

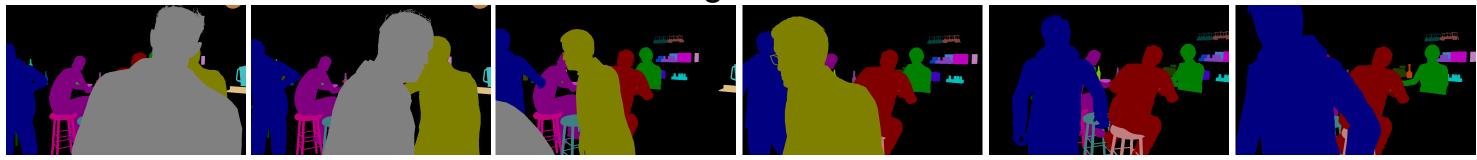
SAIL-VOS: Semantic Amodal Instance Level Video Object Segmentation - A Synthetic Dataset and Baselines Yuan-Ting Hu¹ Hong-Shuo Chen¹ Kexin Hui¹ Jia-Bin Huang² Alexander G. Schwing¹ ¹ University of Illinois Urbana-Champaign ² Virginia Tech

1. Introduction

Goal: Amodal Instance Level <u>Video</u> Segmentation – predicting and forecasting the object extend beyond the visible Amodal segmentation



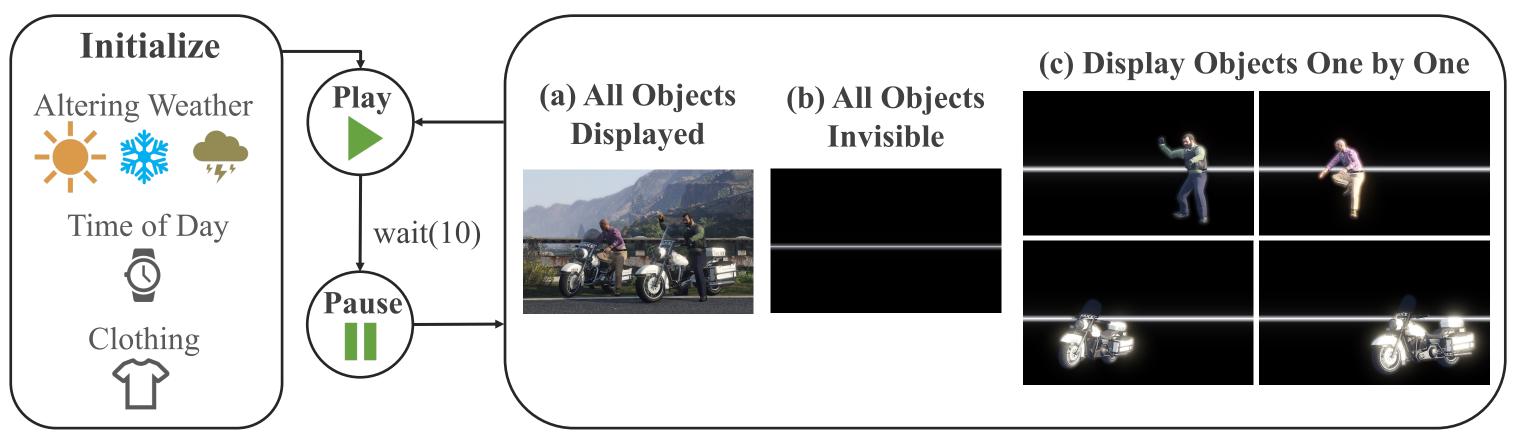
Modal segmentation



Issue: Only image datasets for amodal segmentation available **Contribution**: First *video* dataset & methods that use temporal context

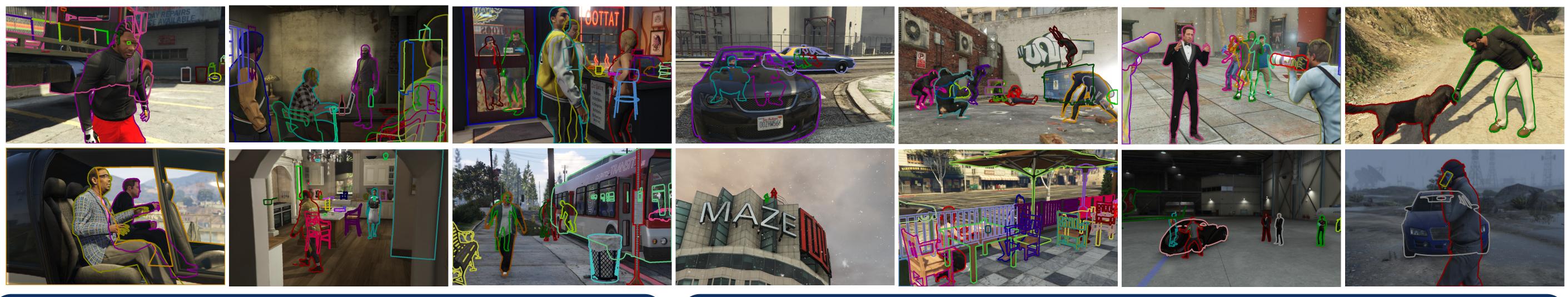
2. Dataset Collection Methodology

Grand Theft Auto V (GTA-V) is used to automate dataset collection



- We record the RGB image and the corresponding depth and stencil buffer
- **Modal and amodal masks:** computed using depth and stencil buffer
- **Object tracking:** achieved by accessing the rendering resources via the ScriptHookV library
- **Semantic class label:** obtained by grouping the name associated with the 3D model file of each object
- Other data: depth ordering, human 2d and 3d pose

