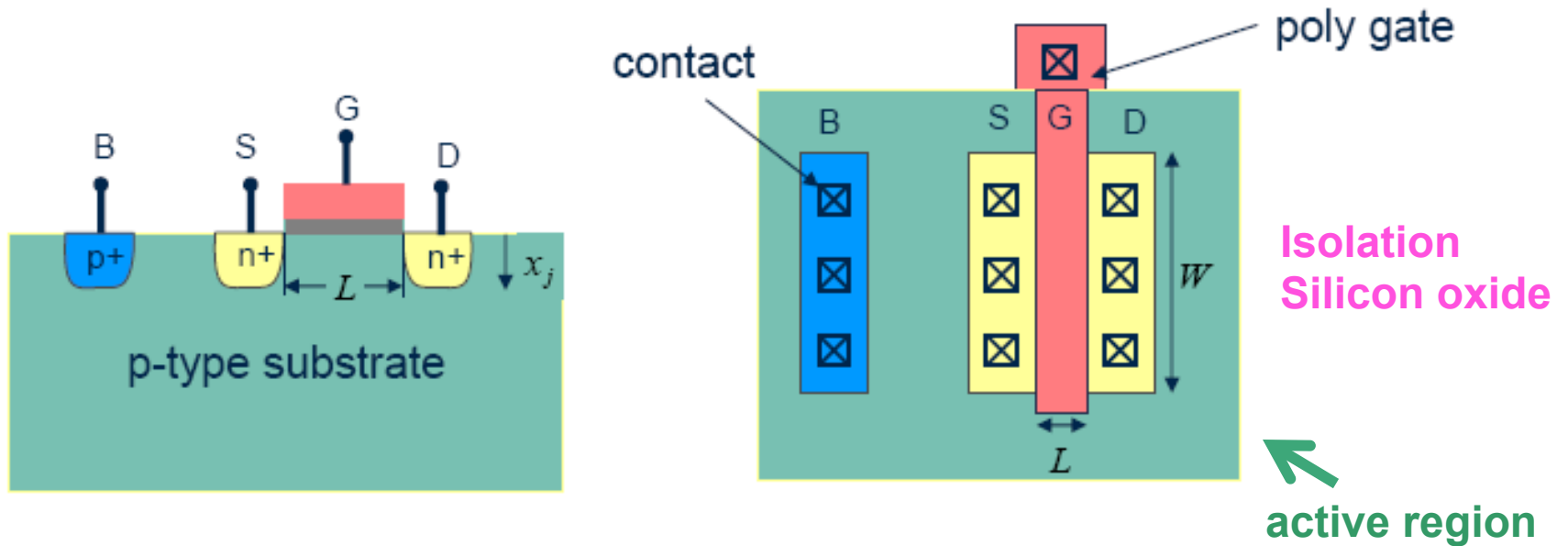


**P-Channel Transistor**





- Add two junctions around MOS capacitor
- The regions forms PN junctions with substrate
- MOSFET is a four terminal device
- The body is usually grounded (or at a DC potential)
- For ICs, the body contact is at surface

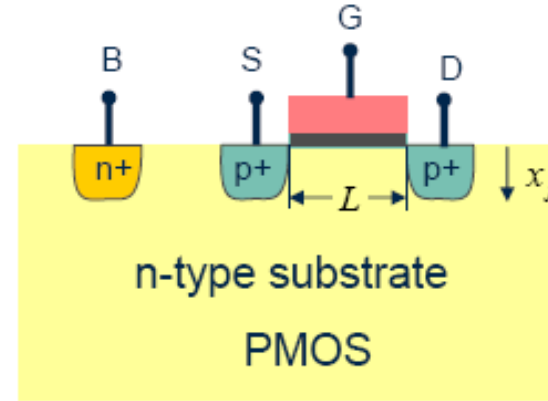
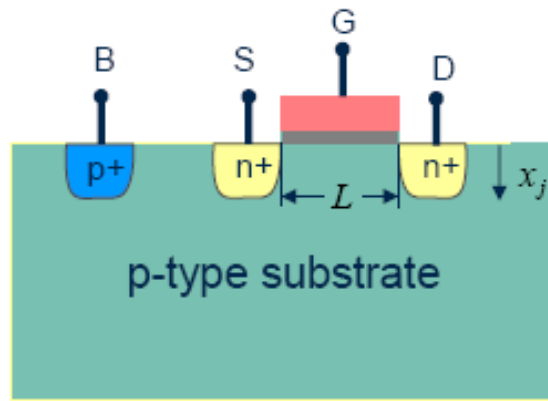


- **Planar process:** complete structure can be specified by a 2D layout
- Design engineer can control the transistor width  $W$  and  $L$
- Process engineer controls  $t_{ox}$ ,  $N_a$ ,  $x_j$ , etc.

Gate is always contacted outside active region (or on isolation)

# PMOS & NMOS

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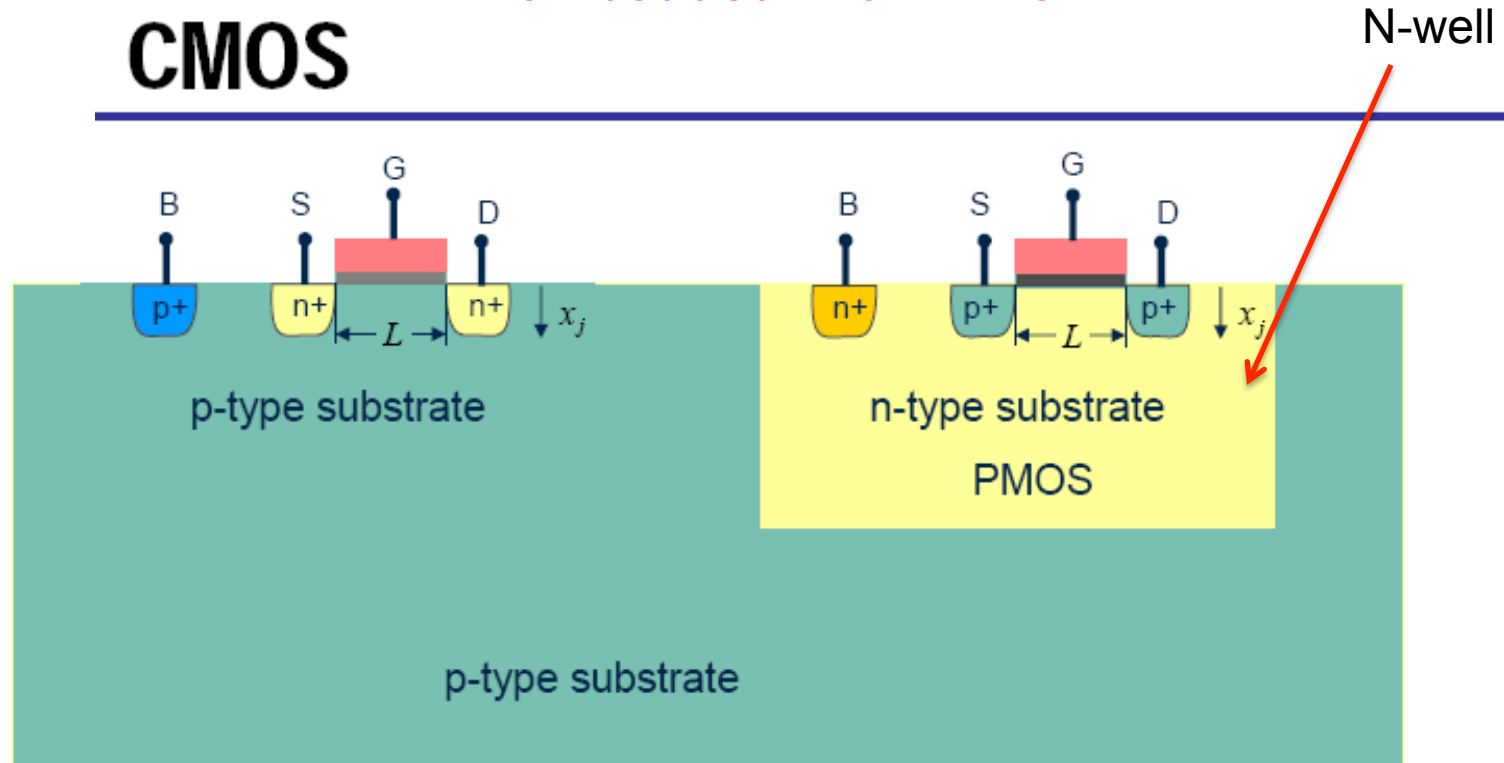


- **A MOSFET by any other name is still a MOSFET:**
  - NMOS, PMOS, nMOS, pMOS
  - NFET, PFET
  - IGFET    Insulated gate field effect transistor
  - Other flavors: JFET, MESFET    junction gate field-effect transistor
- **CMOS technology: The ability to fabricate NMOS and PMOS devices simultaneously**
  - MESFET   metal semiconductor field effect transistor



in a p-substrate wafer PMOSFET is embedded in an n-well

# CMOS



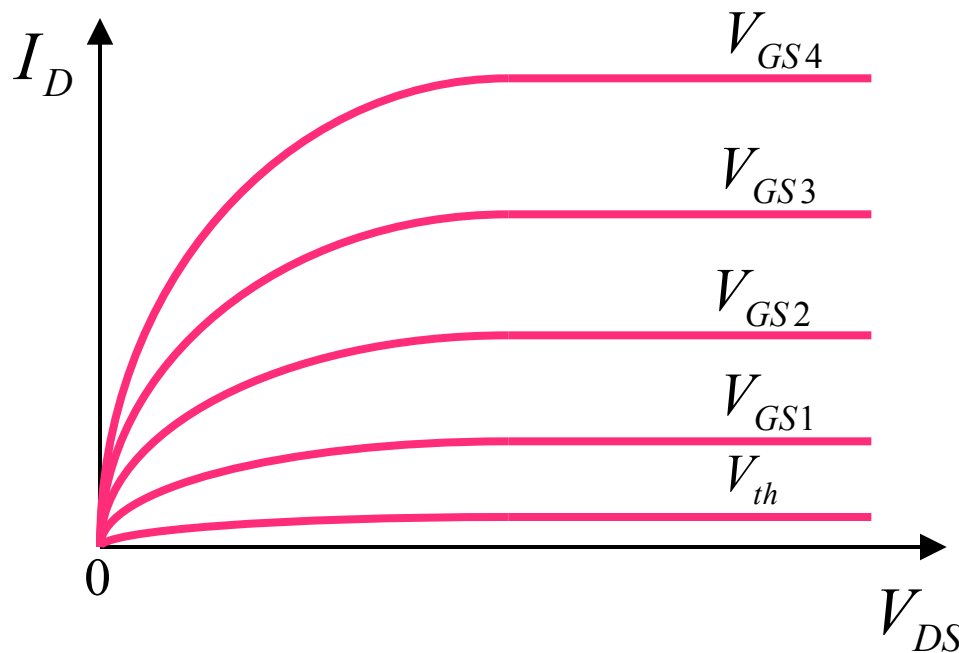
- Complementary MOS: Both P and N type devices
- Create a n-type body in a p-type substrate through compensation. This new region is called a "well".
- To isolate the PMOS from the NMOS, the well must be reverse biased (pn junction)

# **Four types of MOSFETs**

# n-channel **enhancement** MOSFET

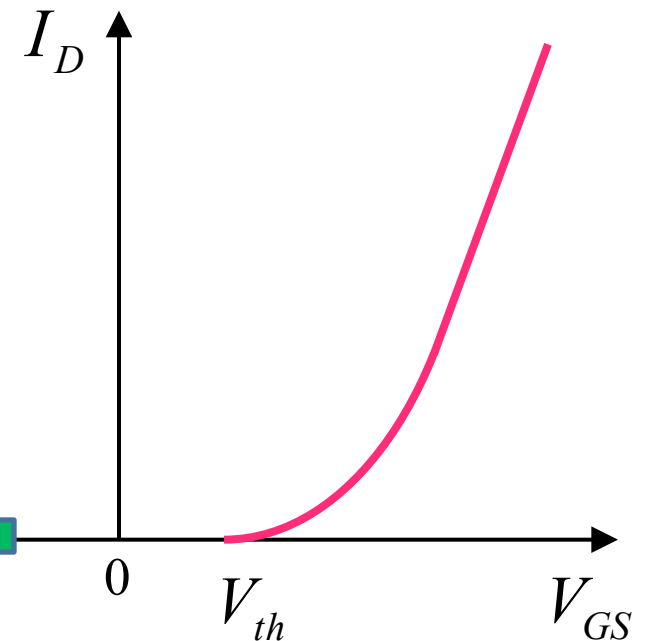
dc output characteristics

$$I_D = f(V_{DS}) \Big|_{V_{GS}}$$



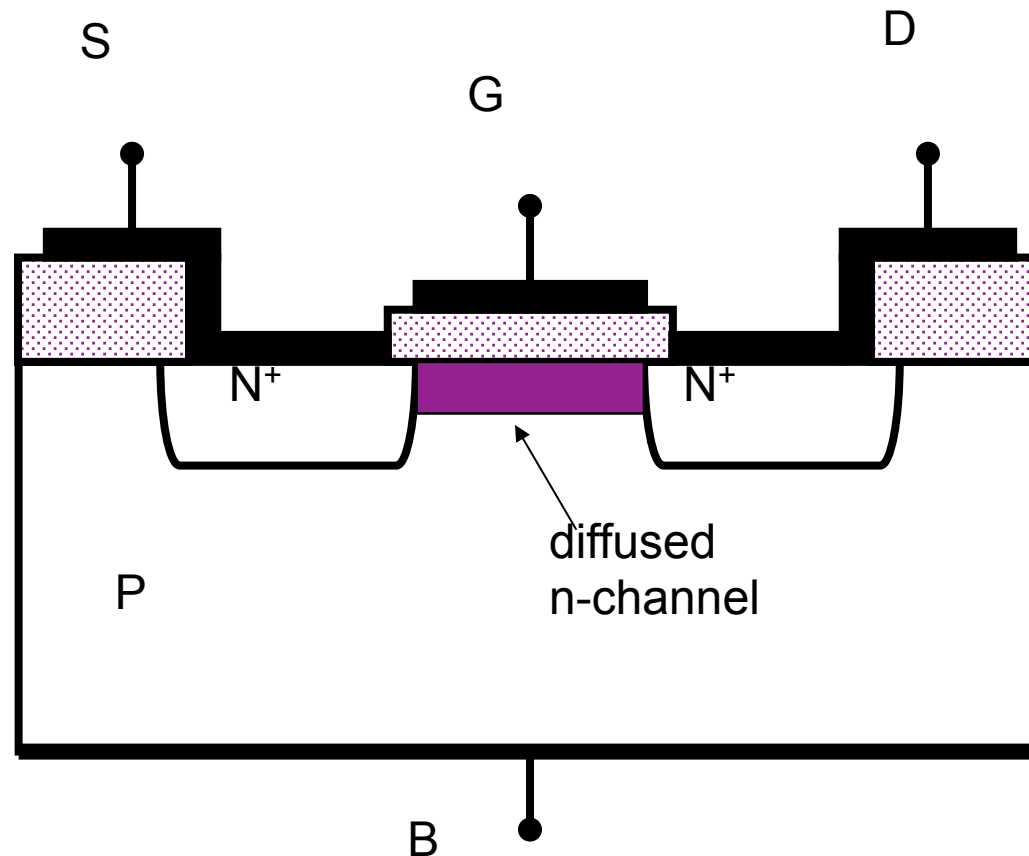
dc transfer characteristics

$$I_D = f(V_{GS}) \Big|_{V_{DS}}$$



NMOS: a positive Gate voltage has to be applied to turn the transistor on. The channel has to be “enhanced”. Transistor is “normally off”

# n-channel **depletion** MOSFET

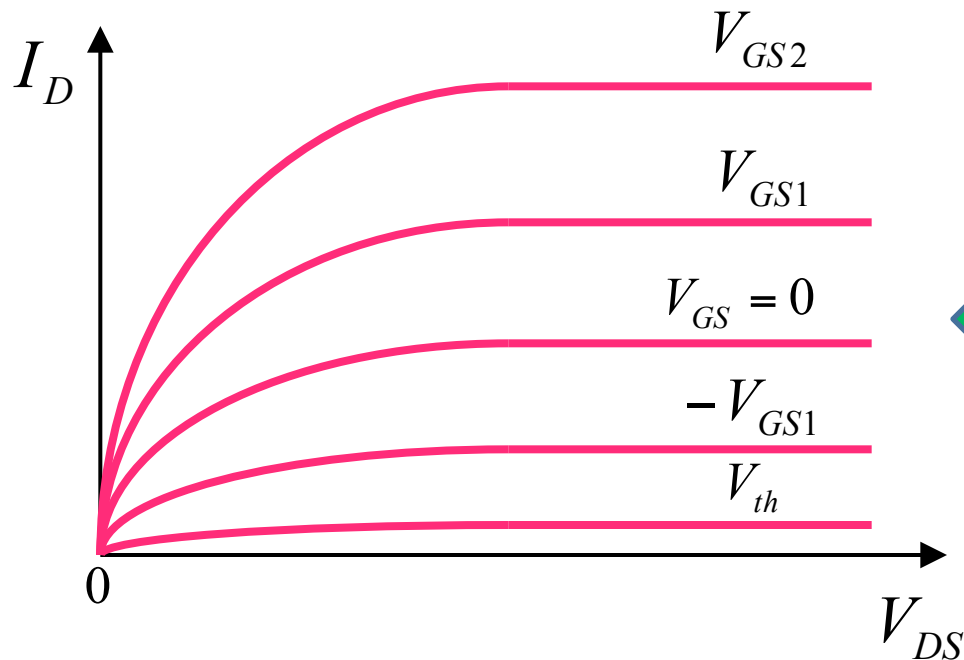


This transistor is “normally on”.  
A negative gate voltage has to be applied  
to turn the transistor off.

# n-channel **depletion** MOSFET

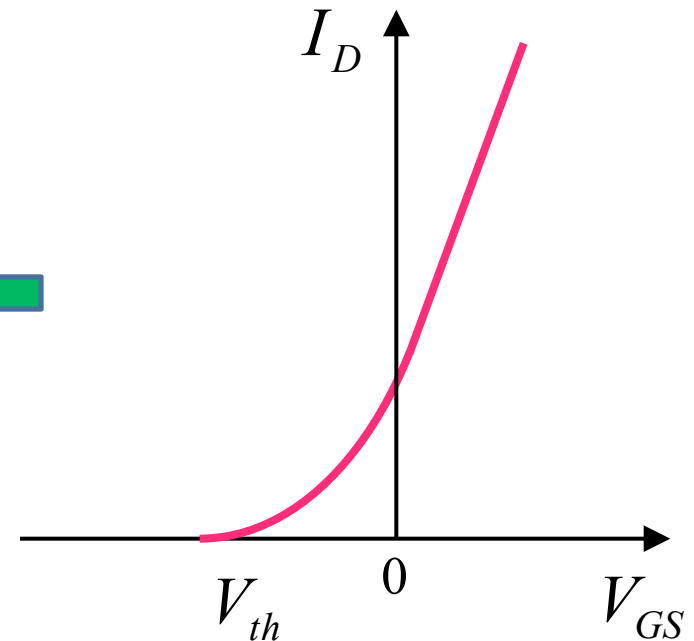
dc output characteristics

$$I_D = f(V_{DS}) \Big|_{V_{GS}}$$



dc transfer characteristics

$$I_D = f(V_{GS}) \Big|_{V_{DS}}$$

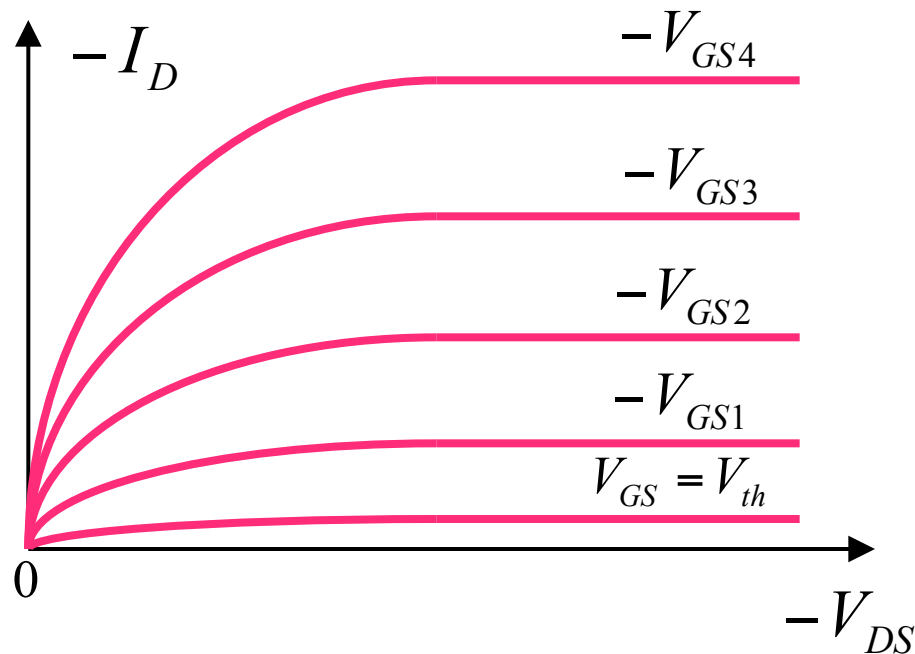


Transistor “normally on”. A negative gate voltage has to be applied to turn the transistor off.

# p-channel **enhancement** MOSFET

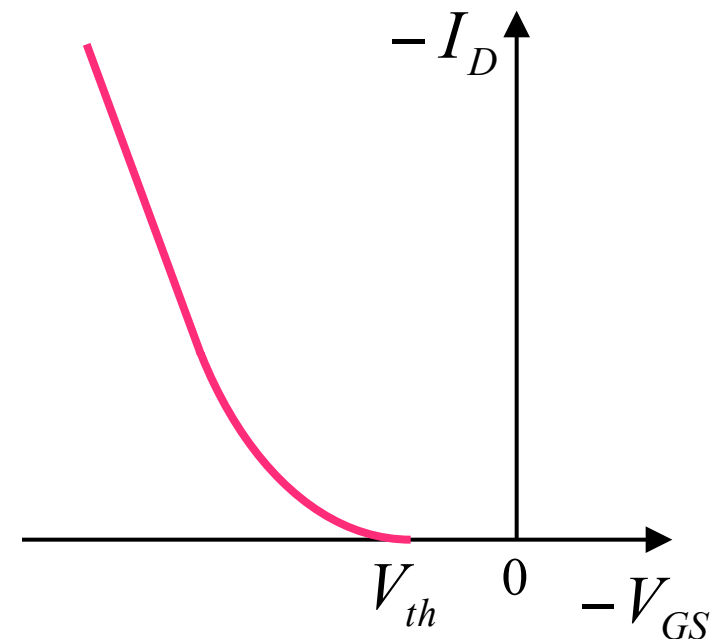
dc output characteristics

$$I_D = f(V_{DS}) \Big|_{V_{GS}}$$



dc transfer characteristics

$$I_D = f(V_{GS}) \Big|_{V_{DS}}$$

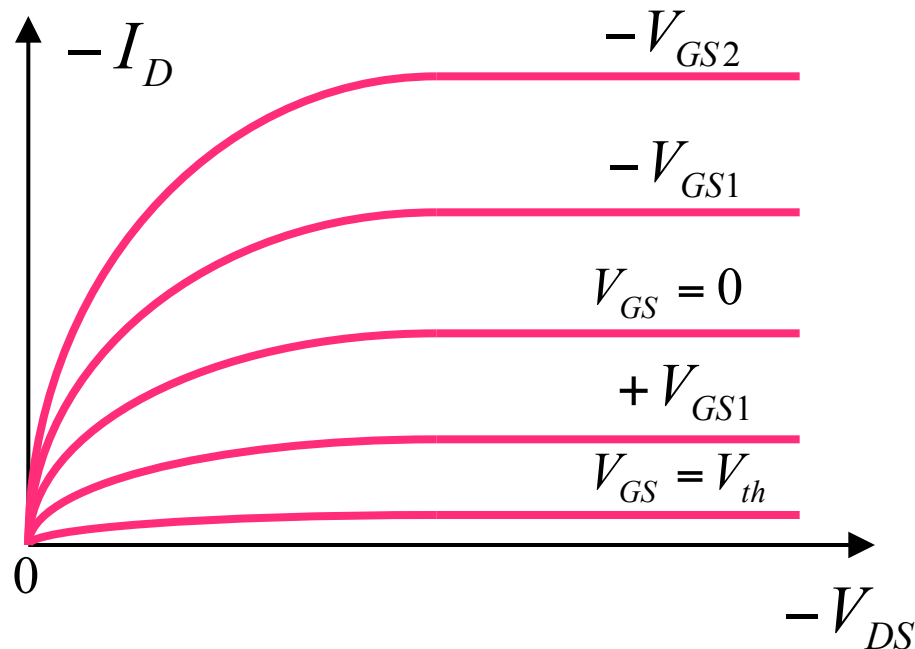


PMOS: a negative Gate voltage has to be applied to turn the transistor on. The channel has to be “enhanced”. Transistor is “normally off”

