

★ Bilateral Laplace

- Recall the definition of the Bilateral Laplace transform

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

- For causal signals $x(t) = 0$ for $t < 0$ and this becomes the one-sided Laplace transform

$$X(s) = \int_0^{\infty} x(t) e^{-st} dt \quad \text{for causal } x(t).$$

- We can split any signal $x(t)$ into its causal and anticausal components as.

$$x(t) = x(t) u(-t) + x(t) u(t) = x_a(t) + x_c(t)$$

and thus the Bilateral transform becomes

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_{-\infty}^{0^-} x_a(t) e^{-st} dt + \int_{0^+}^{\infty} x_c(t) e^{-st} dt$$

so that

$$X(s) = X_a(s) + X_c(s)$$

- The transform $X_c(s)$ we obtain the same way we have in the past, using the definition or one-sided table.

- To obtain $X_a(s)$ we note

$$X_a(s) = \int_{-\infty}^{0^-} x_a(t) e^{-st} dt = \int_{0^+}^{\infty} x_a(-t) e^{-s(-t)} dt$$

$$\text{and } X_a(-s) = \int_{0^+}^{\infty} x_a(-t) e^{+s(-t)} dt = \int_{0^+}^{\infty} x_a(-t) e^{-st} dt$$

one-sided Laplace
of $x_a(-t)$.

- Thus the Laplace transform of the anti-causal component is the one-sided Laplace of $x_a(-t)$ when s is replaced by $-s$.

- Summary of Bilateral Laplace

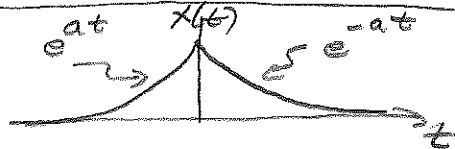
1. Split into causal and anticausal components, $x_a(t)$ and $x_c(t)$

2. Compute $X_c(s)$ using one-sided transform as before (with associated ROC)

3. Compute $X_a(s)$ using one-sided transform of $x_a(-t)$ replace s by $-s$ (including the ROC).

- Example:

$$x(t) = e^{-a|t|} \quad a > 0$$



First, let's use the definition:

$$X(s) = \int_{-\infty}^{0^-} e^{at} e^{-st} dt + \int_{0^+}^{\infty} e^{-at} e^{-st} dt$$

$$= \int_{-\infty}^{0^-} e^{-(s-a)t} dt + \int_{0^+}^{\infty} e^{-(s+a)t} dt$$

$$= \frac{-1}{s-a} e^{-(s-a)t} \Big|_{-\infty}^{0^-} + \frac{-1}{s+a} e^{-(s+a)t} \Big|_{0^+}^{\infty}$$

$$= \frac{-1}{s-a} \left[\underbrace{e^{-(s-a)0^-}}_1 - \underbrace{e^{-(s-a)(-\infty)}} \right] + \frac{-1}{s+a} \left[\underbrace{e^{-(s+a)\infty}}_0 - \underbrace{e^{-(s+a)0^+}}_1 \right]$$

$= 0$ if $\text{Re}\{s-a\} < 0$
or $\text{Re}\{s\} < a$

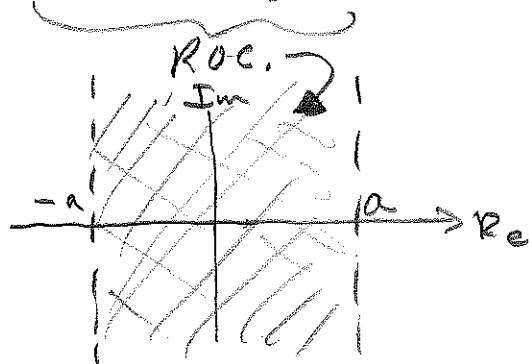
$$= \frac{-1}{s+a} \left[\underbrace{e^{-(s+a)\infty}}_0 - \underbrace{e^{-(s+a)0^+}}_1 \right]$$

$\hookrightarrow 0$ if $\text{Re}\{s+a\} > 0$ or $\text{Re}\{s\} > -a$

$$= \frac{-1}{s-a} + \frac{1}{s+a}$$

$$-a < \text{Re}\{s\} < a$$

$$= \frac{-2a}{(s-a)(s+a)}$$



- Now, lets repeat using the procedure.