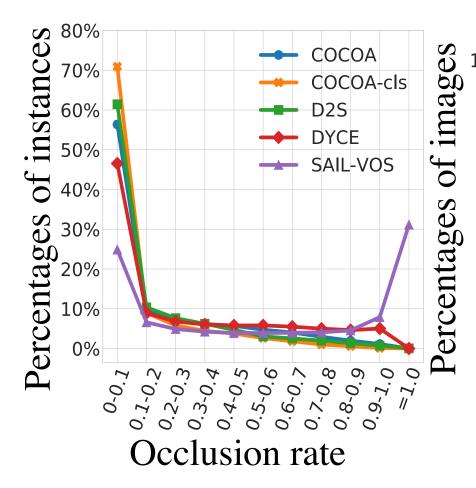


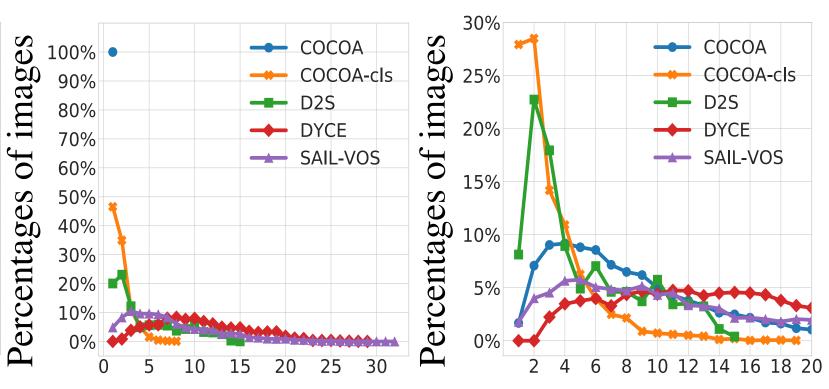


4. Statistics

Comparisons with other datasets:

Dataset	COCOA	COCOA-cls	D2S	DYCE	Ours		
Image/Video	Image	Image	Image	Image	Video		
Resolution	275K pix	275K pix	3M pix	1M pix	1M pix		
	-	-	1440×1920	1000×1000	800×1280		
Synthetic/Real	Real	Real	Real	Synthetic	Synthetic		
# of images	5,073	3499	5,600	5,500	111,654		
# of classes	-	80	60	79	162		
# of instances	46,314	10,562	28,720	85,975	1,896,295		
# of occluded instances	28,106	5,175	16,337	70,766	1,653,980		
Avg. occlusion rate	18.8%	10.7%	15.0%	27.7%	56.3%		





Number of categories

3. SAIL-VOS Dataset

• Contains diverse scenes (outdoor/indoor), different weather (sunny/rainy/storm), different lighting conditions (day/night) • Provides annotations for modal segmentation, amodal segmentation, depth ordering and 2d/3d human pose

Number of instances

Evaluation on the SAIL-VOS dataset in the **class agnostic** setting:

	Modal mask						Amodal mask							
	AP ₅₀	AP	AP_{50}^P	AP_{50}^H	AP_{50}^L	AP_{50}^M	AP_{50}^S	AP ₅₀	AP	AP_{50}^P	AP_{50}^H	AP_{50}^L	AP_{50}^M	AP_{50}^S
MaskRCNN	40.6	28.0	51.2	13.5	74.6	20.2	5.6	-	-	-	-	-	-	-
MaskAmodal	-	-	-	-	-	-	-	40.4	26.6	51.2	14.8	72.9	20.6	6.8
MaskJoint	38.8	26.0	49.5	11.9	70.4	17.4	6.4	40.8	26.4	51.2	15.8	73.1	19.6	7.5
ORCNN	37.3	24.3	49.0	9.8	68.2	16.5	6.3	40.1	25.5	51.2	14.2	71.9	19.5	7.6

Qualitative Results: Groundtruth MaskAmodal

MaskJoint

ORCNN







5. Baselines and Results



Video Object Segmentation: DAVIS results with and without

pretraining on SAIL-VOS: IoU on the DAVIS validation set. **DAVIS** fraction 30% VideoMatch-pretrain 0.74 0.77 0.78 0.78 0.78 0.79 0.55 0.66 0.73 0.74 0.78 0.81 VideoMatch

More details and results on: http://sailvos.web. illinois.edu