# p-channel **depletion** MOSFET

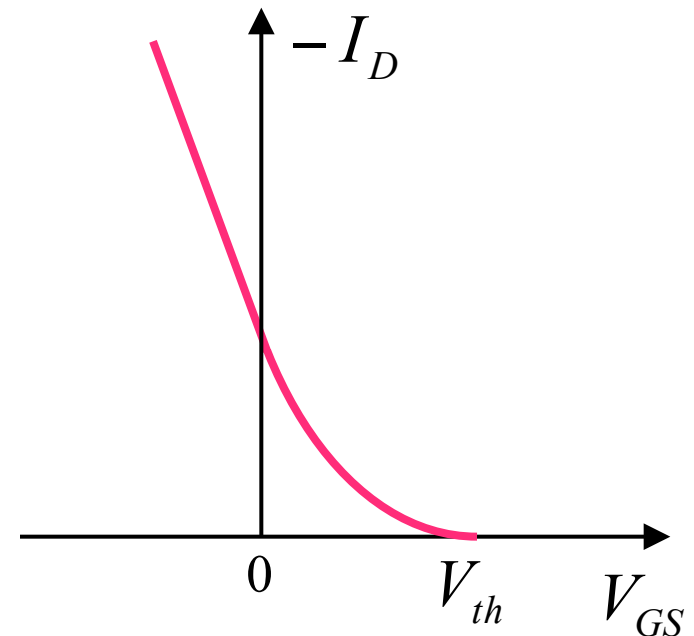
dc output characteristics

$$I_D = f(V_{DS}) \Big|_{V_{GS}}$$



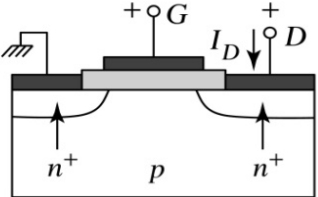
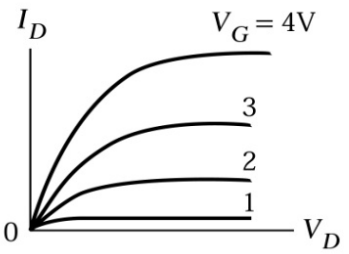
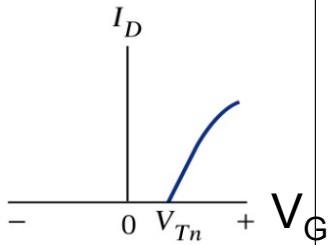
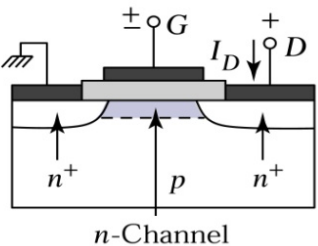
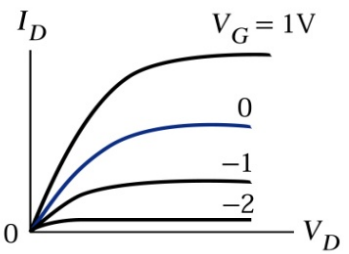
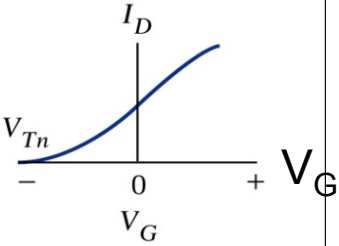
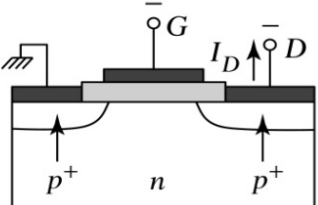
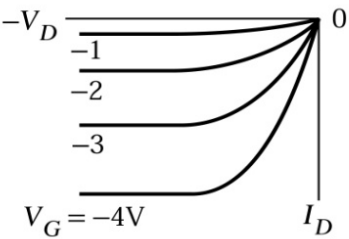
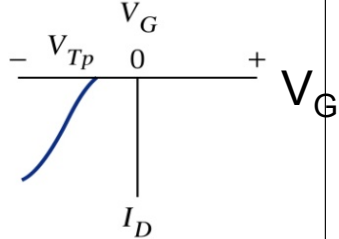
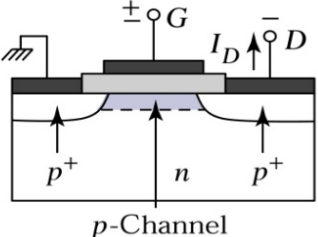
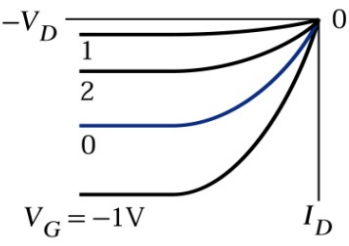
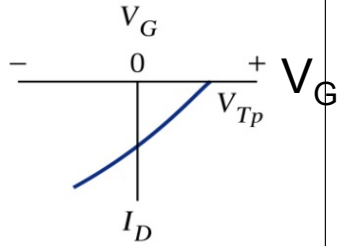
dc transfer characteristics

$$I_D = f(V_{GS}) \Big|_{V_{DS}}$$



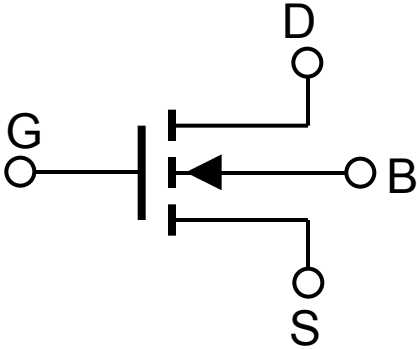
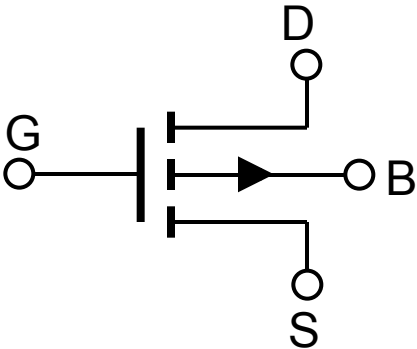
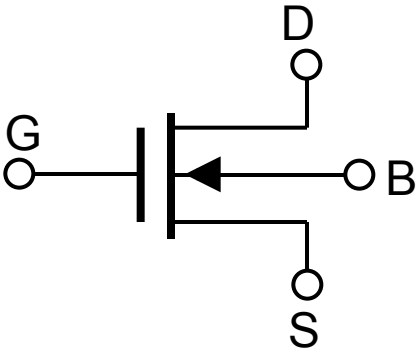
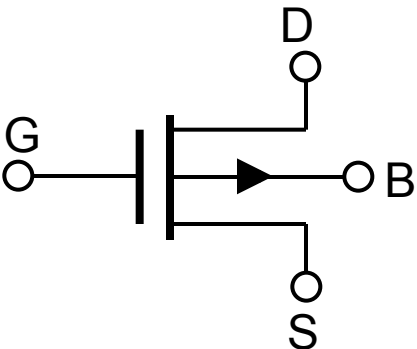
Transistor “normally on”. A positive gate voltage has to be applied to turn the transistor off.

# Summary: Four types of MOSFETs

Type	Cross Section	Output Characteristics	Transfer Characteristics
n-Channel Enhancement (Normally Off)			
n-Channel Depletion (Normally On)			
p-Channel Enhancement (Normally Off)			
p-Channel Depletion (Normally On)			

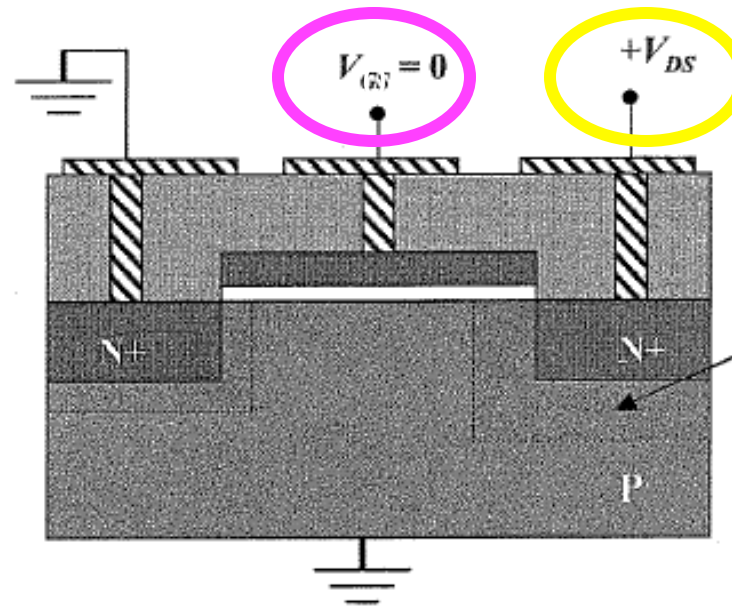


# MOSFET circuit symbols

	n-channel	p-channel
enhancement		
depletion		

# The Basics - Turning the MOSFET On & Off (cont.)

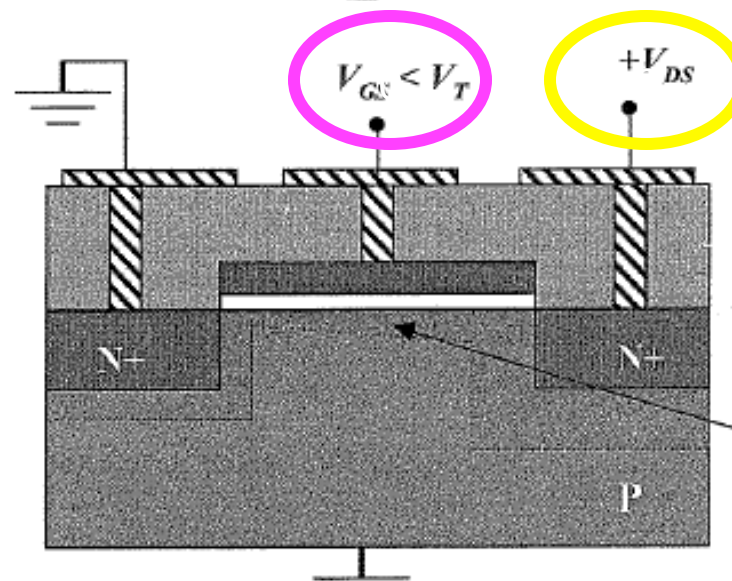
No Applied Gate Voltage  
MOSFET is "OFF"



no current flow

reverse-biased PN junction:  
depletion region widens,  
only leakage current

Subthreshold  
MOSFET is "OFF"

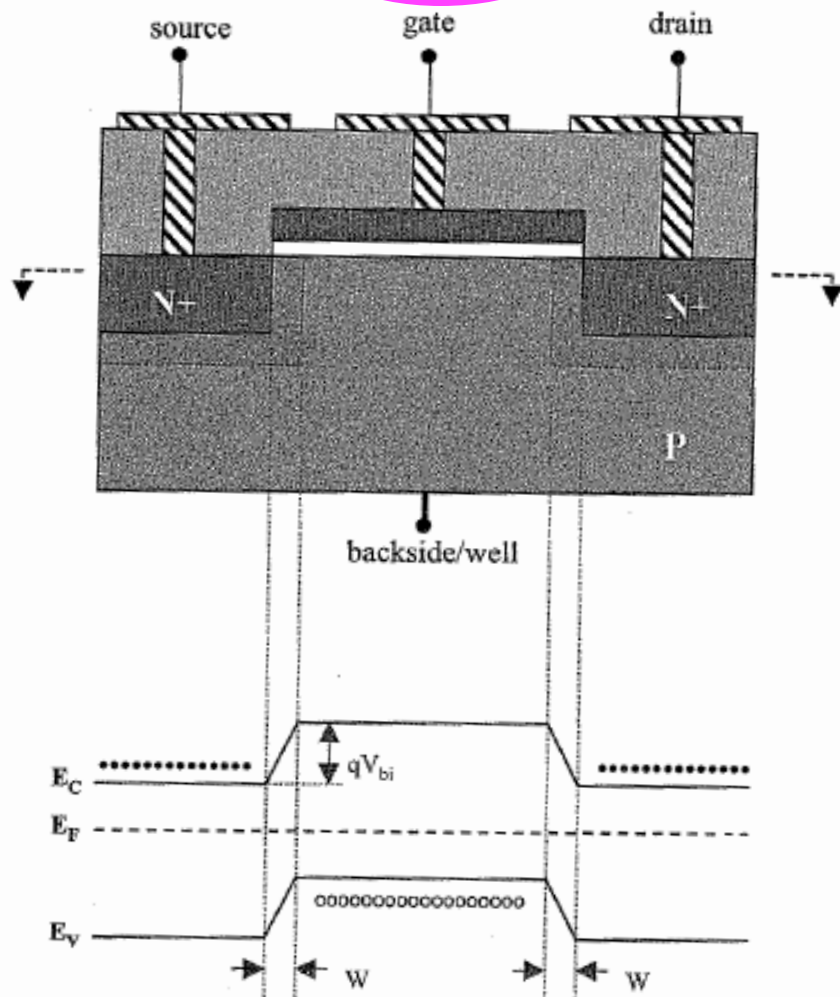


no current flow

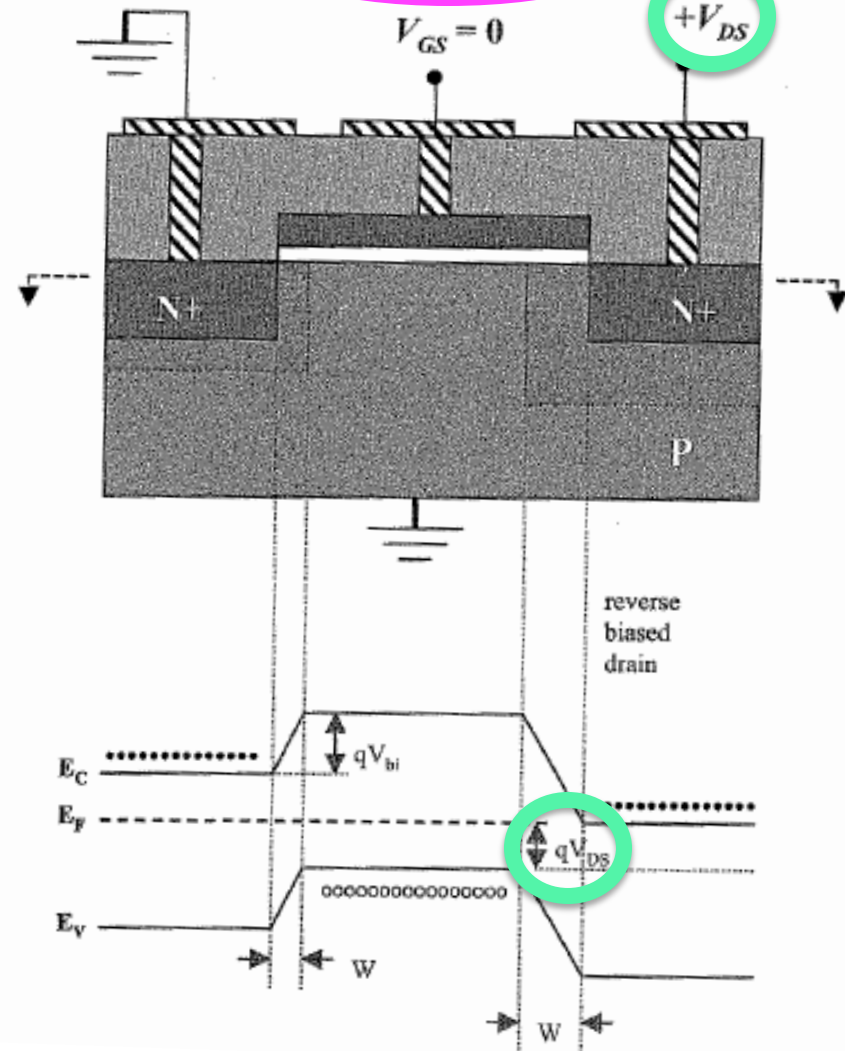
MOS capacitor is  
biased into depletion,  
only leakage current

# MOSFET - Band Diagram

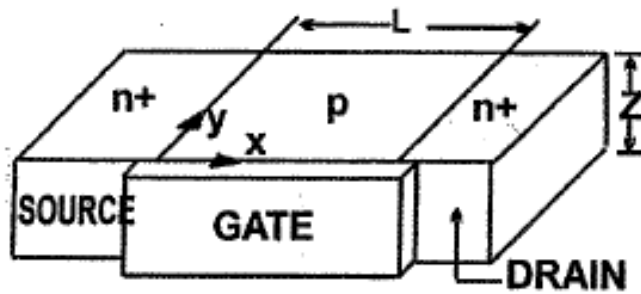
Equilibrium



Applied Drain Voltage

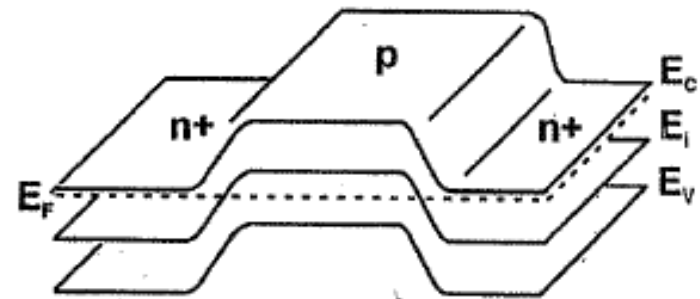


# MOSFET - 3-D Band Diagram



(a)

Gate bias to turn MOS on



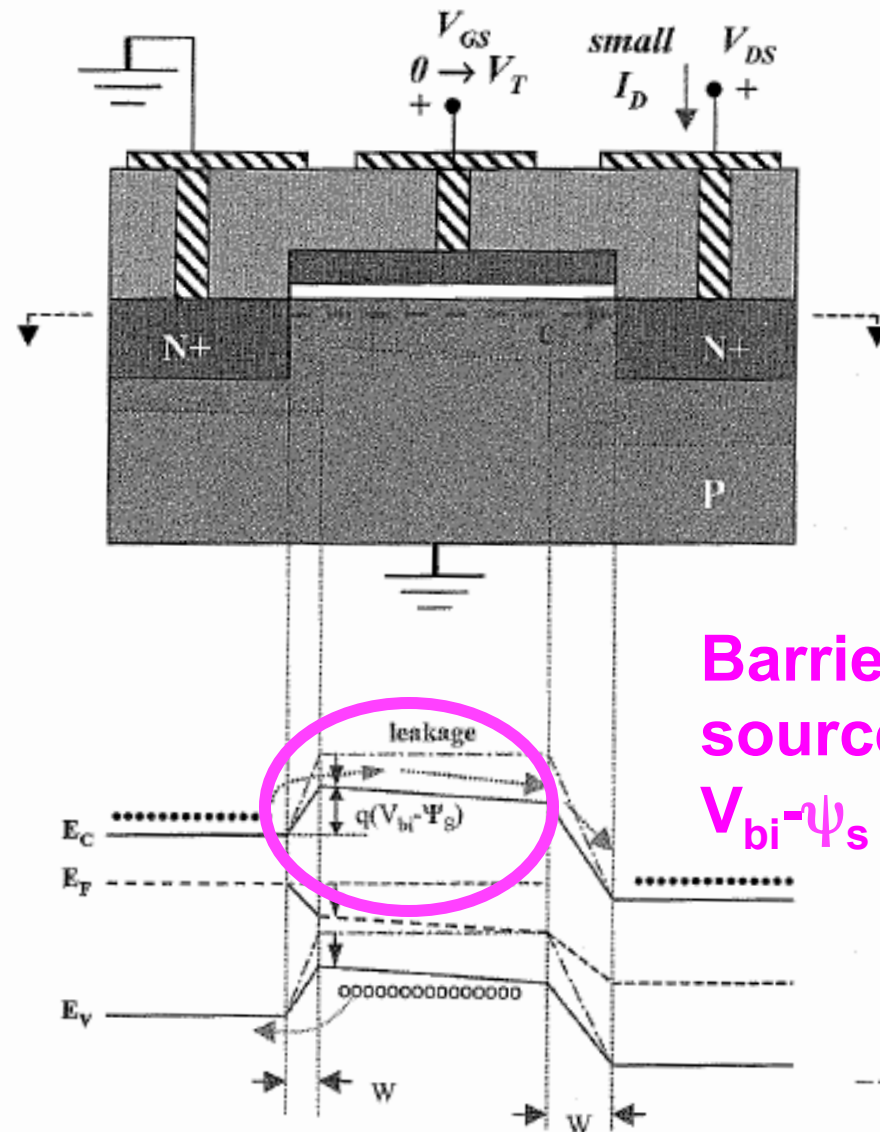
(b)

Gate bias ON and drain bias

# MOSFET - Subthreshold

**MOSFET OFF**  
 “no current flow”  
 but.....  
 leakage current

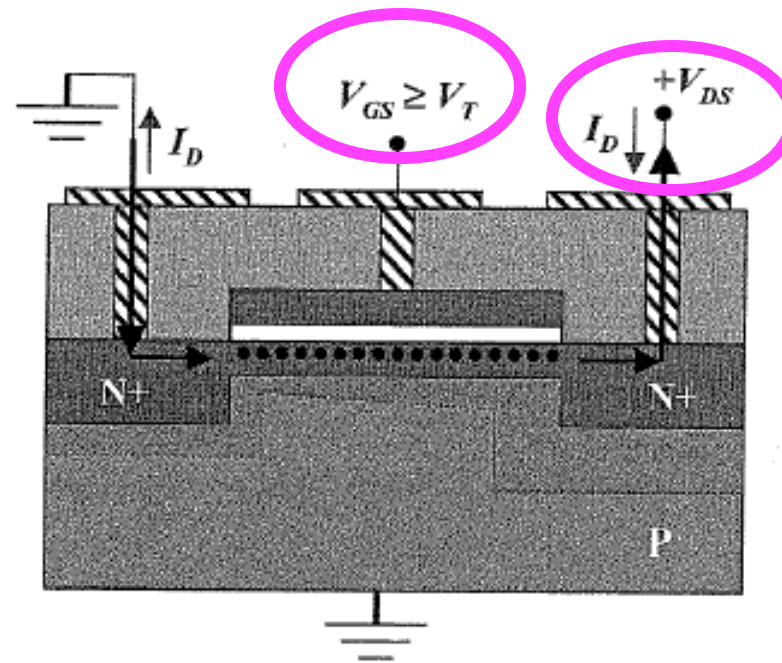
Gate MOS capacitor is  
 biased into depletion



**Barrier height at the  
 source junction is  
 $V_{bi} - \psi_s$  near the source**

## The Basics - Turning the MOSFET On & Off (cont.)

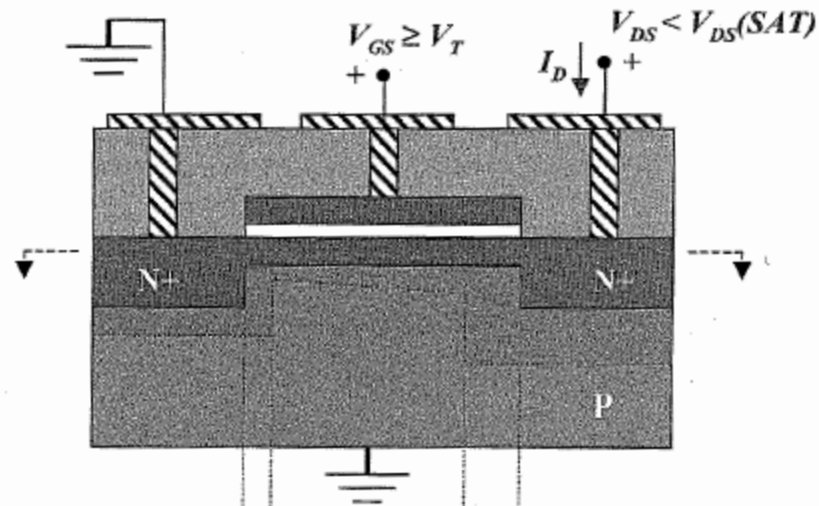
At or Beyond Threshold  
MOSFET is "ON"



*Note:* The depth of the channel is exaggerated for illustration purposes in this diagram. It is actually more like a "sheet" of charge right under the gate oxide.