$$X(t) = X_a(t) + X_c(t) = e^{at} u(-t) + e^{-at} u(t)$$

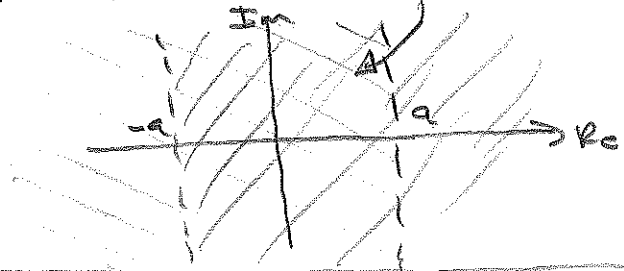
$$X_c(s) = \frac{1}{s+a} \quad \text{Re}\{s\} > -a \quad \text{From table.}$$

$$X_a(-s) = \int \{ X_a(-t) \} = \int \{ e^{-at} u(t) \} = \frac{1}{s+a} \quad \text{Re}\{s\} > -a$$

using table.

$$X_a(s) = \frac{1}{-s+a} = \frac{-1}{s-a} \quad \text{Re}\{s\} < a$$

and $X(s) = X_a(s) + X_c(s)$ ROC is intersection

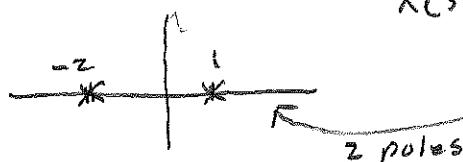


- So how does the inverse Laplace change

- In the case of one-sided transforms we largely ignored the ROC when doing the inverse.

Now, we have to use it since it determines the anti-causal v/s causal parts.

- Example 4.28



$$X(s) = \frac{-3}{(s+2)(s-1)}$$

2 poles

ROC

$$a) -2 < \text{Re}\{s\} < 1$$

$$b) \text{Re}\{s\} > 1$$

$$c) \text{Re}\{s\} < -2$$

• case a)

causal ROC: $\text{Re}\{s\} > -2$

anticausal ROC: $\text{Re}\{s\} < 1$

$$\frac{-3}{(s+2)(s-1)} = \frac{A}{s+2} + \frac{B}{s-1} = \frac{1}{s+2} + \frac{-1}{s-1}$$

$$= X_c(s) + X_a(s)$$

$$X_c(t) = \underline{e^{-2t} u(t)}, \quad X_a(-s) = \frac{1}{s+1}$$

$$X_a(-t) = e^{-t} u(t)$$

$$X_a(t) = \underline{e^t u(-t)}$$

• case b) $\text{Re}\{s\} > 1$ purely causal.

$$\bar{X}(s) = \frac{1}{s+2} + \frac{-1}{s-1}$$

$$x(t) = (e^{-2t} - e^t) u(t)$$

• case c) $\text{Re}\{s\} < -2$ purely anticausal.

$$\bar{X}(s) = \frac{1}{s+2} + \frac{-1}{s-1}$$

$$\bar{X}(-s) = \frac{-1}{s-2} + \frac{1}{s+1}$$

$$x(-t) = (-e^{2t} + e^{-t}) u(t)$$

$$x(t) = (-e^{-2t} + e^t) u(-t)$$

Summary: in each case we get a different inverse.

- Note that for causal systems, with TF $H(s)$

$$Y(s) = \underbrace{H(s) \bar{X}_a(s)}_{\text{causal + anti-causal component}} + \underbrace{H(s) \bar{X}_c(s)}_{\text{causal only.}}$$

Example: $h(t) = e^{-t} u(t) \xleftrightarrow{\mathcal{Z}} H(s) = \frac{1}{s+1} \quad \text{Re}\{s\} > -1$

$$X(t) = u(-t) - u(t)$$


$$\bar{X}_a(s) = -\frac{1}{s} \quad \text{Re}\{s\} < 0$$

$$\bar{X}_c(s) = \frac{-1}{s} \quad \text{Re}\{s\} > 0$$

$$Y(s) = H(s) \bar{X}_a(s) + H(s) \bar{X}_c(s)$$

