

* Laplace Domain Techniques.

Summary:

- The Laplace transform maps time domain signals to a signal that is a function of $s \in \mathbb{C}$.

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

- Given a system description $Q(D)y(t) = P(D)x(t)$ or an impulse response $h(t)$, the system can be described by the Transfer Function

$$H(s) = \mathcal{L}\{h(t)\} \quad \text{or} \quad H(s) = \frac{P(s)}{Q(s)}$$

- The zero-state response is the product of $H(s)$ and $X(s)$

$$Y(s) = H(s)X(s)$$

- The system is BIBO stable if poles of TF are in the left hand of complex plane.
- The system is internally stable if roots of $Q(s)$ are in left hand of complex plane.
- The response to a stable system is

$$\begin{aligned} Y(s) &= Y_0(s) + Y_{zs}(s) \\ &= Y_0(s) + Y_{\text{transient}}(s) + Y_{ss}(s) \end{aligned}$$

- Systems can be realized from $H(s)$ using multipliers, summers, and integrators.
- If the system is stable $H(s)$ can be converted to the frequency response

$$H(s) \Big|_{s=j\omega} = H(j\omega)$$

- This can be plotted as a Bode Plot.
- This can be used to find the sinusoidal response or sinusoidal steady-state response.

Example #1

Given $y'' + 8y' + 15y = \cos(2\pi t)u(t)$
 with $y(0^-) = 0$, $y'(0^-) = 1$ find total
 response $y(t)$ using Laplace.

- Take Laplace transform of Diff Eq.

$$\left[s^2 Y(s) - s y(0^-) - y'(0^-) \right] + 8 \left[s Y(s) - y(0^-) \right] + 15 Y(s) = \frac{s}{s^2 + 4\pi^2}$$

- Solve for $Y(s)$:

$$(s^2 + 8s + 15) Y(s) = \frac{s}{s^2 + 4\pi^2} + 1$$

$$Y(s) = \frac{s}{(s^2 + 8s + 15)(s^2 + 4\pi^2)} + \frac{1}{s^2 + 8s + 15}$$

- Take Inverse Laplace. $(s^2 + 8s + 15) = (s + 5)(s + 3)$

$$Y(s) = \frac{A}{s + 5} + \frac{B}{s + 3} + \frac{Cs + D}{s^2 + 4\pi^2} + \frac{E}{s + 5} + \frac{F}{s + 3}$$

$$A = \frac{s}{(s + 3)(s^2 + 4\pi^2)} \Big|_{s = -5} = \frac{-5}{(-2)(25 + 4\pi^2)} = \frac{5}{2(25 + 4\pi^2)}$$

$$B = \frac{s}{(s + 5)(s^2 + 4\pi^2)} \Big|_{s = -3} = \frac{-3}{(2)(9 + 4\pi^2)}$$

to find C & D: $A(s + 3)(s^2 + 4\pi^2) + B(s + 5)(s^2 + 4\pi^2) + (Cs + D)(s^2 + 8s + 15) = s$

$$A(s^3 + 4\pi^2 s + 3s^2 + 12\pi^2) +$$

$$B(s^3 + 4\pi^2 s + 5s^2 + 20\pi^2) +$$

$$Cs^3 + 8Cs^2 + 15Cs + Ds^2 + 8Ds + 15D = s$$

- Equate coefficients

$$A + B + C = 0$$

$$3A + 5B + 8C + D = 0$$

$$4\pi^2 A + 4\pi^2 B + 15C + 8D = 1$$

$$12\pi^2 A + 20\pi^2 B + 15D = 0$$

$$\text{or } C = -(A+B) = \frac{-5}{2(25+4\pi^2)} + \frac{3}{2(9+4\pi^2)}$$

$$D = \frac{-12\pi^2 A - 20\pi^2 B}{15} = \frac{-12\pi^2 \cdot 5}{2(25+4\pi^2)} + \frac{20\pi^2 \cdot 3}{2(9+4\pi^2)} \\ \frac{15}{15}$$