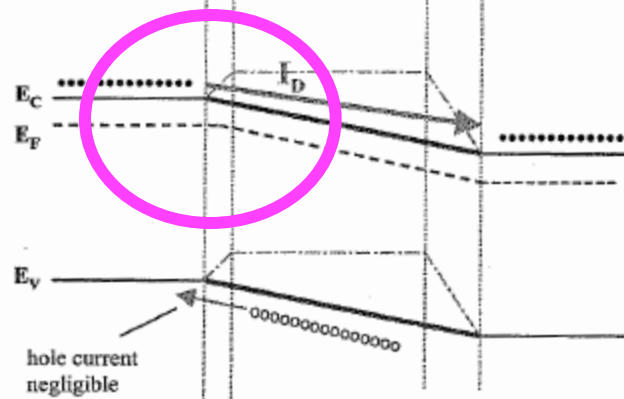


# MOSFET - Linear Regime



Note that the barrier disappeared  
 $V_{bi} - \psi_s = 0$

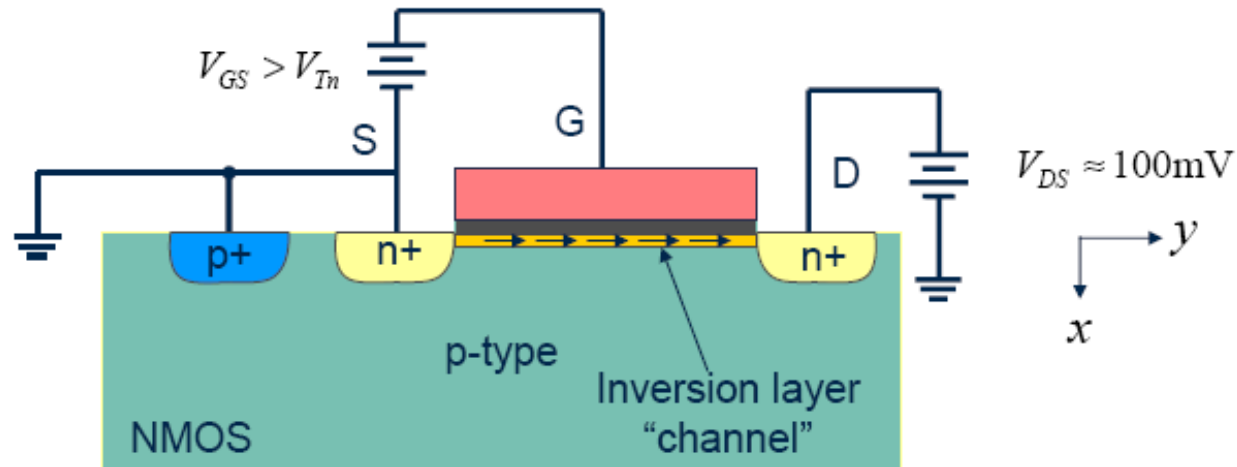
N-type channel, behaves like a resistor (ohmic)



----- from previous band diagram, for reference

## Common biasing of the MOSFET in linear regime

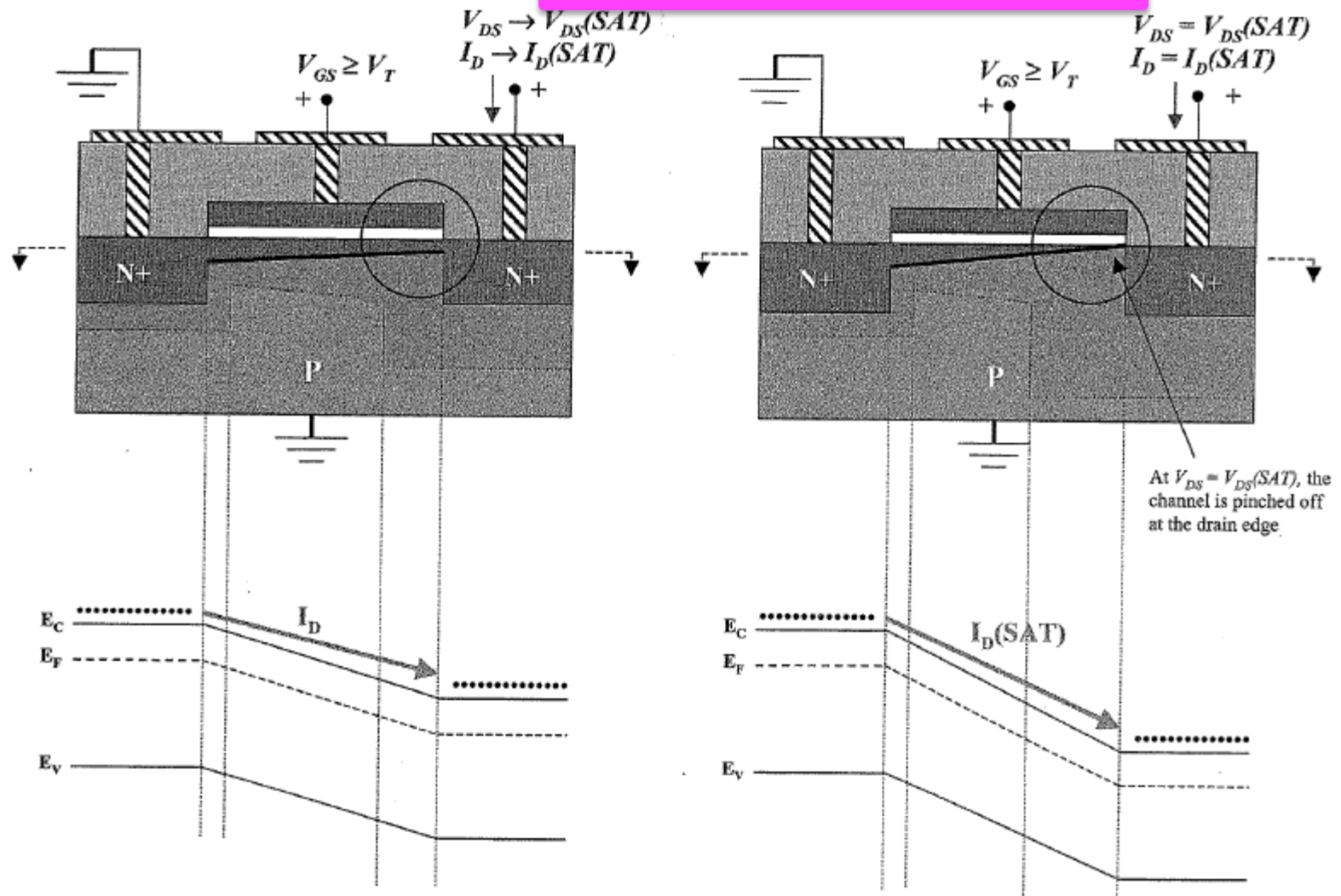
### "Linear" Region Current



- If the gate is biased above threshold, the surface is inverted
- This inverted region forms a channel that connects the drain and gate
- If a drain voltage is applied positive, electrons will flow from source to drain

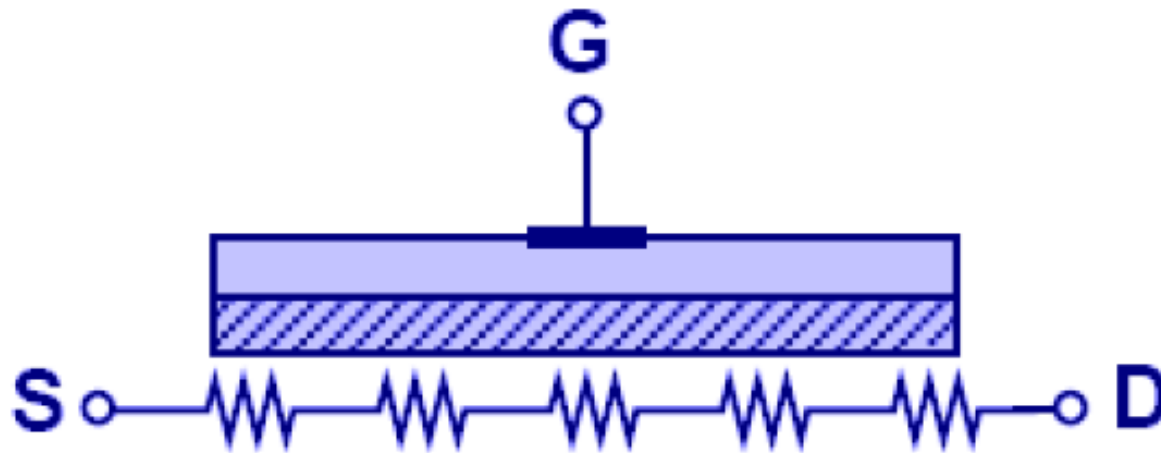


## MOSFET - Linear Into Saturation



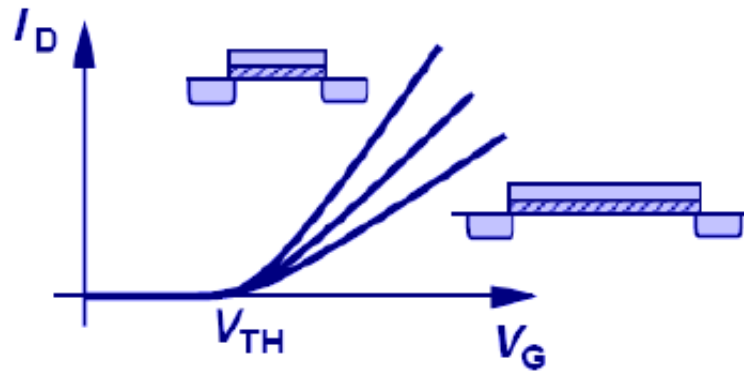
**In the linear regime channel behaves like a gate-controlled resistor**

## Voltage-Dependent Resistor

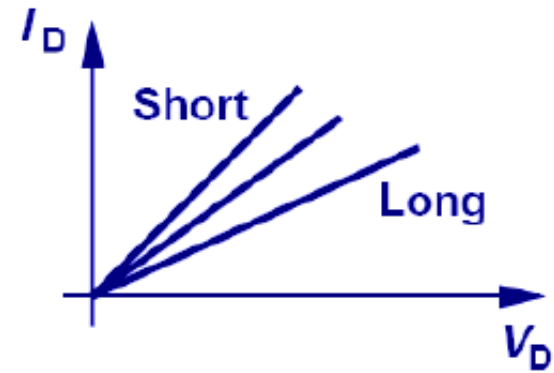


- The inversion channel of a MOSFET can be seen as a resistor.
- Since the charge density inside the channel depends on the gate voltage, this resistance is also voltage-dependent.

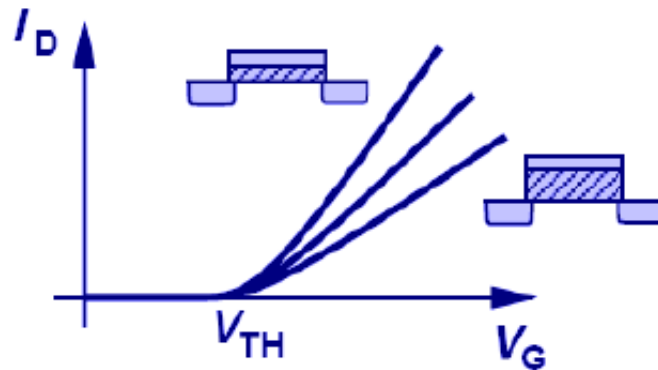
## L and $t_{ox}$ Dependence



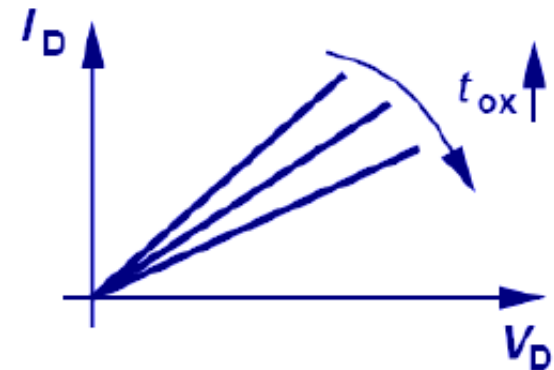
(a)



(b)



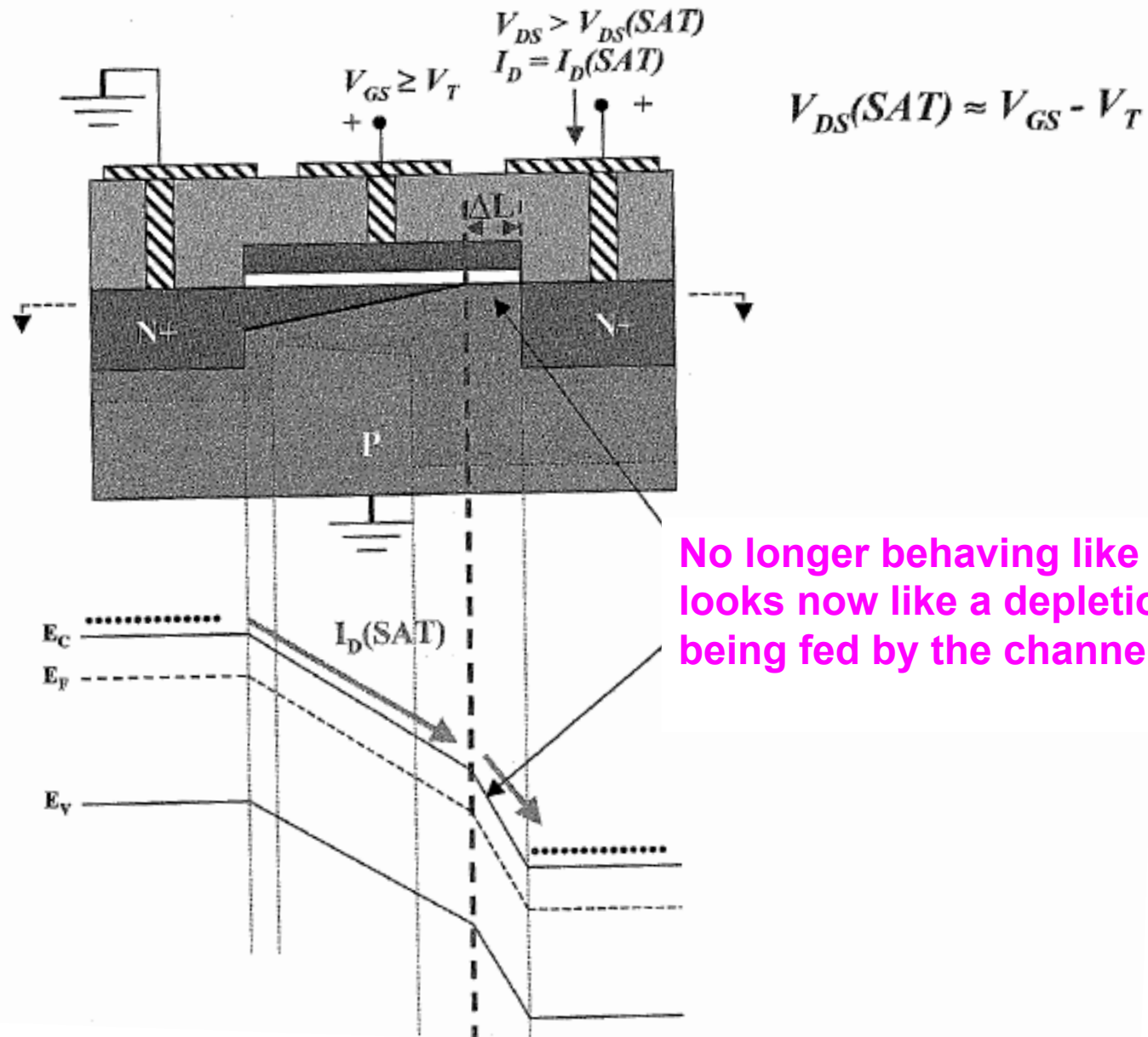
(c)



(d)

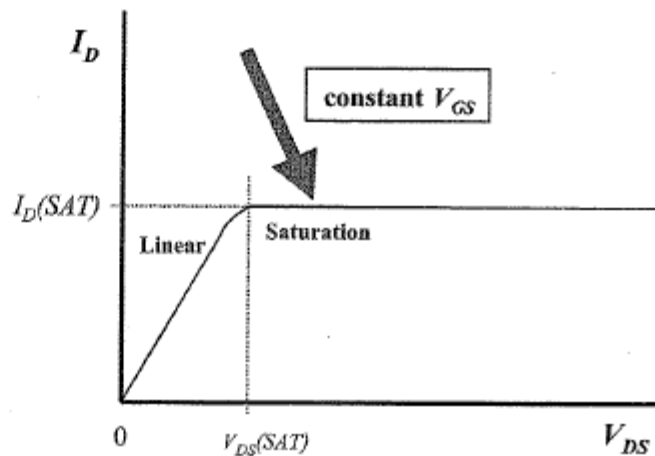
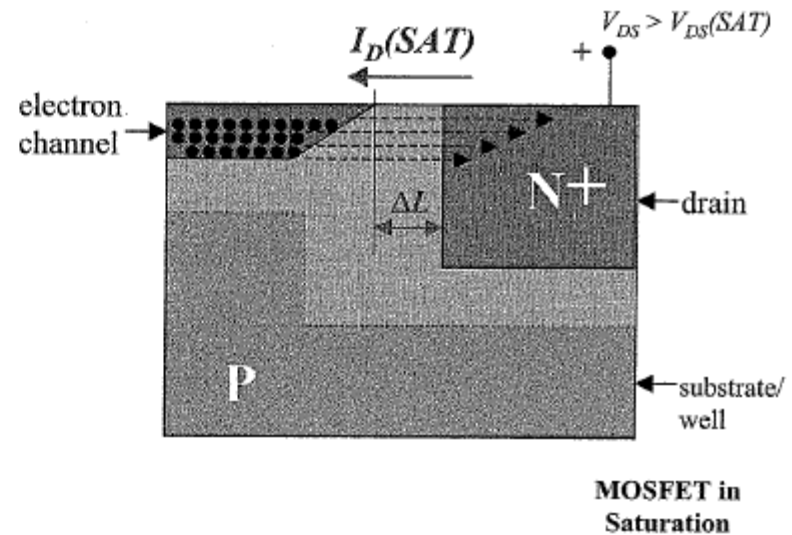
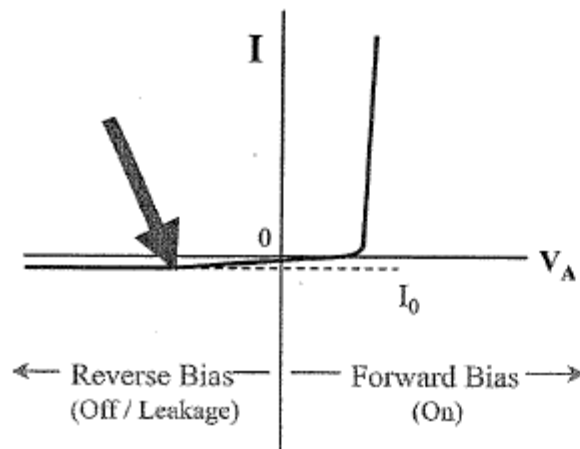
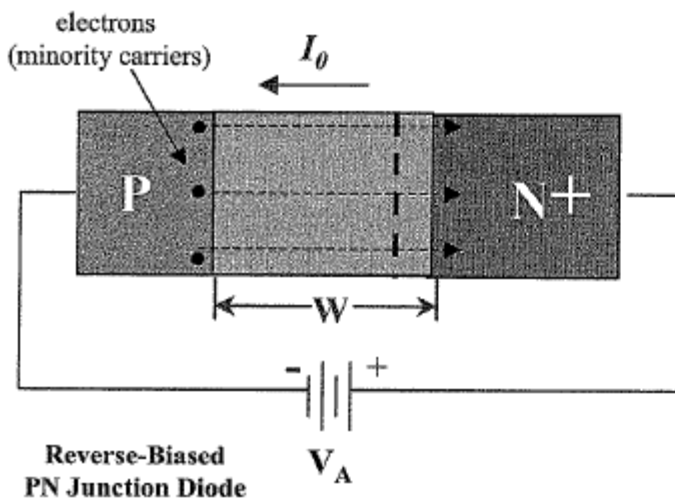
➤ Small gate length and oxide thickness yield low channel resistance, which will increase the drain current.

# MOSFET - Saturation

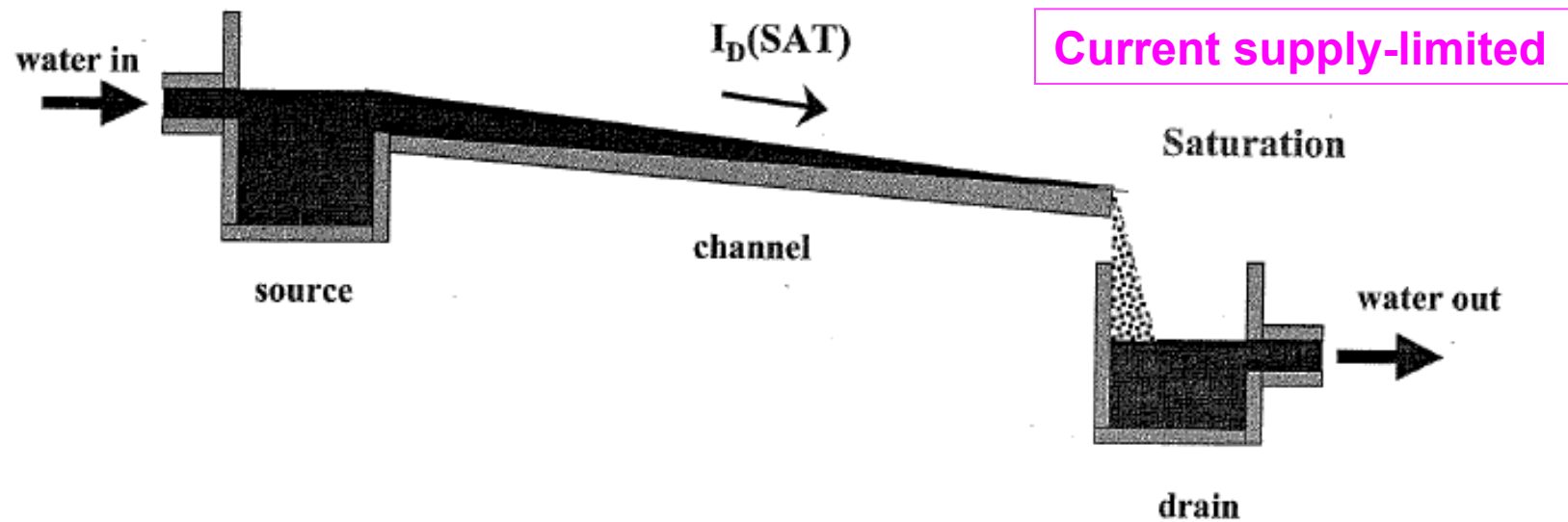
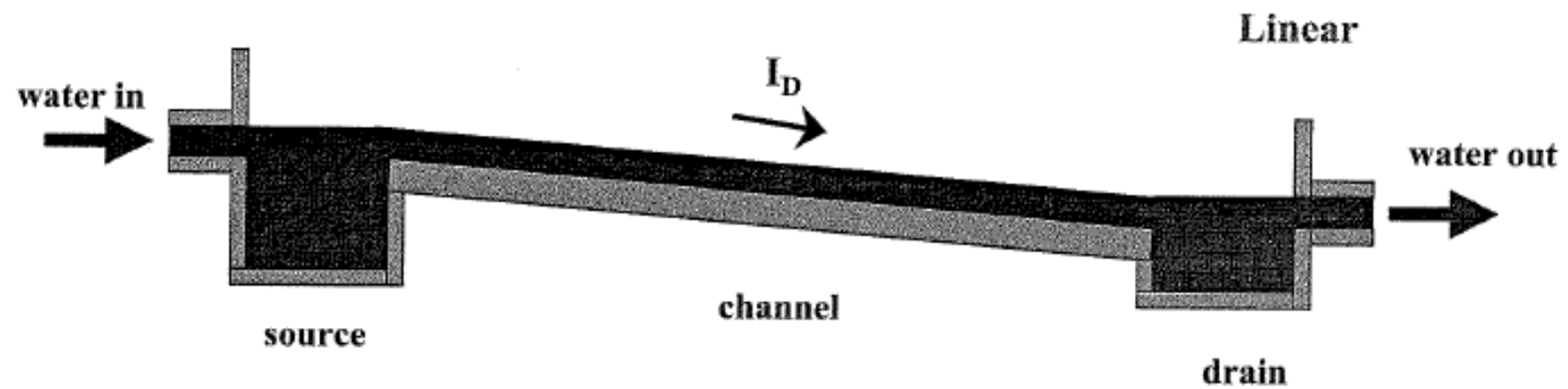


# Analogy with pn diode in reverse bias condition

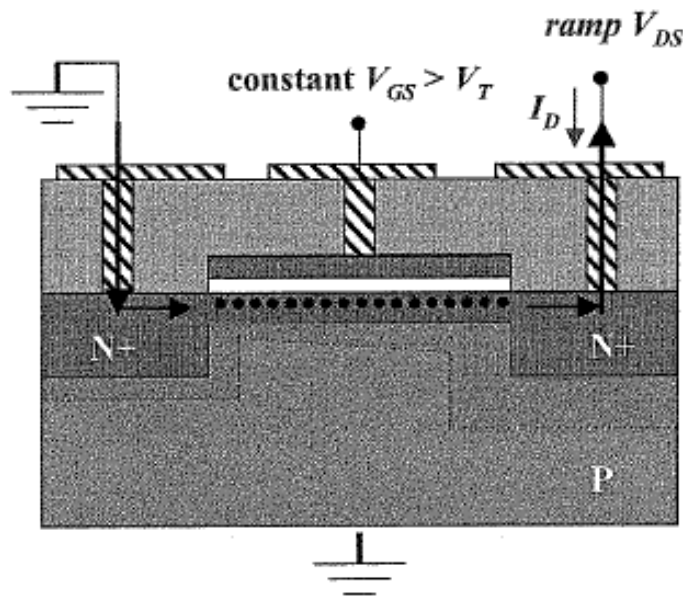
## MOSFET - Saturation (cont.)



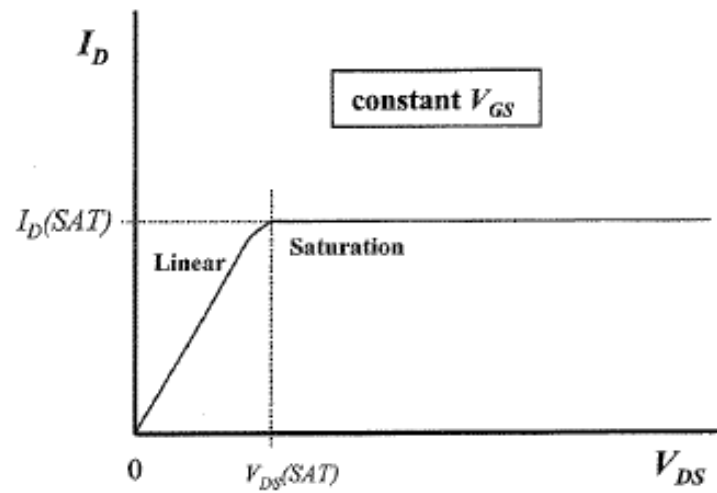
# MOSFET - Saturation Analogy



# MOSFET - I-V Characteristic



For a constant gate voltage (above threshold), ramp  $V_{DS}$  and measure  $I_D$ .



When

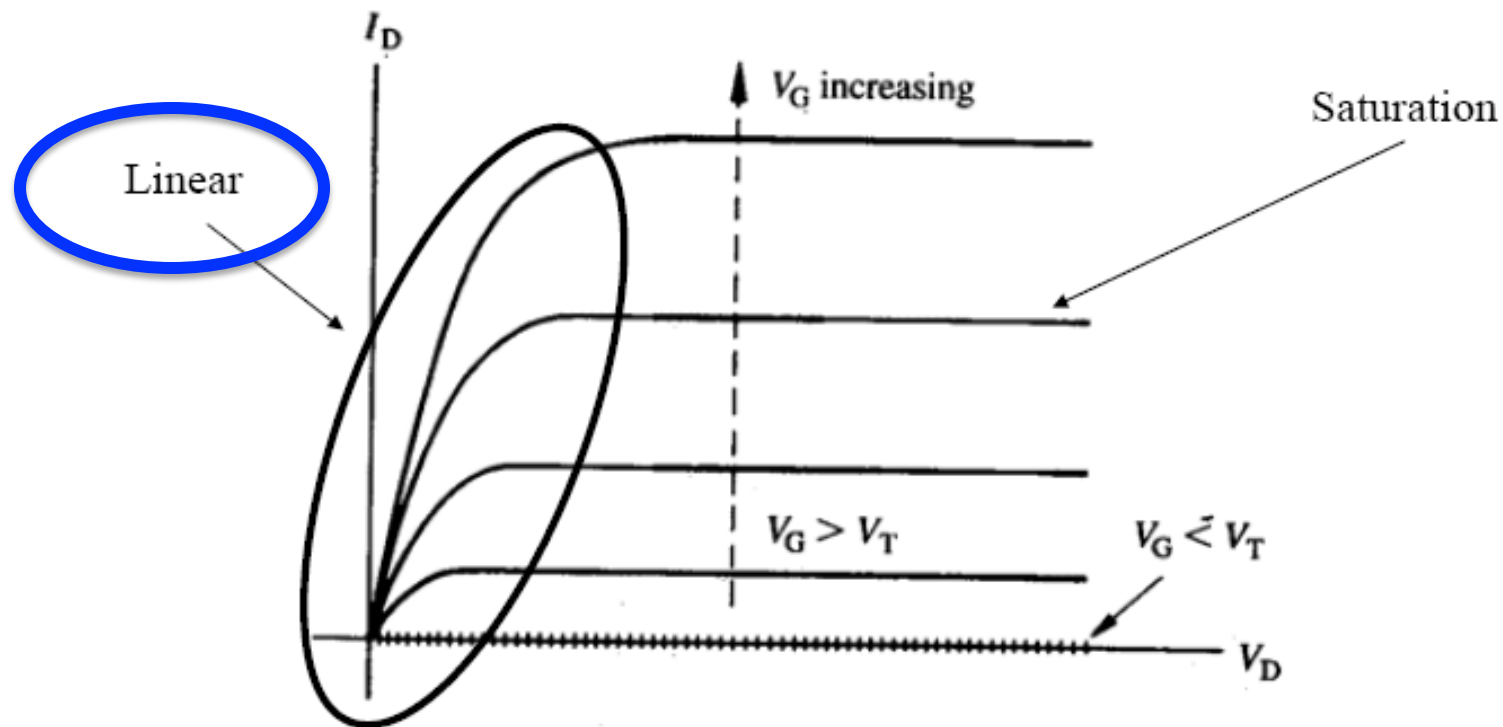
$$V_{GS} - V_T = V_{dsat} < V_D$$

→ saturation



# Linear and Saturation Regime

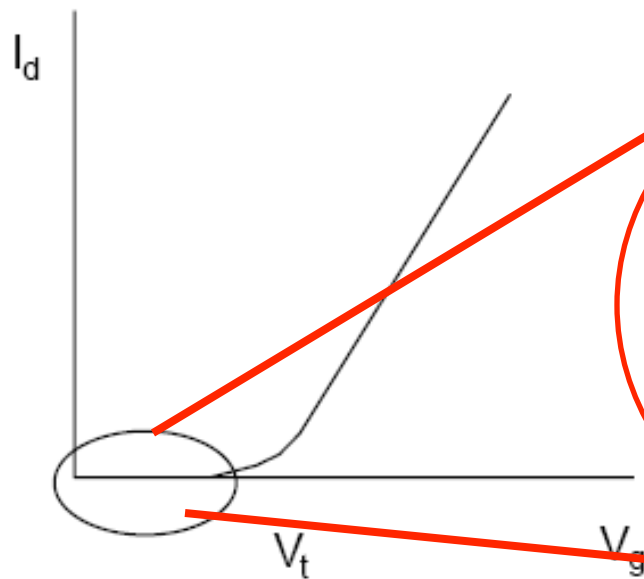
## *Ideal MOSFET I-V Characteristics*



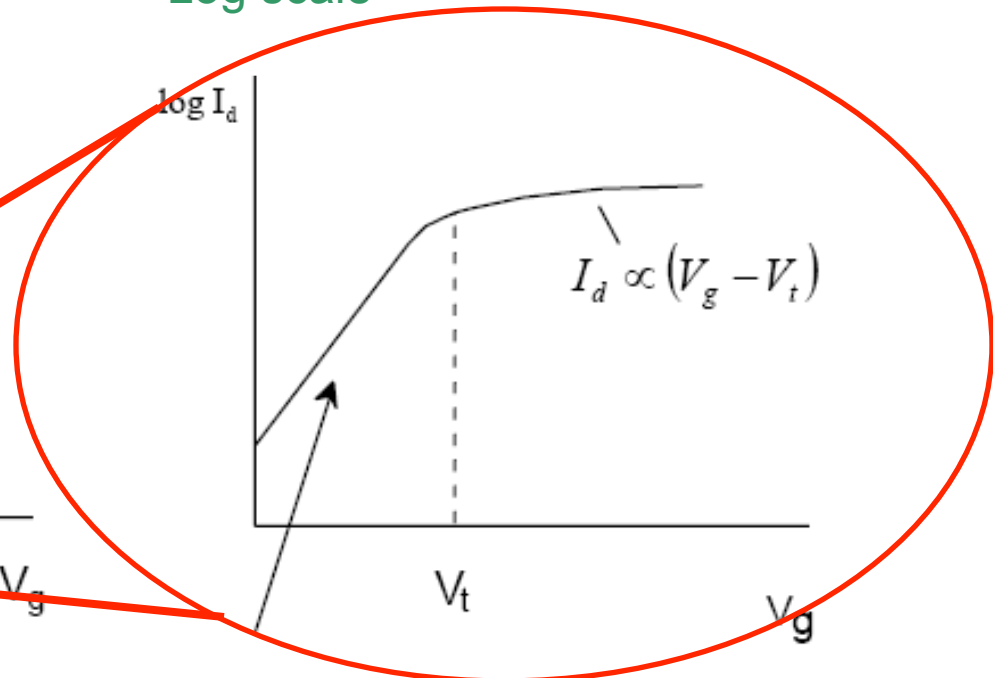


# Subthreshold Current Regime

Linear scale



Log scale



subthreshold weak inversion

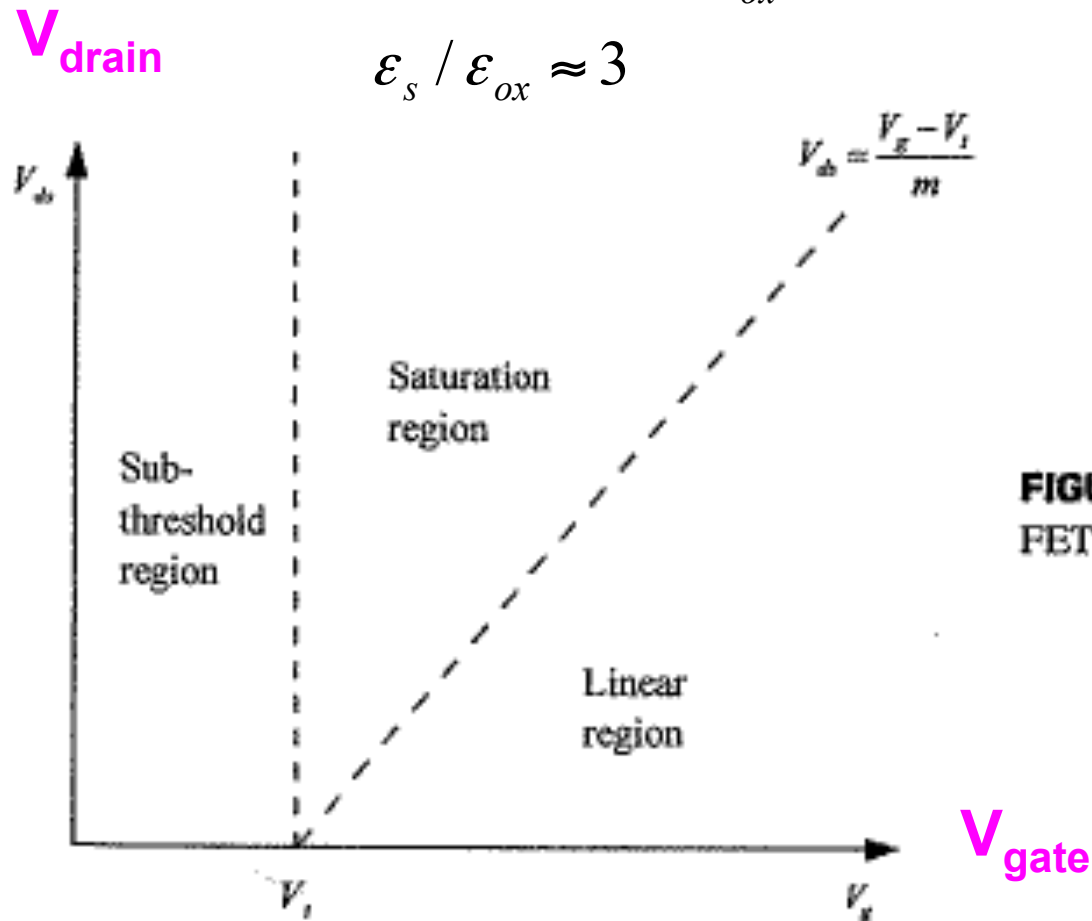
$$Q_{inv} \propto e^{qV_g / nkT}$$

$$I_d \propto e^{qV_g / nkT}$$

# MOSFET Current Regimes

$$m = 1 + \frac{\sqrt{\epsilon_s q N_A / 2\psi_B}}{C_{ox}} = 1 + \frac{C_d}{C_{ox}} = 1 + 3 \frac{t_{ox}}{W_{\max}}$$

$$\epsilon_s / \epsilon_{ox} \approx 3$$



**FIGURE 3.9.** Three regions of MOSFET operation in the  $V_{ds}$ - $V_g$  plane.

# Analytical Formulae for MOSFET I-V Characteristics

# Recall MOS Capacitor

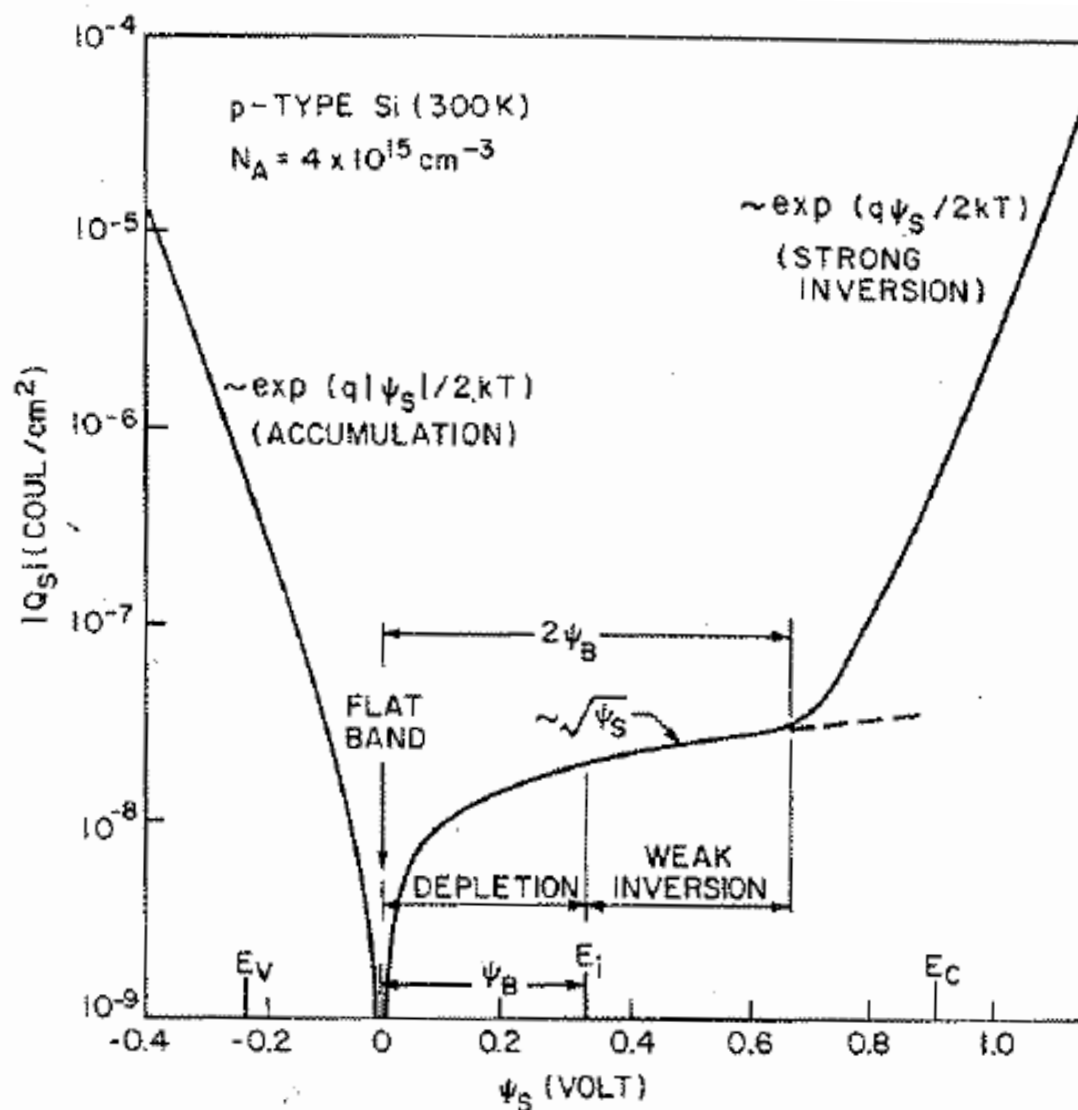
$$p(x) = N_A \exp(-\beta\psi)$$

$$n(x) = \frac{n_i^2}{N_A} \exp(\beta\psi)$$

**Surface potential  $\psi_s$ , surface electrical field  $E_s$ ,  
and total charge in silicon  $Q_s$**

$$E_s = \left\{ \left( \frac{2kT}{q} \right)^2 \left( \frac{qN_A\beta}{2\epsilon_s} \right) [(\exp(-\beta\psi_s) + \beta\psi_s - 1) + \frac{n_i^2}{N_A} (\exp(\beta\psi_s) - \beta\psi_s - 1)] \right\}^{1/2}$$

$$Q_s = -\epsilon_s E_s$$



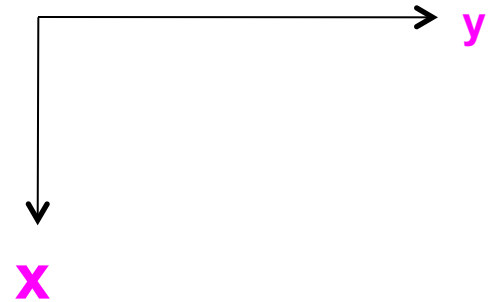
**Fig. 5** Variation of space-charge density in the semiconductor as a function of the surface potential  $\psi_s$  for a p-type silicon with  $N_A = 4 \times 10^{15} \text{ cm}^{-3}$  at room temperature;  $\psi_B$  is the potential difference between the Fermi level and the intrinsic level of the bulk semiconductor. (After Garrett and Brattain, Ref. 13.)

# Inversion Concentration in a MOSFET

Electron concentration in the inversion channel  
along (y) the gate

$$n(x, y) = \frac{n_i^2}{N_A} \exp(\beta[\psi - V(y)])$$

$\psi$  inversion potential (band bending)  
with  $\psi_s$  at the surface



$$E_s^2 =$$

$$= \left( \frac{2kTN_A}{\epsilon_s} \right)^2 [(\exp(-\beta\psi_s) + \beta\psi_s - 1) + \frac{n_i^2}{N_A} (\exp(-\beta V) \exp(\beta\psi_s) - \beta\psi_s - 1)]$$

$$\psi(0, y) = V(y) + 2\psi_B$$

$$W_{\max} = \sqrt{\frac{2\epsilon_s [V(y) + 2\psi_B]}{qN_A}}$$

# Gradual Channel Approximation

## 1-D Model of the MOSFET:

**Key assumption** in the *gradual channel approximation* (GCA) is to assume that the variation of the electric field in the y-direction (along the channel) is much less than the corresponding variation in the x-direction (perpendicular to the channel, i.e. gate field).

This allows to reduce Poisson's equation to the 1-D form (x component only).

GCA is valid for most of the channel regions **except** beyond the pinch-off point.

# Gradual Channel Approximation

Current density at any point (x,y)

$$J_n(x, y) = -q\mu_n n(x, y) \frac{dV(y)}{dy}$$

To get the current we multiply the density by W (width of the transistor) and integrate over the inversion channel thickness in x direction.

$$I_{ds}(y) = qW \int_0^{x_i} \mu_n n(x, y) \frac{dV(y)}{dy} dx$$

The depth of the inversion channel  $x_i$  is defined as the bottom of the inversion layer where  $\psi = \psi_B$



# Gradual Channel Approximation

$$Q_n(y) = -q \int_0^{x_i} n(x, y) dx \quad I_{ds}(y) = qW \int_0^{x_i} \mu_n n(x, y) \frac{dV(y)}{dy} dx$$

$$I_{ds}(y) = -\mu_n W \frac{dV(y)}{dy} Q_n(V)$$

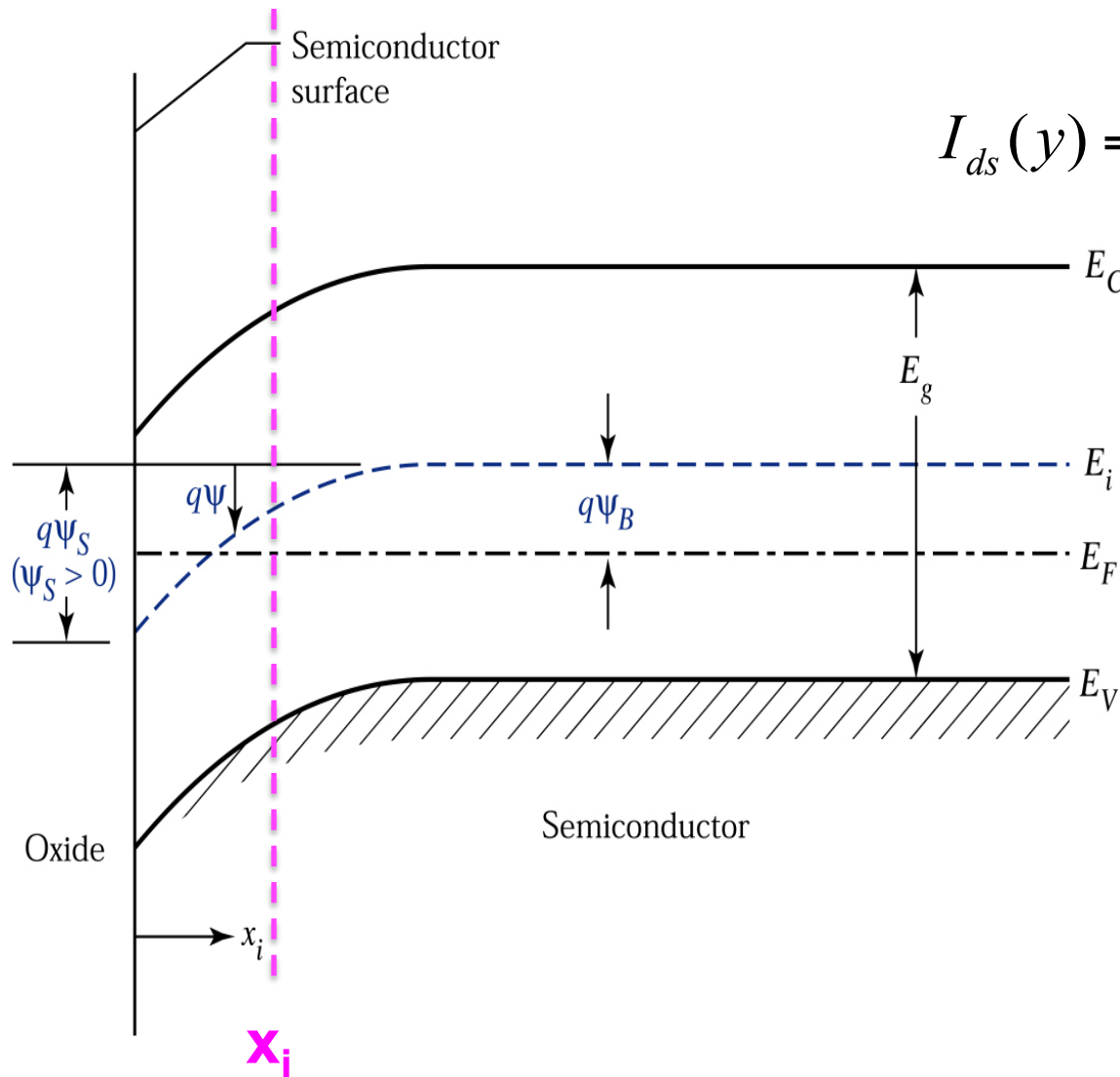
$$\int_0^L I_{ds}(y) dy = - \int_0^L \mu_n W \frac{dV(y)}{dy} Q_n(V) dy$$

**Note that since V is function of y only, V is interchangeable with y.**

**We can multiply both sides by dy and integrate from 0 to L. Since current continuity requires  $I_{ds}$  to be constant, i.e. independent of y. Therefore we obtain:**

$$I_{ds} = \mu_{eff} \frac{W}{L} \int_0^{V_{ds}} [-Q_n(V)] dV$$

# Gradual Channel Approximation channel thickness



$$I_{ds}(y) = qW \int_0^{x_i} \mu_n n(x, y) \frac{dV(y)}{dy} dx$$

0 corresponds to  $\psi_s$  and  
 $x_i$  corresponds to  $\psi_b$   
 recall  $\psi_s = 2\psi_b$  for the  
 onset of inversion

$$\int_0^{x_i} \rightarrow \int_{2\psi_s}^{\psi_B}$$

# PAO and SAH' s Double Integral

$$n(x, y) = n(\psi, V) = \frac{n_i^2}{N_A} \exp(\beta[\psi - V])$$

$$Q_n(V) = -q \int_{\psi_s}^{\psi_B} n(\psi, V) \frac{dx}{d\psi} d\psi$$

$$= -q \int_{\psi_s}^{\psi_B} \frac{n_i^2 / N_A \exp[\beta(\psi - V)]}{E(\psi, V)} d\psi$$

# Pao and Sah's Double Integral

$$I_{ds} = q\mu_{eff} \frac{W}{L} \int_0^{V_{ds}} \left( \int_{\psi_s}^{\psi_B} \frac{n_i^2 / N_A \exp[\beta(\psi - V)]}{E(\psi, V)} d\psi \right) dV$$

Now we need to relate  $\psi_s$  to the gate voltage:

$$\begin{aligned} V_g &= V_{FB} + \psi_s - \frac{Q_s}{C_{ox}} = \\ &= V_{FB} + \psi_s + \frac{\sqrt{2\varepsilon_s kTN_A}}{C_{ox}} \left[ \frac{q\psi_s}{kT} + \frac{n_i^2}{N_A} \exp[\beta(\psi_s - V)] \right]^{1/2} \end{aligned}$$

Which is an implicit equation for  $\psi_s(V)$ .

Both equations have to be solved numerically.