- Now to find E, F

$$E = \frac{1}{s+3} \Big|_{s=-5} = \frac{-1}{2}$$

$$F = \frac{1}{s+5} \Big|_{s=-3} = \frac{1}{2}$$

- Now

$$y(t) = A e^{-5t} u(t) + B e^{-3t} u(t) + C \cos(2\pi t) u(t) \\ + \frac{D}{2\pi} \sin(2\pi t) u(t) - \frac{1}{2} e^{-5t} u(t) + \frac{1}{2} e^{-3t} u(t)$$

- Example # 2

$$H(s) = \frac{1}{s^2 + 8s + 12}$$

a) Is the system stable, in what sense?

We can only determine BIBO stability.

$$(s^2 + 8s + 12) = (s+6)(s+2)$$

both poles in LHP, \therefore BIBO stable.

Example # 2 b) What is the response in the Laplace domain to

$$x(t) = e^{-t} u(t)$$

$$Y(s) = H(s) X(s)$$

$$X(s) = \frac{1}{s+1}$$

$$Y(s) = \frac{1}{(s+1)(s^2+8s+12)}$$

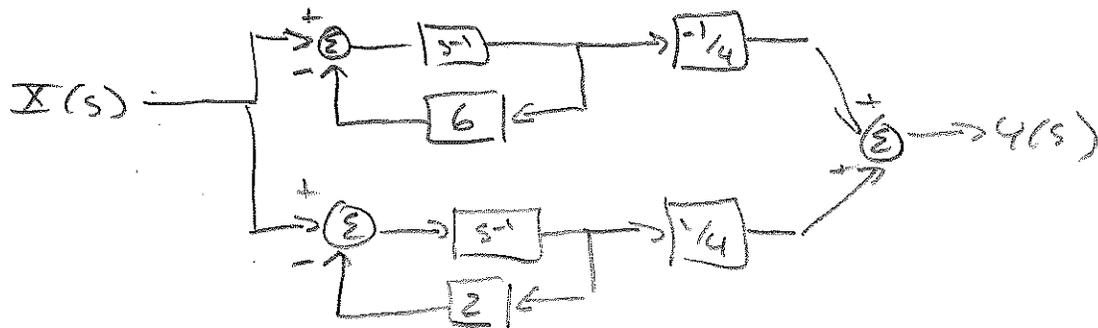
- Example # 3, Realize previous $H(s)$ in parallel form if possible.

$$H(s) = \frac{A}{s+6} + \frac{B}{s+2}$$

$$A = \frac{1}{s+2} \Big|_{s=-6} = -\frac{1}{4}$$

$$= \frac{-\frac{1}{4} s^{-1}}{1+6s^{-1}} + \frac{\frac{1}{4} s^{-1}}{1+2s^{-1}}$$

$$B = \frac{1}{s+6} \Big|_{s=-2} = \frac{1}{4}$$



- Example # 4 : $H(s) = \frac{1}{s(s+2)}$

$$1 + \frac{1}{s(s+2)} = \frac{1}{s(s+2) + 1}$$

$$= \frac{1}{s^2 + 2s + 1}$$

- Example #5: Suppose $H(s) = \frac{6}{s+3}$

What is the steady-state response due to,

$$x(t) = \cos(2t)u(t) + 2\sin(3t)u(t)$$

- The system is stable pole at -3

- The Frequency response $H(\omega) = \frac{6}{3+j\omega}$

$$|H(\omega)| = \frac{6}{(9+\omega^2)^{1/2}} \quad \angle H(\omega) = -\tan^{-1}\left(\frac{\omega}{3}\right)$$

$$\underline{y_{\text{SS}}}(t) = |H(2)| \cos(2t + \angle H(2)) + 2|H(3)| \sin(3t + \angle H(3))$$

$$|H(2)| = \frac{6}{(9+4)^{1/2}} \quad \angle H(2) = -\tan^{-1}\left(\frac{2}{3}\right)$$

$$|H(3)| = \frac{6}{(9+9)^{1/2}} \quad \angle H(3) = -\tan^{-1}\left(\frac{3}{3}\right)$$