# Pao and Sah's Double Integral

$$V_g = V_{FB} + \psi_s + \frac{\sqrt{2\epsilon_s k T N_A}}{C_{ox}} \left[ \frac{q\psi_s}{kT} + \frac{n_i^2}{N_A} \exp[\beta(\psi_s - V)] \right]^{1/2}$$

The last equation has been obtained from

$$Q_s = -\epsilon_s E_s(\psi_s)$$

and

And

$$V_g = V_{FB} + \psi_s - \frac{Q_s}{C_{ox}}$$

$$E_s^2 =$$

$$= \left( \frac{2kTN_A}{\epsilon_s} \right) \left[ (\exp(-\beta\psi) + \beta\psi - 1) + \frac{n_i^2}{N_A} (\exp(-\beta V) \exp(\beta\psi) - \beta\psi - 1) \right]^{1/2}$$

where we kept only the two significant terms in strong inversion.

# Charge Sheet Approximation

In order to derive an **analytical formula** we simplify the inversion charge using **charge-sheet approximation**, in which the **inversion-layer thickness  $x_i$  is treated as zero**. In other words, it assumes that all the inversion charges are located at the silicon interface like a sheet of charge and that there is no potential drop or band bending across the inversion layer. After the onset of inversion, the surface potential is pinned at  $\psi_s = 2\psi_B + V(y)$  as discussed earlier.

We proceed as follows:

1) we determine the depletion charge, 2) the total charge density in silicon, and 3) calculate the inversion charge density:

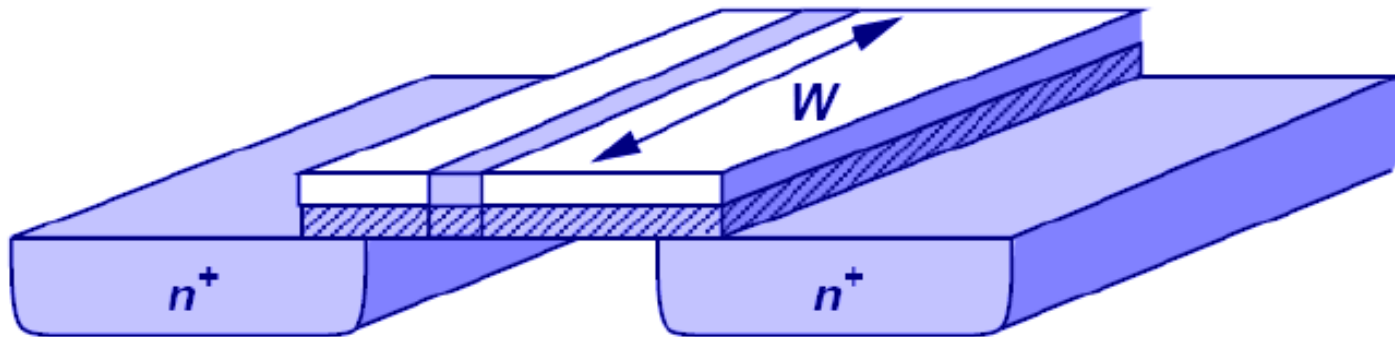
$$Q_d = -qN_A W_{\max} = -\sqrt{2\epsilon_s qN_A (2\psi_B + V)}$$

$$Q_s = -C_{ox} (V_g - V_{FB} - \psi_s) =$$

$$= -C_{ox} (V_g - V_{FB} - 2\psi_B - V)$$

where  $V$  is the potential drop due to the drain bias

## Channel Charge Density



$$Q = WC_{ox}(V_{GS} - V_{TH})$$

no reference to  
channel thickness

- The channel charge density is equal to the gate capacitance times the gate voltage in excess of the threshold voltage.

# Charge Sheet Approximation

Therefore the inversion charge is

$$\begin{aligned} Q_n &= Q_s - Q_d = \\ &= -C_{ox}(V_g - V_{FB} - 2\psi_B - V) + \sqrt{2\varepsilon_s q N_A (2\psi_B + V)} \end{aligned}$$

Substituting  $Q_n$  into current equation

$$I_{ds} = \mu_{eff} W \int_0^{V_{ds}} [-Q_n(V)] dV$$

and carrying out the integration in variable V, one obtains

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left[ (V_g - V_{FB} - 2\psi_B - \frac{V_{ds}}{2}) \cdot V_{ds} - \frac{2\sqrt{2\varepsilon_s q N_A}}{3C_{ox}} [(2\psi_B + V_{ds})^{3/2} - (2\psi_B)^{3/2}] \right]$$



# Charge Sheet Approximation

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left[ (V_g - V_{FB} - 2\psi_B - \frac{V_{ds}}{2}) \cdot V_{ds} - \frac{2\sqrt{2\epsilon_s q N_A}}{3C_{ox}} [(2\psi_B + V_{ds})^{3/2} - (2\psi_B)^{3/2}] \right]$$

The equation indicates that for a given  $V_g$ , the drain current first increases linearly with the drain voltage  $V_{ds}$  (called also the linear or triode region), then gradually levels off to a saturated value (saturation region).

## Charge Sheet Approximation Linear Region

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left[ (V_g - V_{FB} - 2\psi_B - \frac{V_{ds}}{2}) \cdot V_{ds} - \frac{2\sqrt{2\epsilon_s q N_A}}{3C_{ox}} [(2\psi_B + V_{ds})^{3/2} - (2\psi_B)^{3/2}] \right]$$

When  $V_{ds}$  is small we can expand the last equation into a power series in  $V_{ds}$  and keep only the lowest-order (first-order terms in  $V_{ds}$ )

$$\begin{aligned} I_{ds} &= \mu_{eff} C_{ox} \frac{W}{L} \left[ V_g - V_{FB} - 2\psi_B - \frac{\sqrt{4\psi_B \epsilon_s q N_A}}{C_{ox}} \right] \cdot V_{ds} = \\ &= \mu_{eff} C_{ox} \frac{W}{L} (V_g - V_T) V_{ds} \end{aligned}$$

Where  $V_T$  is

$$V_T = V_{FB} - 2\psi_B - \frac{\sqrt{4\psi_B \epsilon_s q N_A}}{C_{ox}}$$

(already familiar to us from our MOS capacitor derivation) and we have assumed That  $V_{ds}/2 \ll V_{gs} - V_T$

# Simple Estimate of MOSFET Current in Inversion Regime

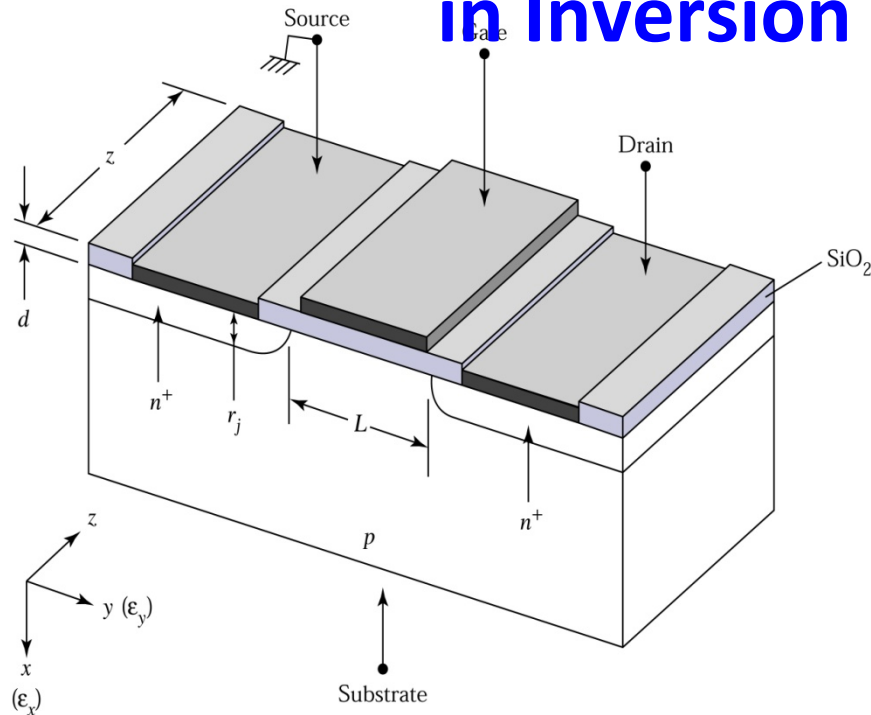
$$I_D = \frac{Q}{t}$$

Mobile charge in the channel

$$Q = C_{ox}(V_G - V_T)$$

Estimate of the transit time

$$t = \frac{L}{v_d} = \frac{L}{E\mu} = \frac{L}{(V_{ds}/L)\mu} = \frac{L^2}{V_{ds}\mu}$$



$$Q_n = C_{ox}^{tot} V = \frac{\epsilon_{ox} A}{t_{ox}} (V_{GS} - V_T) = \frac{\epsilon_{ox} ZL}{t_{ox}} (V_{GS} - V_T) = ZLC_{ox} (V_{GS} - V_T)$$

$$I_d = \frac{Z\mu C'_{ox}}{L} (V_{gs} - V_T) V_{ds}$$

# Charge Sheet Approximation Linear Region

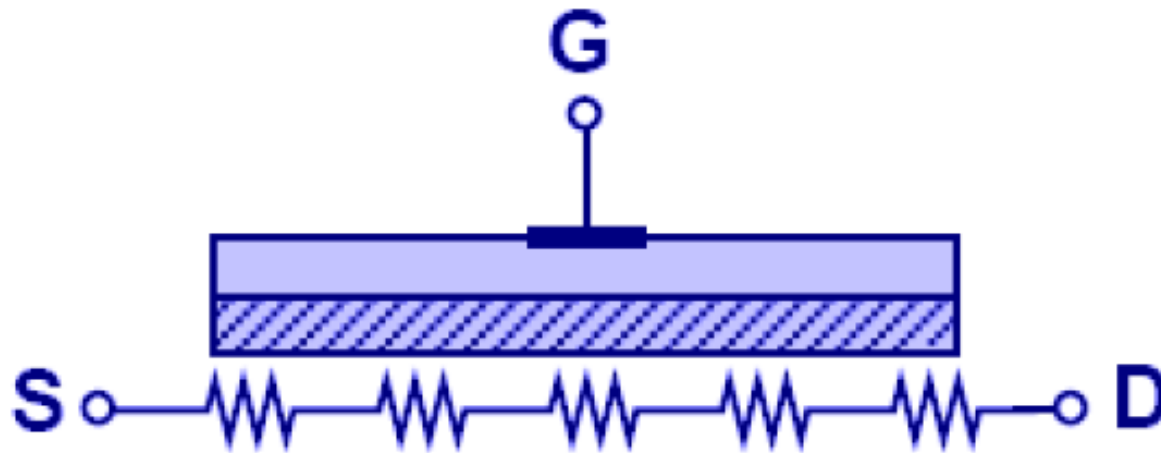
When  $V_g$  is below  $V_T$  there is very little current flowing and the MOSFET is in subthreshold regime (to be addressed next).

In the linear regime, the MOSFET simply acts like a resistor with a sheet resistivity

$$\rho_{sh} = \frac{1}{\mu_{eff} C_{ox} (V_g - V_T)}$$

modulated by the gate voltage.

## Voltage-Dependent Resistor

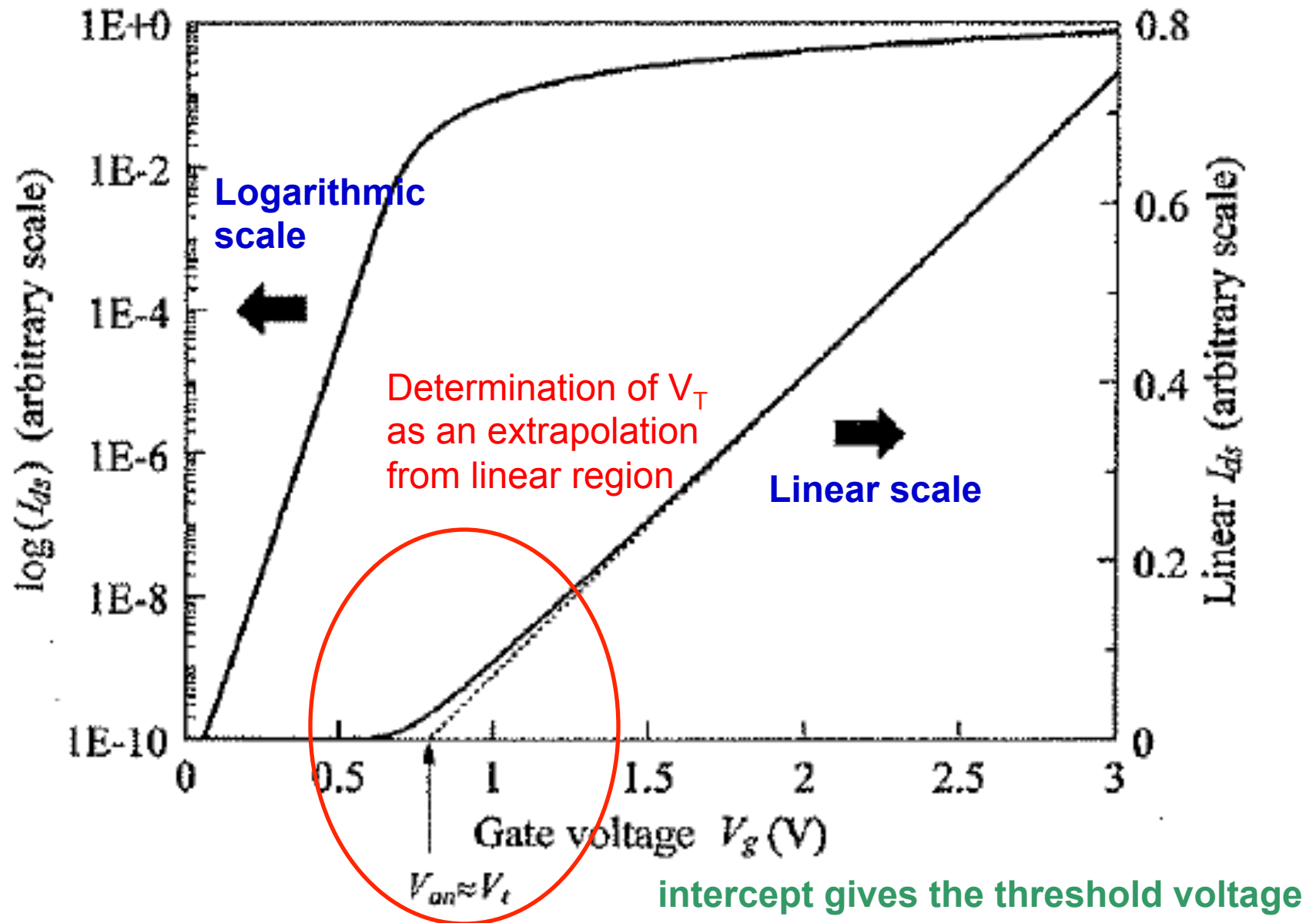


- The inversion channel of a MOSFET can be seen as a resistor.
- Since the charge density inside the channel depends on the gate voltage, this resistance is also voltage-dependent.

# Determination of the Threshold Voltage from the Linear Behavior

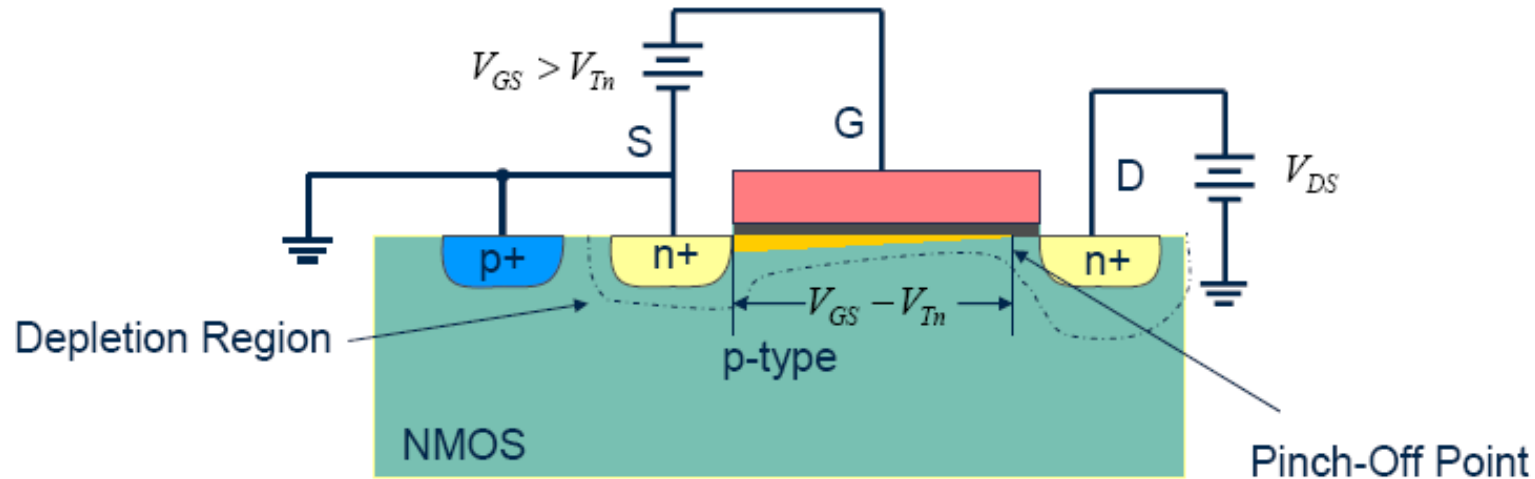
The threshold voltage  $V_T$  can be determined by plotting  $I_{ds}$  versus  $V_g$  at low drain voltages as shown in the figure (see next slide). The extrapolated intercept of the linear portion of  $I_{ds}(V_g)$  curve with the  $V_g$ -axis gives the approximate value of  $V_T$ . In reality such a linearly extrapolated threshold voltage is slightly higher than “ $2\psi_B$ ” due to inversion-layer capacitance and other effects to be discussed later. The  $I_{ds}(V_g)$  curve is not linear near threshold voltage, because charge-sheet-approximation” is no longer valid in this regime.

# Charge Sheet Approximation Linear Region



# Saturation Regime and Pinch-Off

## Pinching the MOS Transistors



- When  $V_{DS} > V_{DS,sat}$  the channel is "pinched" off at drain end (hence the name "pinch-off region")
- Drain mobile charge goes to zero (region is depleted), the remaining electric field is dropped across this high-field depletion region
- As the drain voltage is increases further, the pinch off point moves back towards source
- Channel Length Modulation: The effective channel length is thus reduced  $\rightarrow$  higher  $I_{DS}$

CLM will be addressed later on



# Saturation Regime

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left[ (V_g - V_{FB} - 2\psi_B - \frac{V_{ds}}{2}) \cdot V_{ds} - \frac{2\sqrt{2\epsilon_s q N_A}}{3C_{ox}} [(2\psi_B + V_{ds})^{3/2} - (2\psi_B)^{3/2}] \right]$$

For larger values of  $V_{ds}$ , the second order terms in the power series expansion are not negligible and must be kept. A good approximation of the  $I_{ds}$  current can be obtained as:

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left( (V_g - V_T) V_{ds} - \frac{m}{2} V_{ds}^2 \right)$$

$$m = 1 + \frac{\sqrt{\epsilon_s q N_A \psi_B}}{2C_{ox}} = 1 + \frac{C_d}{C_{ox}} = 1 + \frac{3t_{ox}}{W_{max}} \quad \frac{\epsilon_s}{\epsilon_{ox}} \approx 3$$

$m$  is usually close to unity since the  $W_{max}$  is much larger than  $t_{ox}$

# Saturation Regime

The  $V_T$  can be now expressed in terms of  $m$  as

$$V_T = V_{FB} + (2m - 1)2\psi_B$$

As  $V_{ds}$  increases,  $I_{ds}$  follows a parabolic curve, as shown in the figure on the next slide until a maximum (or saturation value) is reached. This occurs when  $V_{ds} = V_{dsat} = (V_g - V_T)/m$  at which

$$I_{ds} = I_{dsat} = \mu_{eff} C_{ox} \frac{W}{L} \frac{(V_g - V_T)^2}{2m}$$

One often finds a following formula for the saturation current in the textbooks ( $m \approx 1$   $C_d \ll C_{ox}$ )

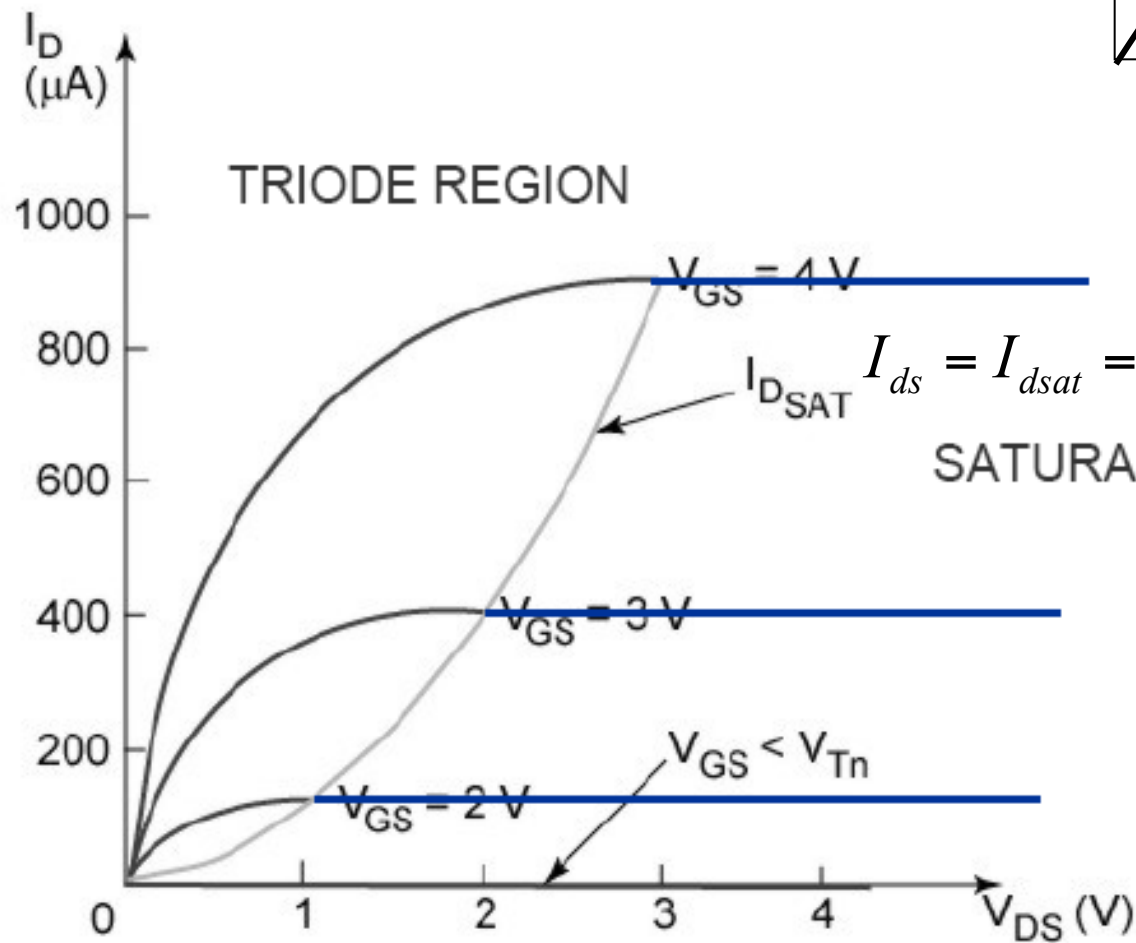
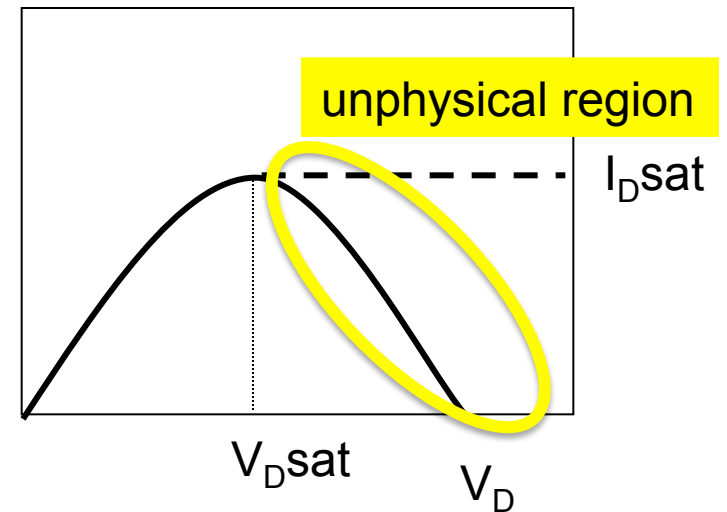
$$I_{ds} = I_{dsat} = \mu_{eff} C_{ox} \frac{W}{2L} (V_g - V_T)^2$$

$$m = 1 + \frac{\sqrt{\epsilon_s q N_A / 2\psi_B}}{C_{ox}} = 1 + \frac{C_d}{C_{ox}} = 1 + 3 \frac{t_{ox}}{W_{max}}$$

$$\epsilon_s / \epsilon_{ox} \approx 3$$

# Saturation Regime

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left( (V_g - V_T) V_{ds} - \frac{m}{2} V_{ds}^2 \right) \quad I_D$$



$$I_{ds} = I_{dsat} = \mu_{eff} C_{ox} \frac{W}{2L} (V_g - V_T)^2$$

SATURATION REGION

# Saturation Regime – explicit calculation

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left( (V_g - V_T) V_{ds} - \frac{m}{2} V_{ds}^2 \right)$$

$$\frac{\partial I_{ds}}{\partial V_{ds}} = 0 = \mu_{eff} C_{ox} \frac{W}{L} (V_g - V_T) - m V_{ds}$$

for  $m \approx 1$

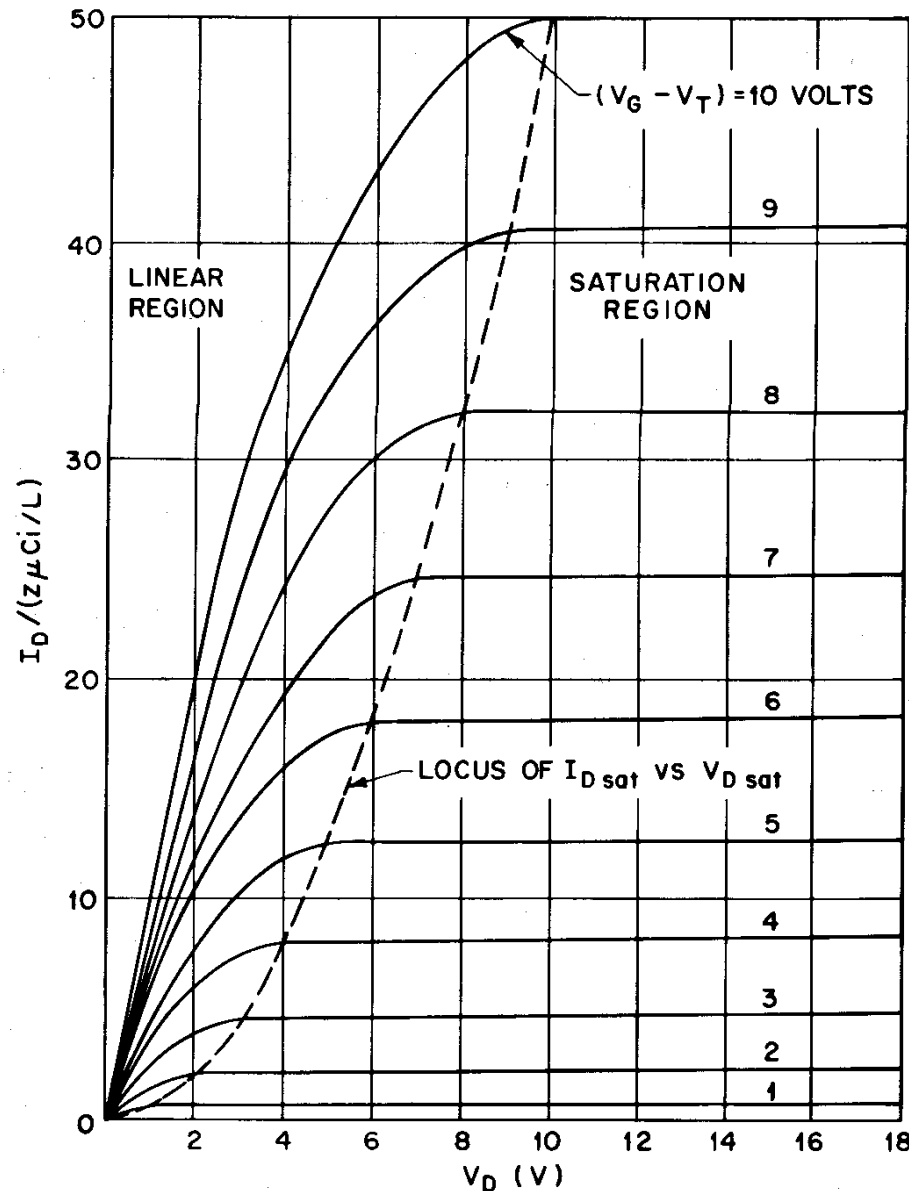
$$\mu_{eff} C_{ox} \frac{W}{L} (V_g - V_T) = V_{ds}$$

then

$$I_{ds}(V_{ds} = \mu_{eff} C_{ox} \frac{W}{L} (V_g - V_T)) = I_{dsat}$$

$$I_{dsat} = \mu_{eff} C_{ox} \frac{W}{2L} (V_g - V_T)^2$$

# Saturation Regime



## Ideal Characteristics of n-channel enhancement mode MOSFET

$$I_{ds} = I_{dsat} = \mu_{eff} C_{ox} \frac{W}{2L} (V_g - V_T)^2$$

$$V_{dsat} = (V_g - V_T)$$

$$I_{dsat} = \mu_{eff} C_{ox} \frac{W}{2L} V_{dsat}^2$$

# Saturation Regime

$$I_{ds} = I_{dsat} = \mu_{eff} C_{ox} \frac{W}{2L} (V_g - V_T)^2$$

**This is valid for low substrate doping where  $W_{max} \gg t_{ox}$  and then  $m \approx 1$ .**

**So beyond  $V_{dsat}$ ,  $I_{ds}$  stays constant at  $I_{dsat}$  independent of  $V_{ds}$ .**

# ONSET of Pinch-Off

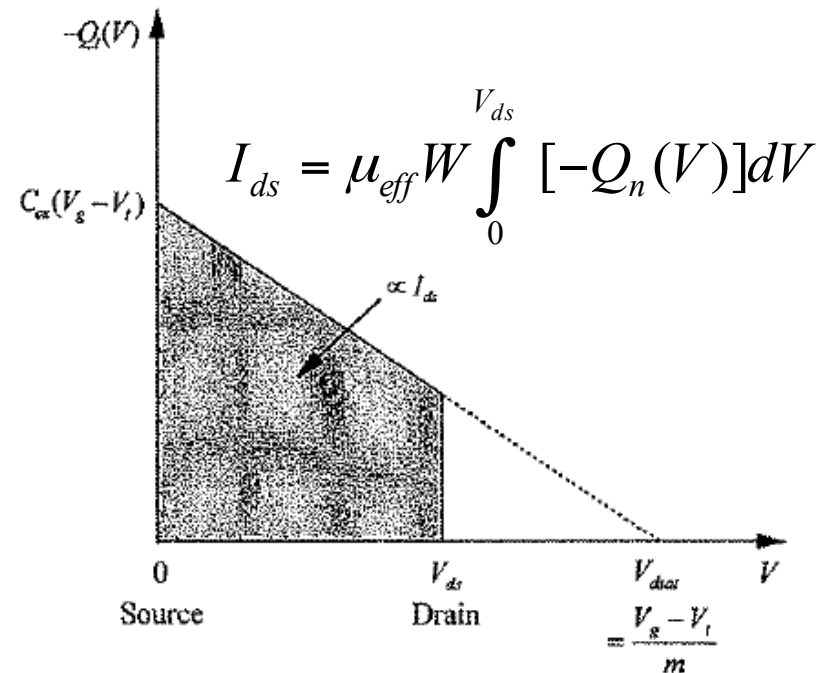
$$Q_n(V) = Q_s - Q_d =$$

$$= -C_{ox}(V_g - V_{FB} - 2\psi_B - V) + \sqrt{2\varepsilon_s q N_A (2\psi_B + V)}$$

For  $V < 2\psi_B$  one can expand the square root term into power series in  $V$  and keep only the two lowest terms:

$$Q_n = Q_s - Q_d = -C_{ox}(V_g - V_T - mV)$$

Drain current is proportional to the area under the  $-Q_n$  curve between  $V=0$  and  $V=V_{ds}$ . When  $V_{ds}$  small,  $Q_n$  is only slightly lower than that at the source end. But as the drain voltage increases  $Q_n$  decreases and goes to zero at  $V_{dsat}$ . Inversion vanishes at the drain – channel saturation. This condition is called **pinch-off**.



**FIGURE 3.5.** Inversion charge density as a function of the quasi-Fermi potential of a point in the channel. Before saturation, the drain current is proportional to the shaded area integrated from zero to the drain voltage.

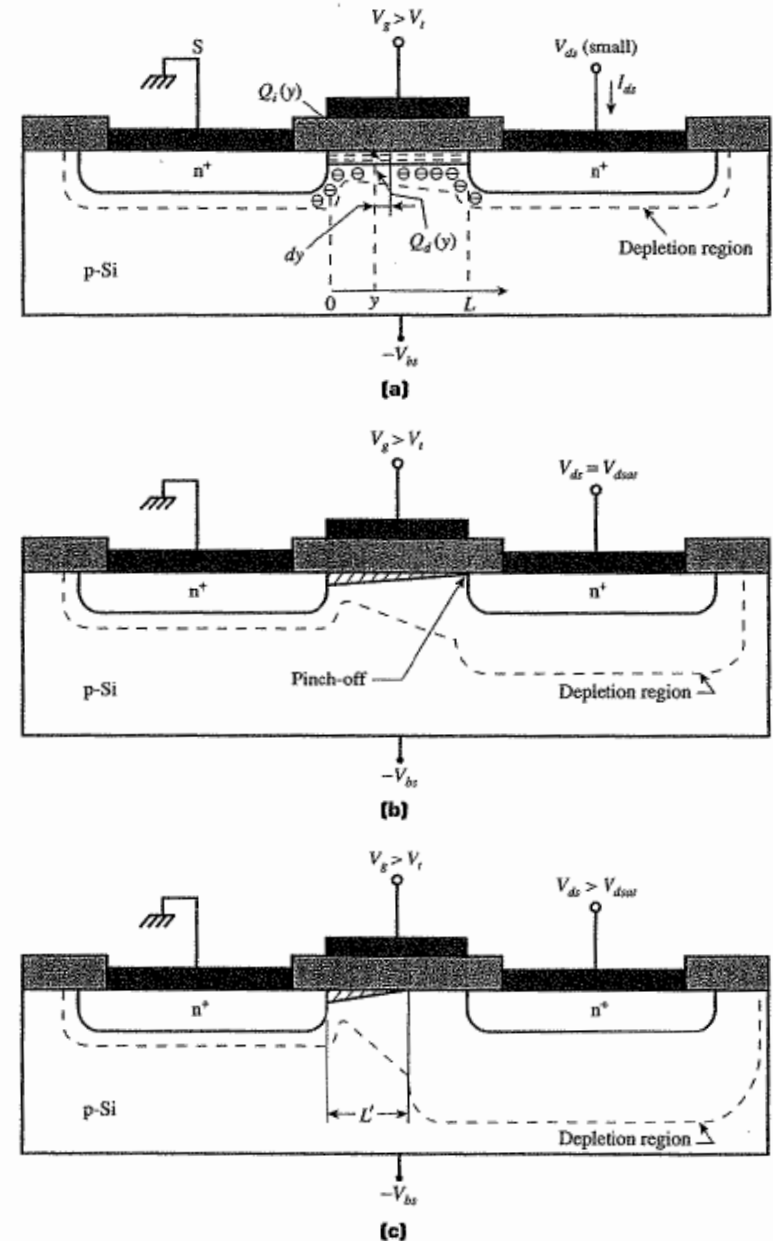
# ONSET of Pinch-Off

When  $V_{ds}$  increases even further (beyond saturation), the **pinch-off point moves toward the source**, but the drain current remains **essentially the same**.

$L'$

$$\int_0^{L'} I_{ds} dy = \mu_{eff} W \int_0^{V_{ds}} [-Q_n(V)] dV$$

But note that we have now  $L' < L$ . This phenomenon is called **channel length modulation** and will be discussed later.



**FIGURE 3.6.** (a) MOSFET operated in the linear region (low drain voltage). (b) MOSFET operated at the onset of saturation. The pinch-off point is indicated by  $Y$ . (c) MOSFET operated beyond saturation where the channel length is reduced to  $L'$ . (After Sze, 1981.)



# ONSET of Pinch-Off

We wish to learn explicitly about  $V(y)$  behavior as a function of  $y$ .  
So far we know  $V(y=0)=0$  and  $V(y=L)=V_{ds}$ .

Using  $Q_n = Q_s - Q_d = -C_{ox}(V_g - V_T - mV)$

We can integrate  $\int_0^y I_{ds} dy = \mu_{eff} W \int_0^{V(y)} [-Q_n(V)] dV$

And obtain  $I_{ds} \cdot y = \mu_{eff} C_{ox} W (V_g - V_T) V(y) - \frac{m}{2} V(y)^2$

Substituting  $I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left( (V_g - V_T) V_{ds} - \frac{m}{2} V_{ds}^2 \right)$

One can solve the resulting equation for  $V(y)$  and obtain

$$V(y) = \frac{V_g - V_T}{m} - \sqrt{\left( \frac{V_g - V_T}{m} \right)^2 - 2 \frac{y}{L} \left( \frac{V_g - V_T}{m} \right) V_{ds} + \frac{y}{L} V_{ds}^2}$$

# ONSET of Pinch-Off

$$V(y) = \frac{V_g - V_T}{m} - \sqrt{\left(\frac{V_g - V_T}{m}\right)^2 - 2\frac{y}{L}\left(\frac{V_g - V_T}{m}\right)V_{ds} + \frac{y}{L}V_{ds}^2}$$

$$m = 1 + \frac{\sqrt{\epsilon_s q N_A / 2\psi_B}}{C_{ox}} = 1 + \frac{C_d}{C_{ox}} = 1 + 3\frac{t_{ox}}{W_{\max}}$$

$$\epsilon_s / \epsilon_{ox} \approx 3$$

This is a very satisfying result:  $V(y)$  depends on the external biases  $V_g$  and  $V_{ds}$ ; it depends also on  $V_T$  and on transistor geometry:  $L$ ,  $t_{ox}$ , and  $W_{\max}$ .

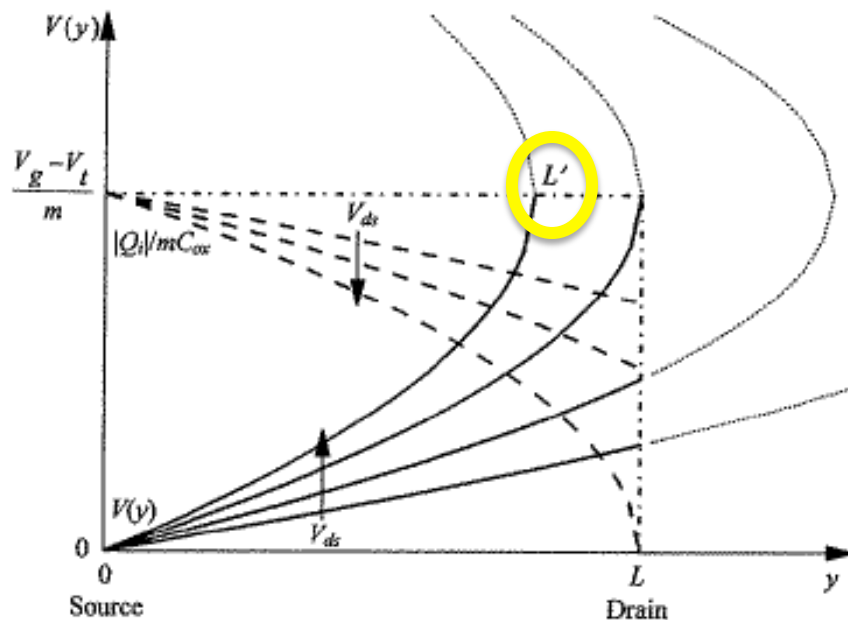
We remind ourselves that the current  $I_{ds}$  = (const at each location  $y$ ) is proportional to the product of  $Q_n(y)dV(y)/dy$ .

We now plot  $Q_n(y)$  and  $V(y)$  in the same figure.

# ONSET of Pinch-Off

$$V(y) = \frac{V_g - V_T}{m} - \sqrt{\left(\frac{V_g - V_T}{m}\right)^2 - 2\frac{y}{L}\left(\frac{V_g - V_T}{m}\right)V_{ds} + \frac{y}{L}V_{ds}^2}$$

Both  $V(y)$  and  $-Q_n/(mC_{ox})$  are plotted below:



**FIGURE 3.7.** Quasi-Fermi potential versus distance between the source and the drain for several  $V_{ds}$ -values from the linear region to beyond saturation. The dashed curves show the corresponding variation of inversion charge density along the channel. The dotted curves help visualize the parabolic behavior of the characteristics.

At low  $V_{ds}$   $V(y)$  varies linearly between source and drain. But as  $V_{ds}$  increases, The inversion charge at the drain decreases due to the lowering of the electron quasi Fermi level. **This is accompanied by a corresponding increase of  $dV(y)/dy$  to maintain the current continuity.** When  $V_{ds}$  reaches saturation we have:  $V_{dsat} = (V_g - V_T)/m$  and  $Q_n(y=L)=0$ .

**This implies that the electric field in the y-direction changes more rapidly than the field in x-direction and the gradual channel approximation breaks down.**

# ONSET of Pinch-Off

Comparison between

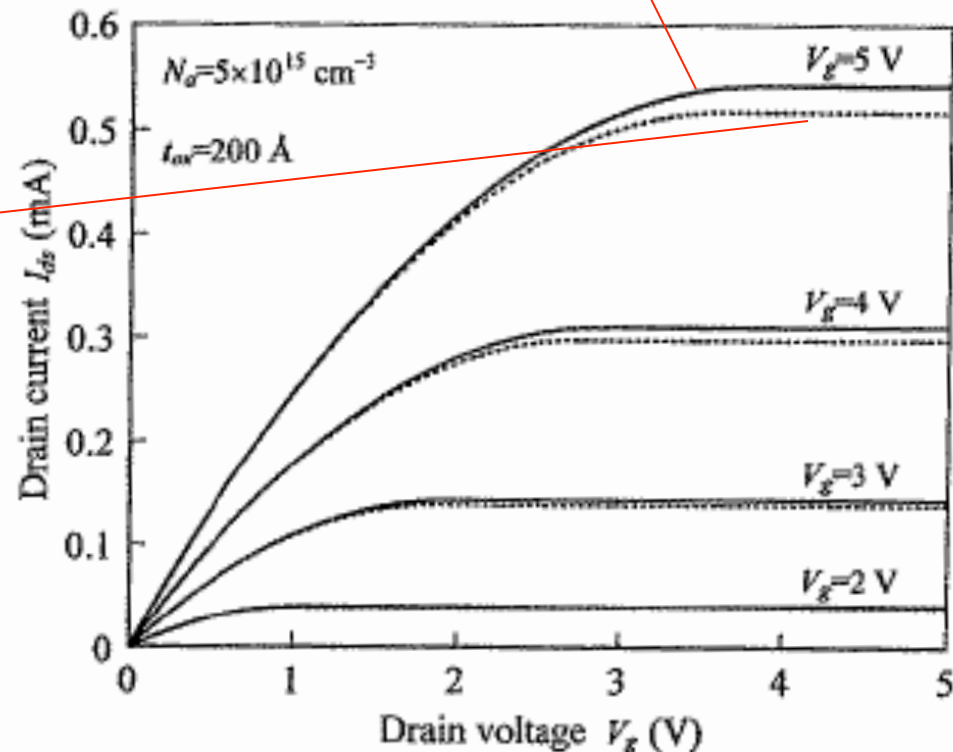
$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left[ (V_g - V_{FB} - 2\psi_B - \frac{V_{ds}}{2}) \cdot V_{ds} - \frac{2\sqrt{2\epsilon_s q N_A}}{3C_{ox}} [(2\psi_B + V_{ds})^{3/2} - (2\psi_B)^{3/2}] \right]$$

and

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left( (V_g - V_T) V_{ds} - \frac{m}{2} V_{ds}^2 \right)$$

**Note: strictly speaking, when  $V_{ds} > 2\psi_B$  we can't expand the square root in power series.**

**But we can differentiate the above equation  $dI_{ds}/dV_{ds}=0$  and we obtain for  $V_{dsat}$ :**



**FIGURE 3.8.**  $I_{ds}$ - $V_{ds}$  curves calculated from the full equation (3.18) (solid curves), compared with the parabolic approximation (3.21) (dotted curves).

# ONSET of Pinch-Off

Note: strictly speaking, when  $V_{sd} > 2\psi_B$  we can't expand the square root in power series.

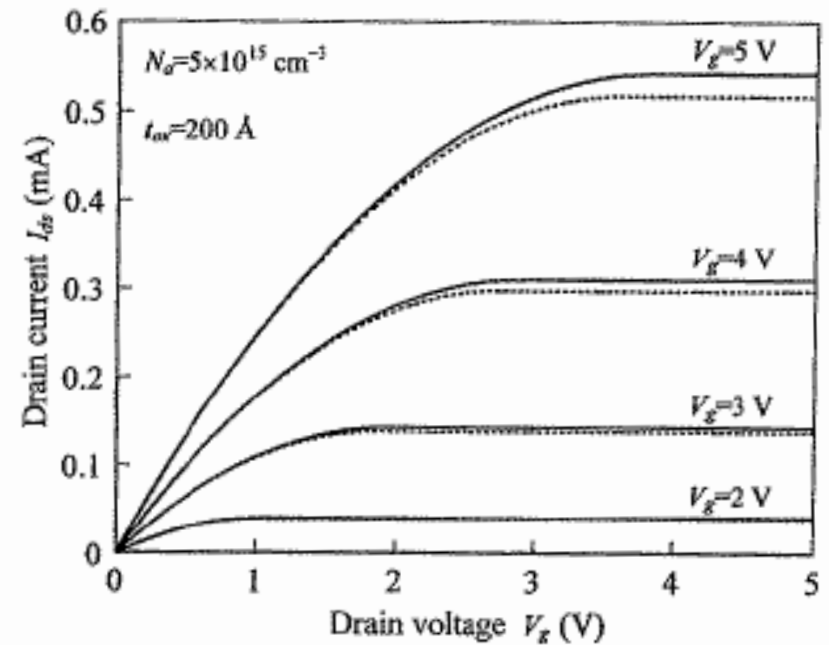
But we can differentiate the above equation  $dI_{ds}/dV_{ds}=0$  and we obtain for  $V_{dsat}$ :

$$V_{dsat} = V_g - V_{FB} - 2\psi_B + \frac{\epsilon_s q N_a}{C_{ox}^2} - \sqrt{\frac{\epsilon_s q N_a}{C_{ox}^2} (V_g - V_{FB}) + \frac{\epsilon_s q N_a}{C_{ox}^2}}$$

The corresponding  $I_{dsat}$  can be found by substituting the above equation in

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left[ (V_g - V_{FB} - 2\psi_B - \frac{V_{ds}}{2}) \cdot V_{ds} - \frac{2\sqrt{2\epsilon_s q N_a}}{3C_{ox}} [(2\psi_B + V_{ds})^{3/2} - (2\psi_B)^{3/2}] \right]$$

(not shown, usually numerical evaluation)



**FIGURE 3.8.**  $I_{ds}$ - $V_{ds}$  curves calculated from the full equation (3.18) (solid curves), compared with the parabolic approximation (3.21) (dotted curves).

# Simplified Analysis for Linear and Saturation MOSFET Regime

Inversion layer thickness      Inversion layer concentration

$$I_D = W \underset{\text{Inversion layer thickness}}{t} \bullet (-q \underset{\text{Inversion layer concentration}}{n} V_{\text{drift}})$$
$$= W \bullet Q_n \bullet V_{\text{drift}}$$

Note:  $I_D$  is constant for all positions along channel

Let  $V_T$  defined to be threshold voltage at Source

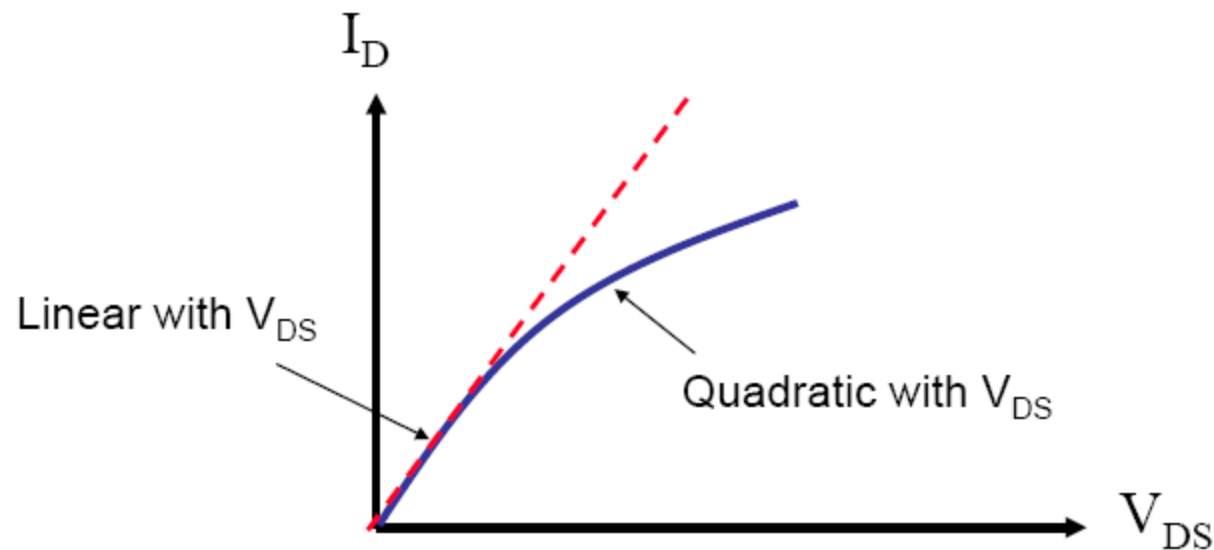
$$V_T(\text{average}) \sim V_T + \frac{V_{DS}}{2} \quad [\text{This is an approximation}]$$

$$Q_n(\text{average}) = C_{ox} (V_G - V_T(\text{average}))$$
$$= C_{ox} \left( V_G - V_T - \frac{V_{DS}}{2} \right)$$

# Simplified Analysis for Linear and Saturation MOSFET Regime

**With**  $v_{\text{drift}} = -\mu_n \mathbf{E} \approx \frac{\mu_n V_{\text{DS}}}{L}$

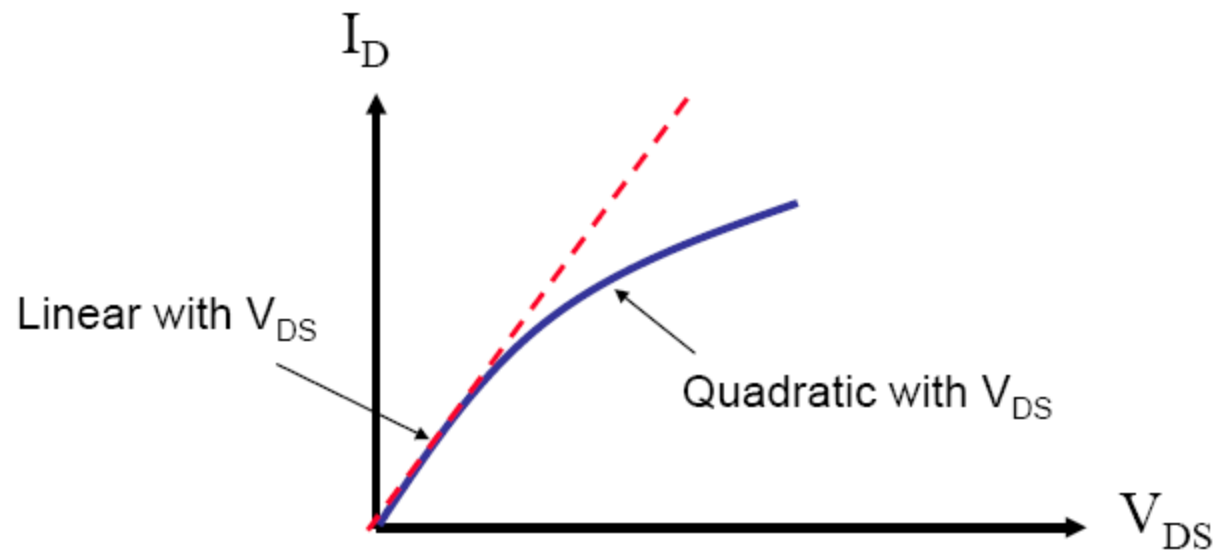
$$I_D = \mu \frac{W}{L} C_{\text{OX}} \left( V_G - V_T - \frac{V_{\text{DS}}}{2} \right) V_{\text{DS}}$$



# Simplified Analysis for Linear and Saturation MOSFET Regime

**With**  $v_{\text{drift}} = -\mu_n \mathbf{E} \approx \frac{\mu_n V_{\text{DS}}}{L}$

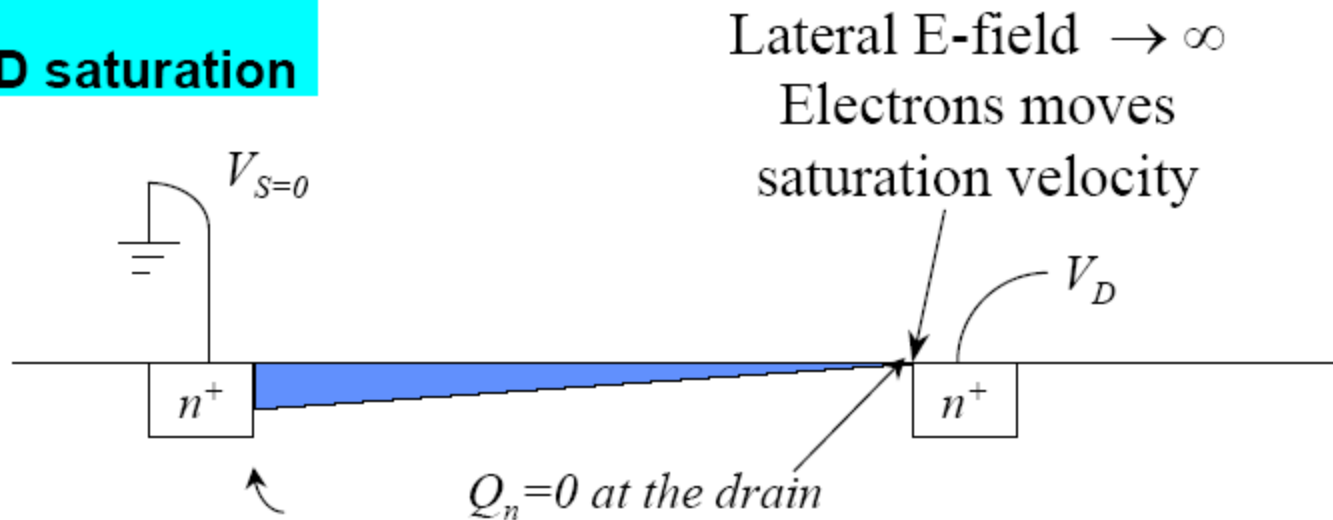
$$I_D = \mu \frac{W}{L} C_{\text{OX}} \left( V_G - V_T - \frac{V_{\text{DS}}}{2} \right) V_{\text{DS}}$$





# Simplified Analysis for Linear and Saturation MOSFET Regime

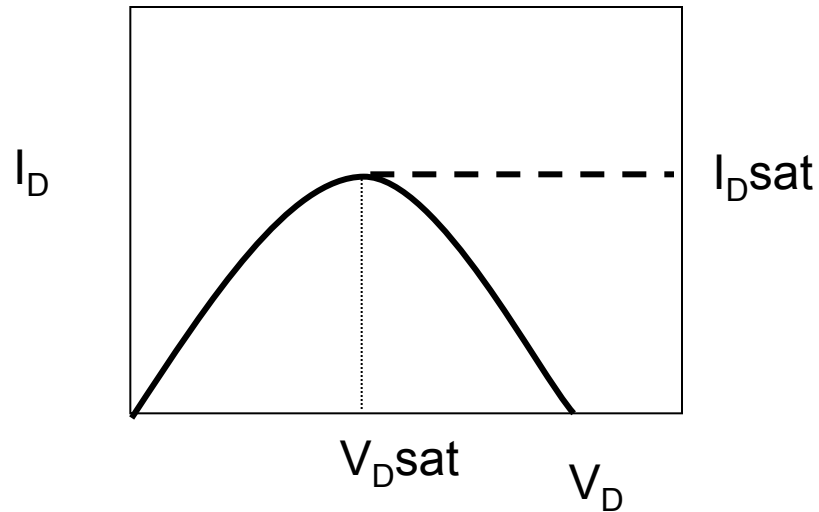
**$V_D$  saturation**



$V_{Dsat}$  is *defined* to be the value of  $V_D$  with  $Q_n = 0$  at drain.

From  $Q_n = C_{ox} (V_G - V_T - V_D)$ , we get  $V_{Dsat} = V_G - V_T$

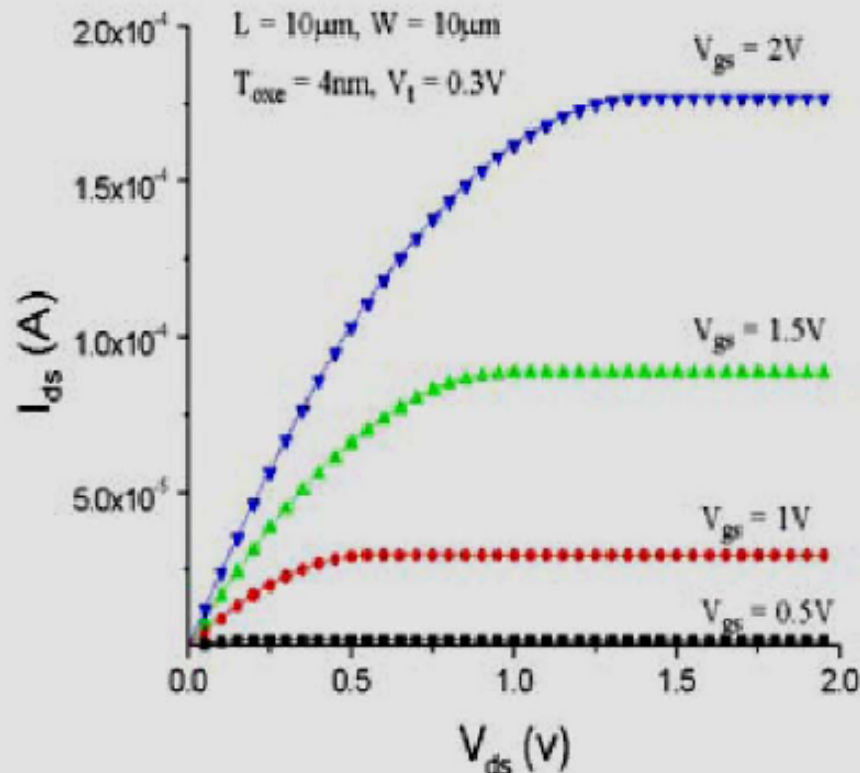
# Simplified Analysis for Linear and Saturation MOSFET Regime



This makes it clear that the branch for  $V_d > V_{dsat}$  has to be discarded as unphysical because it would imply that for  $V_d > V_{dsat}$  we would have at the end of the channel a positive (hole) inversion charge

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} \left( (V_g - V_T) V_{ds} - \frac{m}{2} V_{ds}^2 \right)$$

# Simplified Analysis Saturation MOSFET Regime



- saturation region:

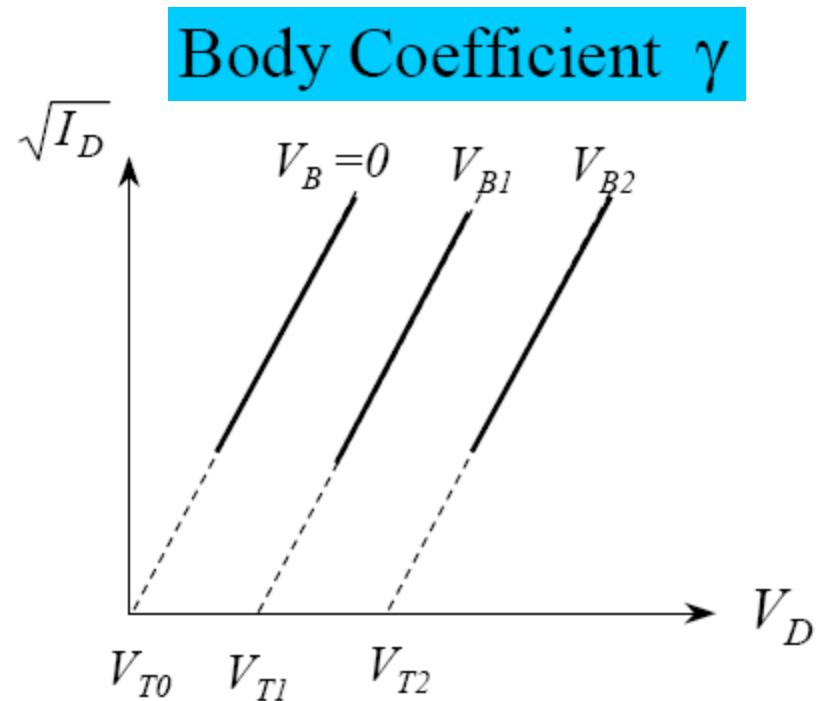
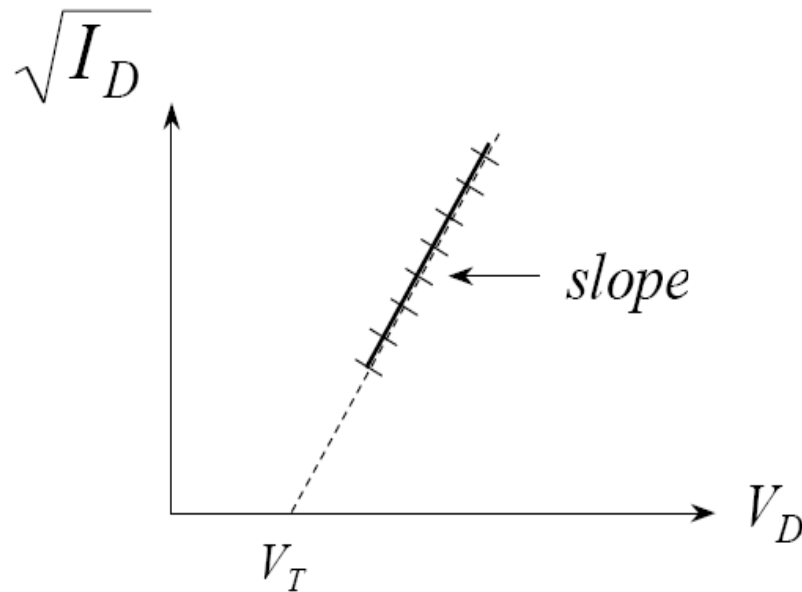
$$V_D \geq V_{Dsat} = V_{GS} - V_T$$

$$I_{Dsat} = \frac{W}{2L} C_{\text{oxe}} \mu_{\text{eff}} (V_{GS} - V_T)^2$$

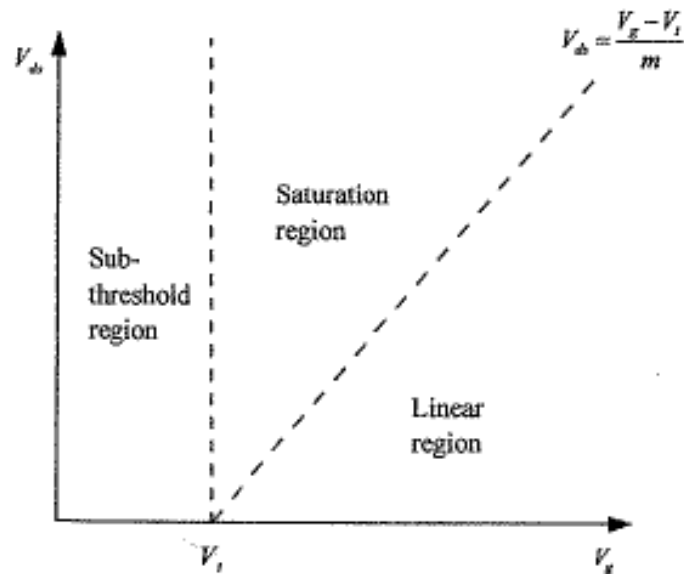
Note that we can extract  $V_T$  now from saturation region. In practice, the extractions of  $V_T$  from linear and saturation regions differed.

# Threshold Voltage Extraction from linear region

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} [V_g - V_T(V_B)] V_{ds}$$



# Subthreshold Characteristics



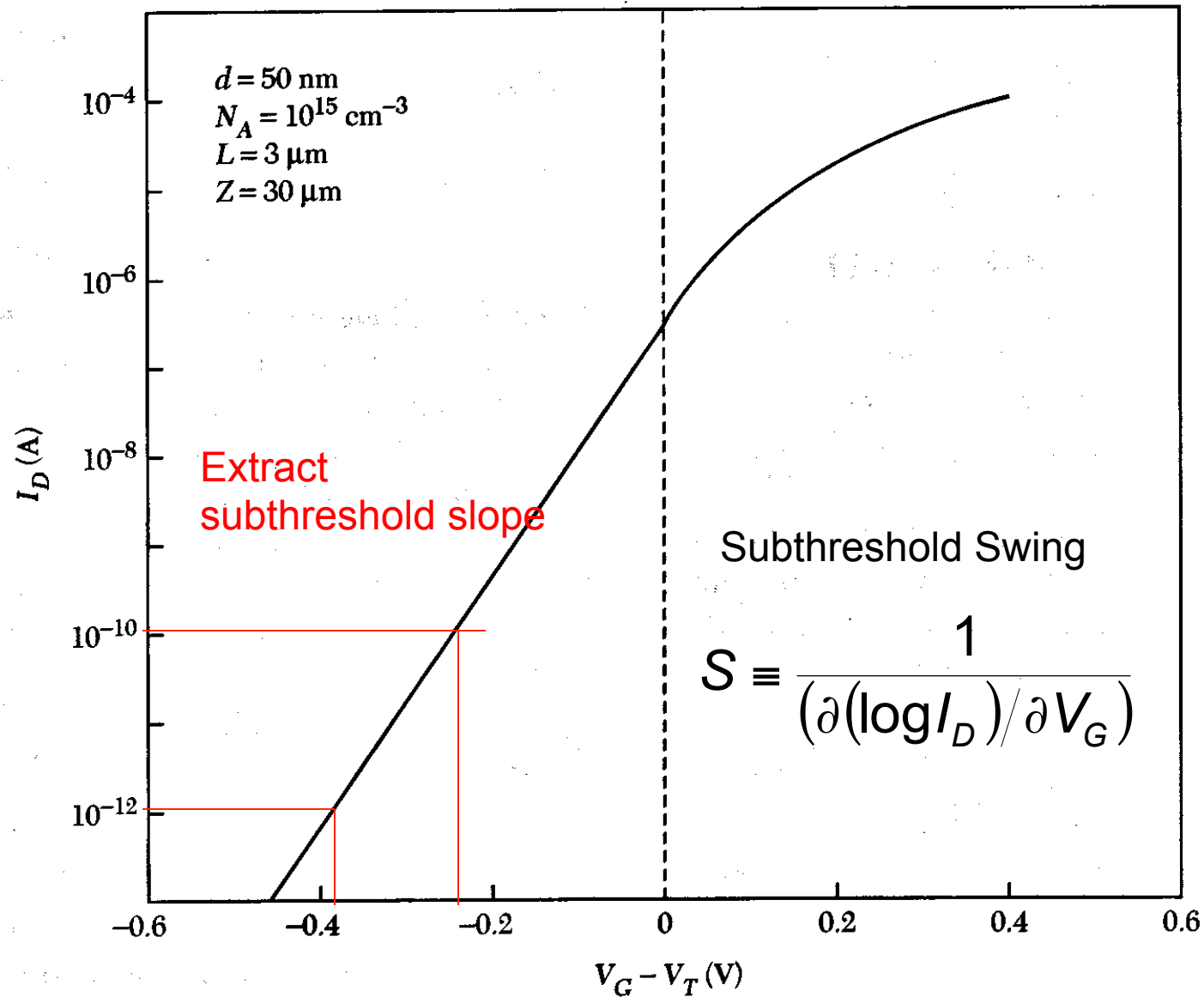
**FIGURE 3.9.** Three regions of MOS-FET operation in the  $V_{ds}$ - $V_g$  plane.

On linear scale, the off-current is negligible. However, on a logarithmic scale, the drain current remains at non-negligible levels for several tenths of a volt below  $V_T$ .

This is because the inversion charge density does not drop to zero abruptly. Rather, it follows an exponential dependence on  $\psi_s$  or  $V_g$ .

$$n(x, y) = n(\psi, V) = \frac{n_i^2}{N_A} \exp(\beta[\psi - V])$$

# Subthreshold Slope or Swing



# Subthreshold Current

## Leakage current issues

---

- ❑ Leakage vs. performance trade-off:
  - For high-speed, need small  $V_T$  and  $L$
  - For low leakage, need high  $V_T$  and large  $L$  (to reduce DIBL and  $V_T$  roll-off)
- ❑ Process scaling
  - $V_T$  reduces with each new process (historically)
  - Leakage increases  $\sim 10X$ !
- ❑ One solution: dual- $V_T$  process
  - Low- $V_T$  transistors: use in critical paths for high speed
  - High- $V_T$  transistors: use to reduce power

# Subthreshold Characteristics

Subthreshold behavior is of particular importance in low-voltage, low-power applications. The subthreshold is the region immediately below  $V_T$ .

$(\psi_B < \psi_s < 2\psi_B)$  is called the **WEAK INVERSION** region and has received a lot of attention in the last 15 years.

[Comment: Swiss watch industry, integrated circuits for watches, Prof. Eric Vittoz, University of Lausanne.]

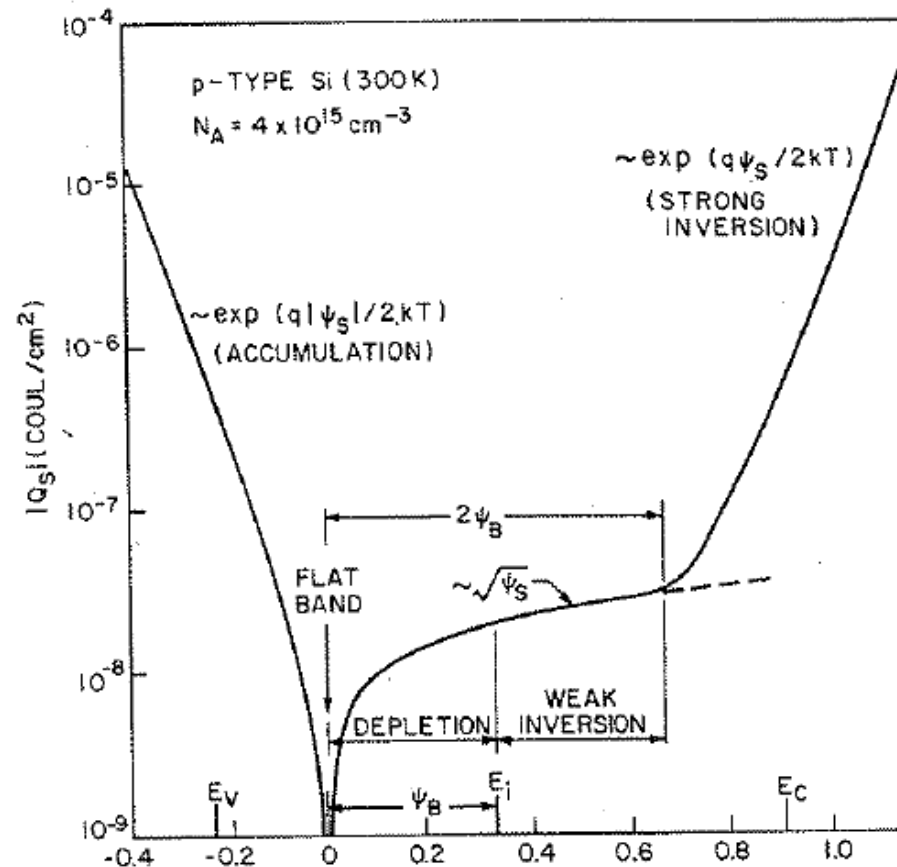
We know already the exact relation between surface potential and electric field at the semiconductor surface valid for any band bending.

$$E_s^2 = \left( \frac{2kTN_A}{\epsilon_s} \right) \left[ (\exp(-\beta\psi) + \beta\psi - 1) + \frac{n_i^2}{N_A} (\exp(-\beta V) \exp(\beta\psi) - \beta\psi - 1) \right]^{1/2}$$



# Subthreshold Characteristics

recall



$$E_s^2 =$$

$$= \left( \frac{2kTN_A}{\epsilon_s} \right) \left[ (\exp(-\beta\psi) + \beta\psi - 1) + \frac{n_i^2}{N_A} (\exp(-\beta V) \exp(\beta\psi) - \beta\psi - 1) \right]^{1/2}$$

# Subthreshold Characteristics

## Drift and Diffusion Components of the Current

Unlike the strong inversion region, in which the drift current dominates, **subthreshold conduction is dominated by the diffusion current**. Both components are included in the Pao-Sah double-integral formula. In general, current continuity applies to the total current, NOT to its components. In other words, the ratio between drift and diffusion may vary from one point of the channel to another.

At low drain bias it is possible to separate drift and diffusion components using  $\psi_s(V)$  relation. When  $qV/kT \ll 1$ , only the first terms of the expansion in  $V$  need to be kept.

$$I_{ds}(y) = -\mu_{eff} W \frac{dV(y)}{dy} Q_n(V) \approx -\mu_{eff} W \frac{dV(y)}{dy} Q_n(0)$$

Since the total current is proportional to  $dV/dy$ , the **drift fraction of the current is given by the change of surface potential (band bending) with respect to the quasi-Fermi potential, i.e.  $d\psi_s/dV$** .

# Subthreshold Characteristics

## Drift and Diffusion Components of the Current

This can be evaluated from eq.:

$$V_g = V_{FB} + \psi_s + \frac{\sqrt{2\epsilon_s k T N_A}}{C_{ox}} \left[ \frac{q\psi_s}{kT} + \frac{n_i^2}{N_A} \exp[\beta(\psi_s - V_D)] \right]$$

In the limit for small V we obtain;

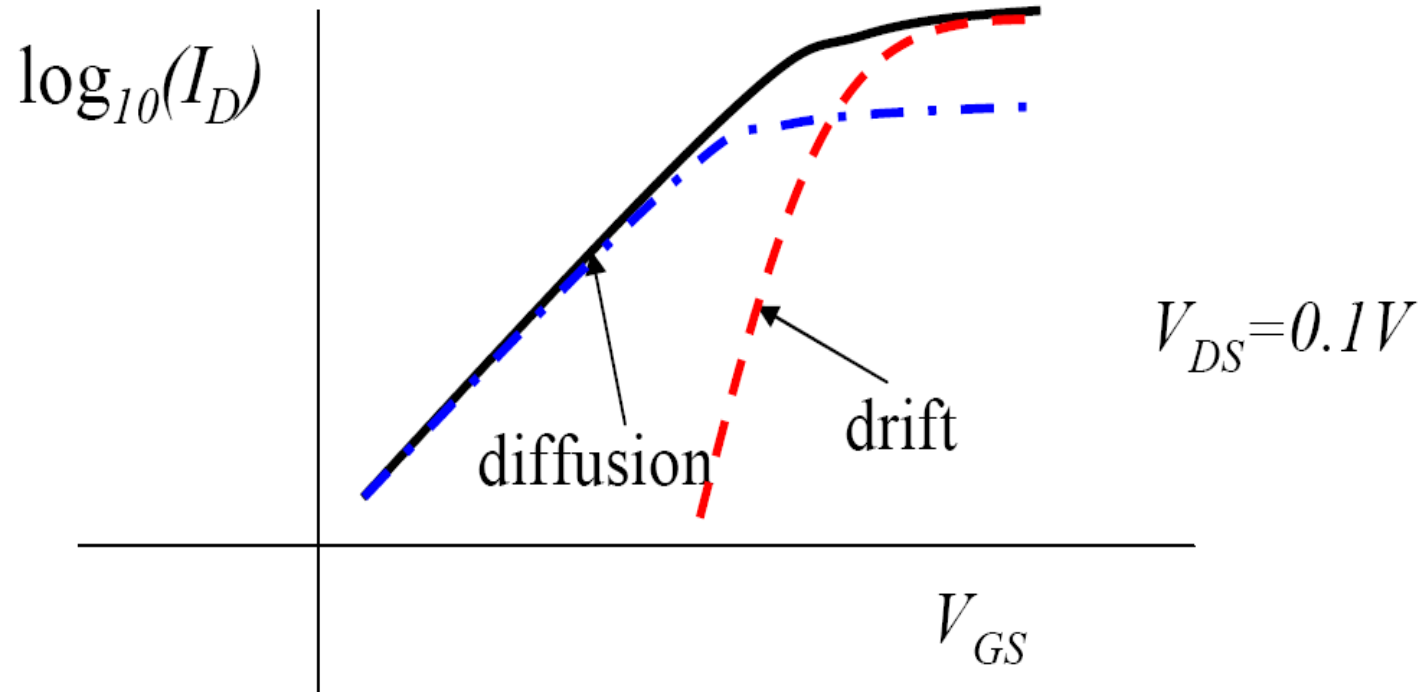
$$\frac{d\psi_s}{dV_D} = \frac{\frac{n_i^2}{N_A^2} \exp[\beta\psi_s]}{1 + \frac{n_i^2}{N_A} \exp[\beta(\psi_s - V_D)] + \frac{C_{ox}^2}{\epsilon_s q N_A} \frac{|Q_s|}{C_{ox}}}$$

In the weak inversion where ( $\psi_B < \psi_s < 2\psi_B$ ), the numerator is much smaller than 1 and the **diffusion current** dominates.

Conversely, beyond strong inversion,  $d\psi_s/dV \approx 1$  and the **drift current** dominates. This is shown in Figure on next page.

# Subthreshold Characteristics

## Drift and Diffusion Components of the Current



# Derivation of Subthreshold Current

$$E_s^2 =$$

$$= \left( \frac{2kTN_A}{\epsilon_s} \right) \left[ (\exp(-\beta\psi) + \beta\psi - 1) + \frac{n_i^2}{N_A} (\exp(-\beta V) \exp(\beta\psi) - \beta\psi - 1) \right]^{1/2}$$

From  $E_s$  we can calculate  $Q_s$  and we keep only the **two significant terms in the weak inversion region**

$$-Q_s = \epsilon_s E_s = \sqrt{2\epsilon_s kTN_A} \left[ \frac{q\psi_s}{kT} + \frac{n_i^2}{N_A^2} \exp[q(\psi_s - V)/kT] \right]^{1/2}$$

$$Q_d = -qNAWd = -\sqrt{2\epsilon_s qN_A \psi_s}$$

Of course the first term is the depletion charge density (we know this from our threshold voltage formula) and the second term gives the **(weak) inversion** charge density, after expanding into a power series and identifying the zeroth-order term as  $Q_d$ , one obtains:

$$-Q_n = \sqrt{2\epsilon_s qN_A / (2\psi_s)} \frac{kT}{q} \frac{n_i^2}{N_A^2} \exp[q(\psi_s - V)/kT]$$

# Derivation of Subthreshold Current

$$-Q_n = \sqrt{2\epsilon_s k T N_A / (2\psi_s)} \left[ \frac{kT}{q} \frac{n_i^2}{N_A^2} \exp[q(\psi_s - V) / kT] \right]$$

Substituting  $Q_n$  in  $I_{ds} = \mu_{eff} W \int_0^{V_{ds}} [-Q_n(V)] dV$

We obtain

$$I_{ds} = \mu_{eff} \frac{W}{L} \sqrt{2\epsilon_s k T N_A / (2\psi_s)} \left( \frac{kT}{q} \frac{n_i^2}{N_A^2} \right)^2 \exp(q\psi_s / kT) [1 - \exp(-qV_{ds} / kT)]$$

With  $V_g = V_{FB} + \psi_s + \frac{\sqrt{2\epsilon_s q N_A \psi_s}}{C_{ox}}$

The last equation can be solved for  $\psi_s$ . After few more transformations we can eliminate  $\psi_s$  from the drain current formula and replace it by an expression with  $V_g$ .

# Derivation of Subthreshold Current

We obtain the final formula for the subthreshold current:

$$I_{ds} = \mu_{eff} C_{ox} \frac{W}{L} (m - 1) \left( \frac{kT}{q} \right)^2 \exp(q(V_g - V_T) / kT) [1 - \exp(-qV_{ds} / kT)]$$

Note that the subthreshold current depends exponentially on both the gate and drain bias.

The subthreshold current is however independent of  $V_{ds}$  once  $V_{ds}$  is larger than a few  $kT/q$  as we would expect for diffusion-dominated current transport.

The dependence on the gate voltage is exponential and is called **subthreshold slope**.

# Subthreshold Slope and Swing

We define the subthreshold **slope** as

$$\ln 10 = 2.3$$

$$S = \left( \frac{d(\log_{10} I_{ds})}{dV_g} \right)^{-1} = \frac{mkT}{q} \ln 10 = 2.3 \frac{kT}{q} \left( 1 + \frac{C_d}{C_{ox}} \right)$$

Which is typically for bulk transistors 70-100 mV/decade. Here  $m=1+C_d/C_{ox}$ .

Subthreshold slope gives the gate voltage decrease to reduce the current by one decade.

Note that subthreshold slope decreases with smaller depletion capacitance (lighter p-substrate doping  $\rightarrow$  larger depletion width). This runs counter to the scaling trends of the MOSFETs. (Solution: Fully depleted SOI transistors)

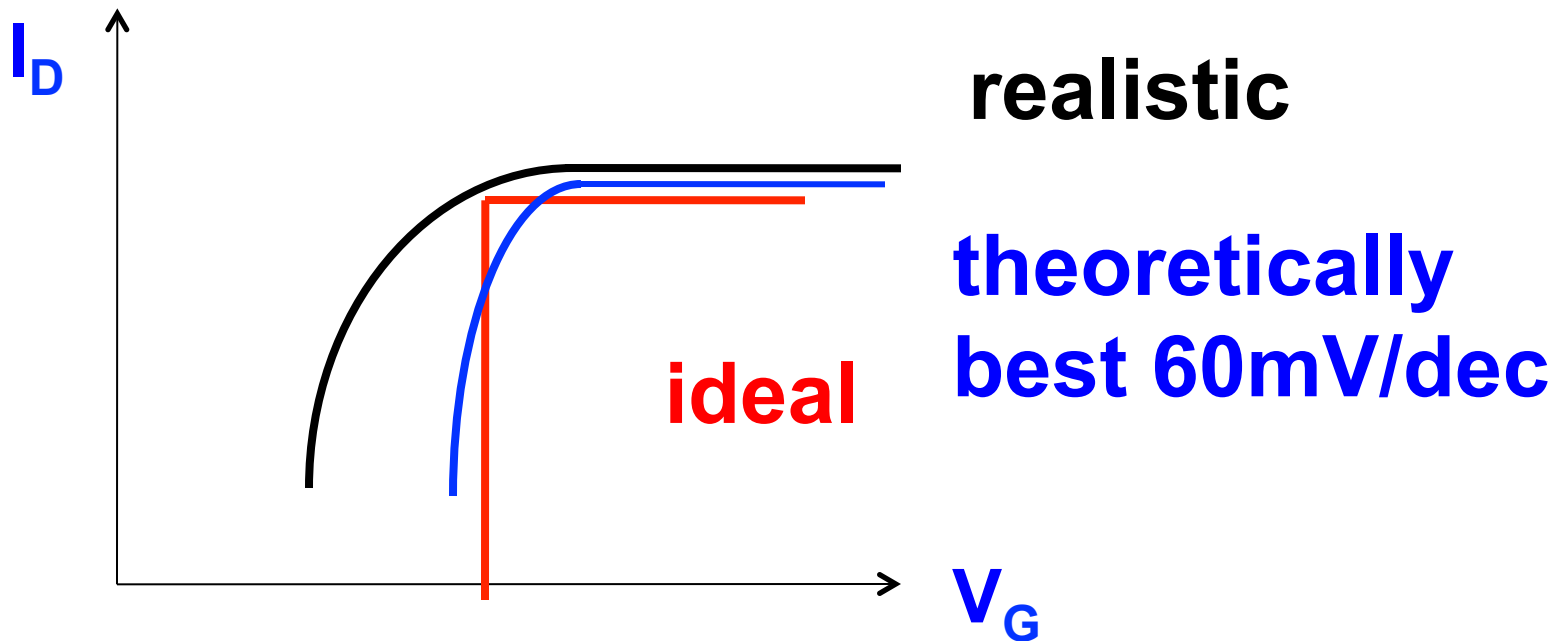
Note that the term in parenthesis is the inverse capacitive divider ratio  $(C_{ox}+C_d)/C_{ox}$ .



# Theoretical Limit of Subthreshold Slope

$$S = 2.3 \frac{kT}{q} \left( 1 + \frac{C_d}{C_{ox}} \right) \rightarrow 2.3 \frac{kT}{q}$$

$$\begin{matrix} 300K \\ \rightarrow \end{matrix} \quad 2.3 \times 0.0259 = 60mV / dec$$



# Theoretical Limit of Subthreshold Slope

$$S = 2.3 \frac{kT}{q} \left( 1 + \frac{C_d}{C_{ox}} \right) \rightarrow 2.3 \frac{kT}{q}$$

$$\xrightarrow{300K} 2.3 \times 0.0259 = 60 mV / dec$$

$(1+C_d/C_{ox})$  depends on the oxide thickness  $d$  ( $C_{ox}$ ) and on the maximum depletion width  $W_d$  ( $C_d$ ). The maximum depletion width depends in turn on the substrate doping (assuming uniform substrate doping  $N_A$ ) and substrate doping can be characterized by the Debey length  $L_D(N_A)$ . Therefore the factor is often characterized in terms of parameter  $a$  defined as:

$$a = \sqrt{2}(\epsilon_s / L_D) / C_{ox} = \sqrt{2}(\epsilon_s / \epsilon_{ox})(d_{ox} / L_D)$$

# Subthreshold Slope and Oxide damage

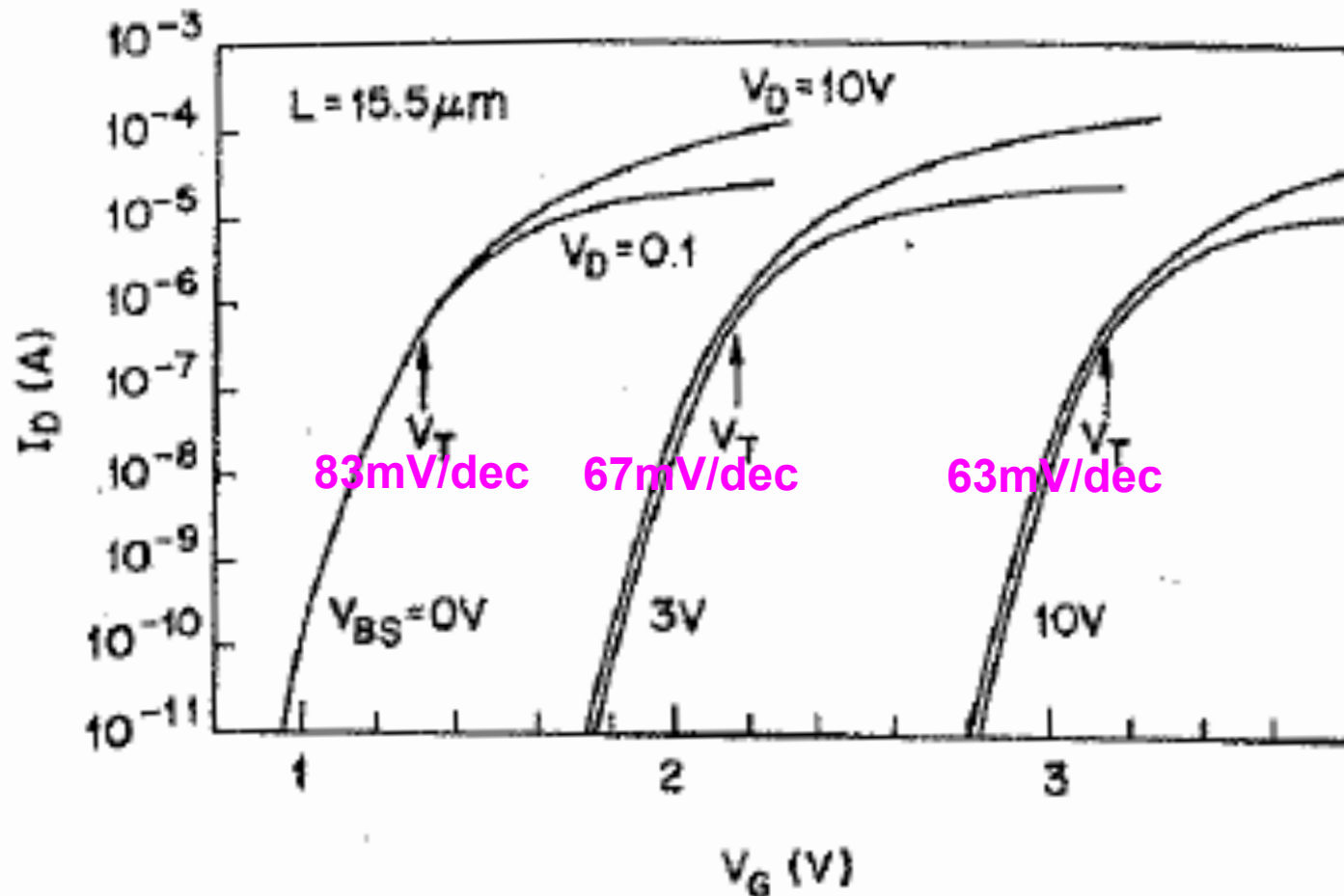
If there is a significant interface-trap density, the capacity  $C_{it}$  associated with the interface traps is in parallel with the depletion layer capacitance  $C_d$ . So we have to substitute  $(C_d + C_{it})$  for  $C_d$  and obtain

$$S = 2.3 \frac{kT}{q} \left( 1 + \frac{C_d}{C_{ox}} \right) \times \frac{1 + (C_d + C_{it}) / C_{ox}}{1 + C_d / C_{ox}}$$

The extra factor is larger than one and **degrades** the subthreshold slope.

# Subthreshold Slope and Substrate Bias

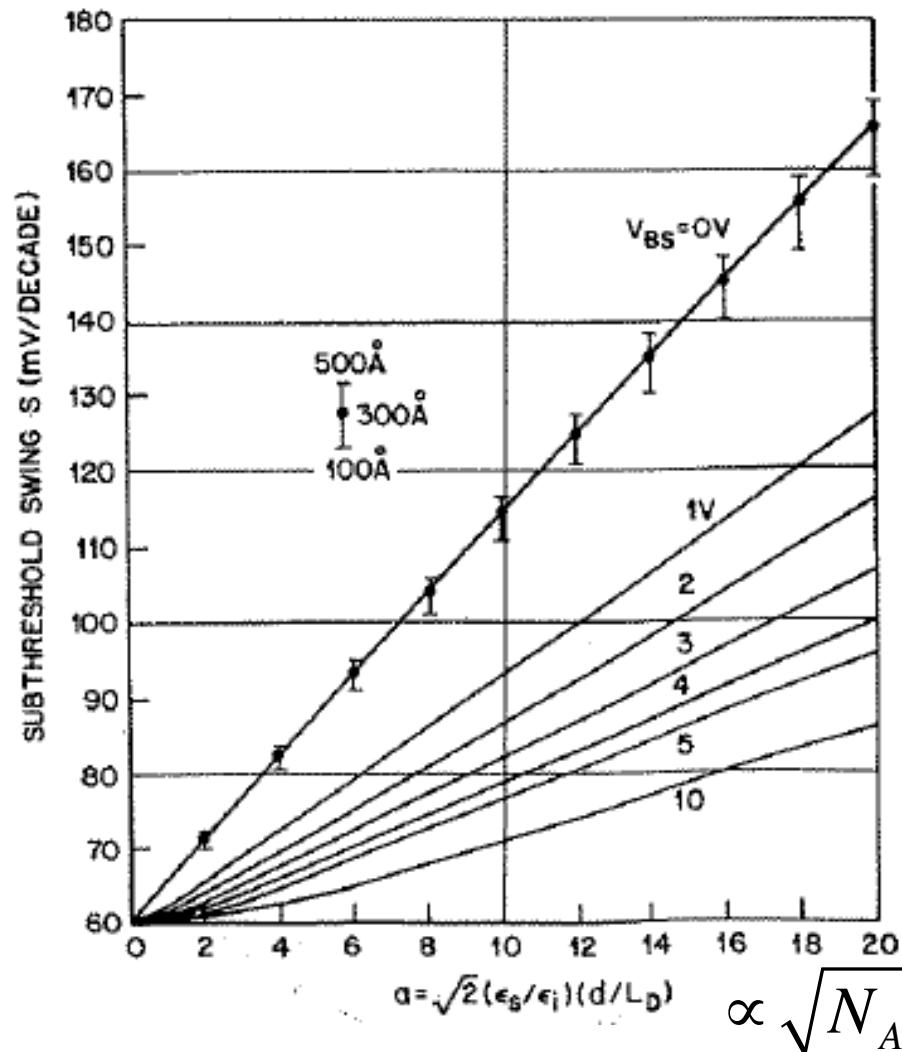
Subthreshold slope can be improved by applying substrate bias because the substrate bias increases the depletion width and reduces thus  $C_d$ .



Subthreshold swing versus substrate doping and versus substrate reverse bias.

# Subthreshold Slope and Substrate Bias

Subthreshold swing versus substrate doping and versus substrate reverse bias.



$$a = \sqrt{2}(\epsilon_s / L_D) / C_{ox}$$

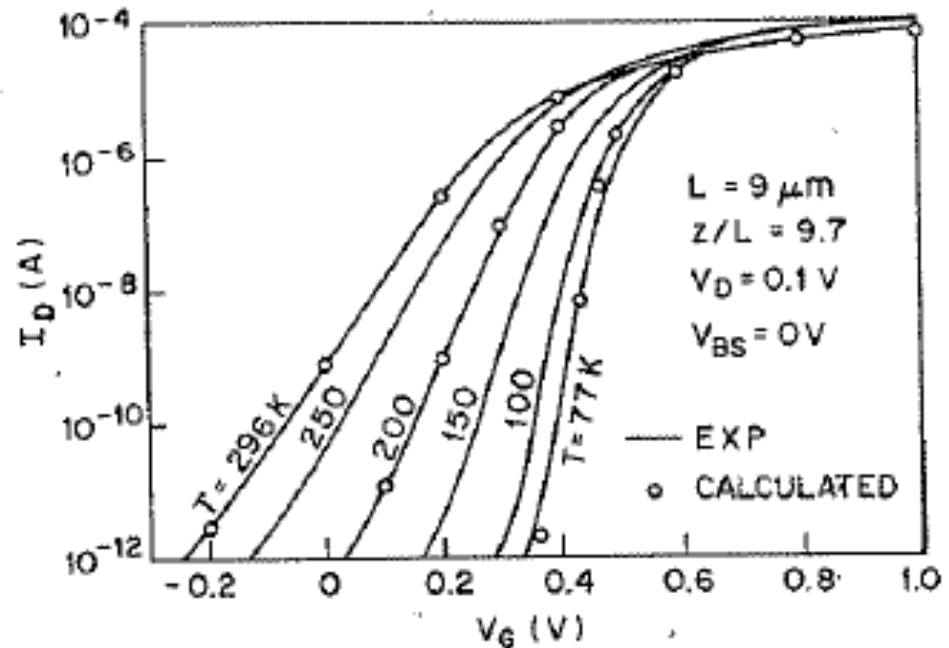
Essentially ratio between flat band capacitance and gate oxide capacitance

# Subthreshold Slope and Temperature

$$S = \ln 10 \times \frac{kT}{q} \left( 1 + \frac{C_d}{C_{ox}} \right)$$

$$S_{\min} = \ln 10 \times \frac{kT}{q} = 60 \text{ mV} / \text{dec}$$

@  $T = 300\text{K}$



As  $T$  decreases, the switching properties of a MOSFET improve. As  $T$  decreases from 296K to 77K, the  $V_T$  increases from 0.25V to about 0.5V. The most important improvement is the reduction of subthreshold swing from 80mV/dec at 296K to 22mV/decade (a dream for CMOS circuit designers for room temperature applications) at 77K – thus an improvement of almost factor of 4. Of course this improvement is coming mainly from the  $kT/q$  term. Other improvements of low temperature operation include higher mobility, lower leakage current and lower metal resistance.

However MOSFET would have to be immersed in liquid nitrogen (not a very practical proposition).

# Alternative (Intuitive) Derivation of Subthreshold Current

We already know that in a weak inversion the current is dominated by diffusion and can be derived in the same way as in pn junction or in the bipolar transistor. Considering the MOSFET as an n-p-n back-to-back junctions, we have

$$I_d = -qAD_n \frac{dn}{dy} = qAD_n \frac{n(0) - n(L)}{L}$$

But

$$n(0) = n_{p0} \exp(\beta\psi_s)$$

$$n(L) = n_{p0} \exp[\beta(\psi_s - V_D)]$$

We have to determine A. A is product of the width W of the device times the thickness of the channel  $x_i$ . Because of the exponential dependence of electron density on the potential  $\psi_s$ , the effective channel thickness corresponds to the distance in which  $\psi_s$  decreases by  $kT/q$ . Therefore, the effective channel thickness is  $kT/qE_s$  where  $E_s$  is the weak-inversion surface field

$$x_i = \frac{kT}{q} \cdot \frac{1}{E_s}$$

$$E_s = -Q_B / \epsilon_s = \sqrt{2qN_A\psi_s / \epsilon_s}$$

## Alternative (Intuitive) Derivation of Subthreshold Current

$$\begin{aligned} n(0) &= n_{p0} \exp(\beta\psi_s) & E_s &= -Q_B / \epsilon_s = \sqrt{2qN_A\psi_s / \epsilon_s} \\ n(L) &= n_{p0} \exp[\beta(\psi_s - V_D)] & x_i &= kT / \epsilon_s E_s \end{aligned}$$

Here we make the assumption from the beginning that subthreshold current is due to diffusion.

$$I_d = -qAD_n \frac{dn}{dy} = qAD_n \frac{n(0) - n(L)}{L}$$

Substituting the two first equation in the third one, we obtain:

$$\begin{aligned} I_d &= \mu_n \left( \frac{W}{L} \right) \frac{aC_{ox}}{2\beta^2} \left( \frac{n_i}{N_A} \right)^2 (1 - \exp(-\beta V_d) \exp(-\beta\psi_s) (\beta\psi_s)^{1/2} \\ \psi_s &= (V_g - V_{FB}) - \frac{a^2}{2\beta} \left\{ \left[ 1 + \frac{4}{a^2} (\beta V_g - \beta V_{FB} - 1) \right]^{1/2} - 1 \right\} \\ a &= \sqrt{2} (\epsilon_s / L_D) / C_{ox} \end{aligned}$$

From this the subthreshold swing can be found in the same way as previously.



## More complete model – sub-threshold to saturation

- Must include diffusion and drift currents
- Still use gradual channel approximation
- Yields sub-threshold and saturation behavior for long channel MOSFETS
- Exact Charge Model – numerical integration (Pao-Sah Model)

$$I_D = \frac{Z}{L} \frac{\epsilon_s \mu_n}{L_D} \int_0^{V_D} \int_{\psi_B}^{\psi_s} \frac{e^{\beta\psi - \beta V}}{F\left(\beta\psi, V, \frac{n_{p0}}{p_{p0}}\right)} d\psi dV$$