

Action Recognition



Computer Vision

Jia-Bin Huang, Virginia Tech

This section: advanced topics

- Convolutional neural networks in vision
- Action recognition
- Vision and Language
- 3D Scenes and Context

What is an action?



Action: a transition from one state to another

- Who is the actor?
- How is the state of the actor changing?
- What (if anything) is being acted on?
- How is that thing changing?
- What is the purpose of the action (if any)?

How do we represent actions?

Categories

Walking, hammering, dancing, skiing, sitting down, standing up, jumping

Poses



Nouns and Predicates

<man, swings, hammer>

<man, hits, nail, w/ hammer>

What is the purpose of action recognition?

To describe



What is the purpose of action recognition?

- To predict



What is the purpose of action recognition?

- To understand the intention and motivation

Why are they doing that?



to sell ice cream



to commute to work



to answer emergency call



to win race

How can we identify actions?

Motion



Pose



Held
Objects



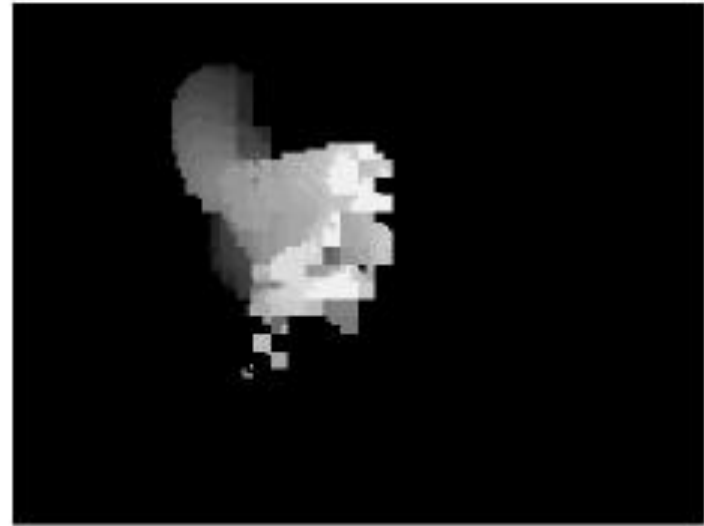
Nearby
Objects

Representing Motion

Optical Flow with Motion History



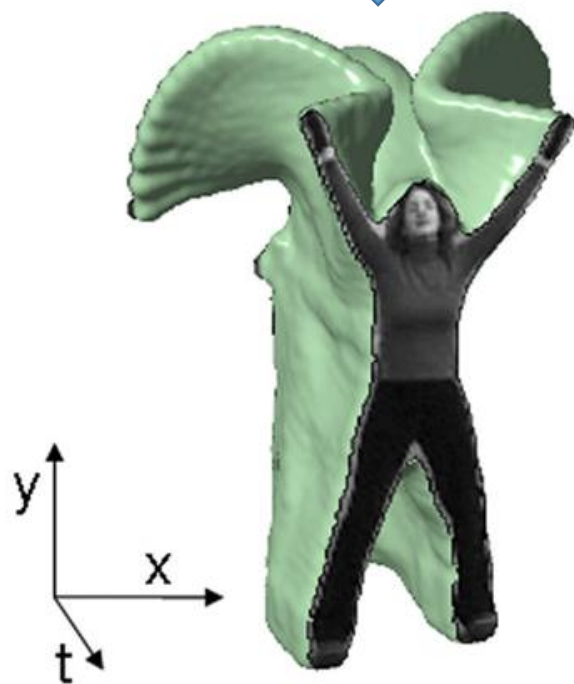
sit-down



sit-down MHI

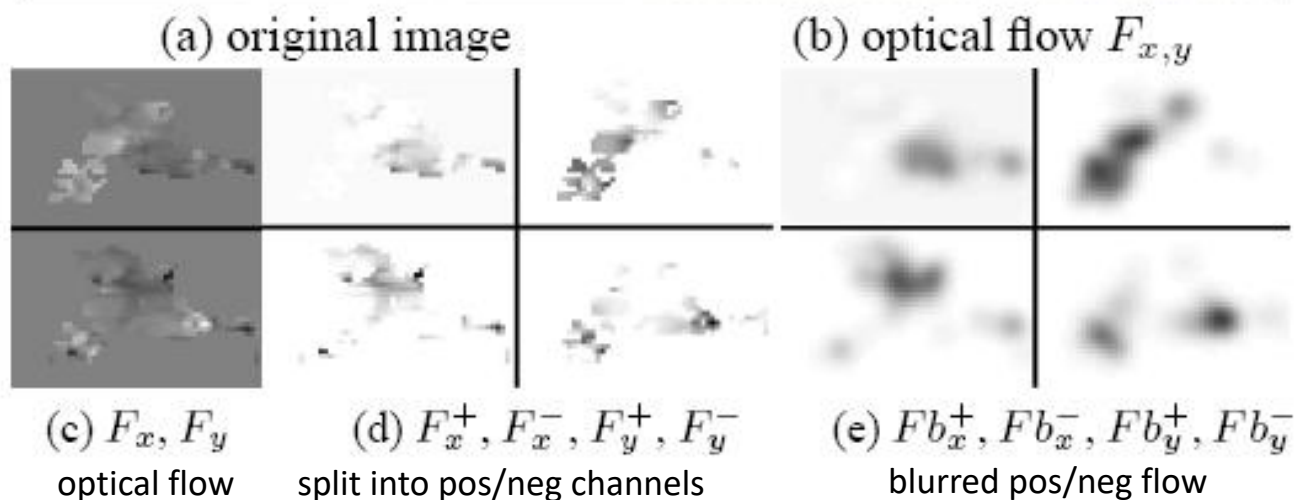
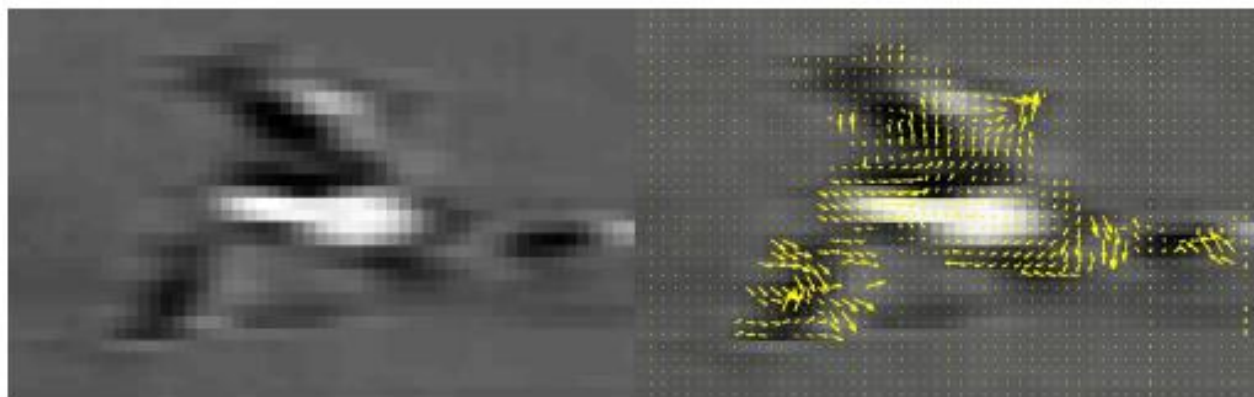
Representing Motion

Space-Time Volumes



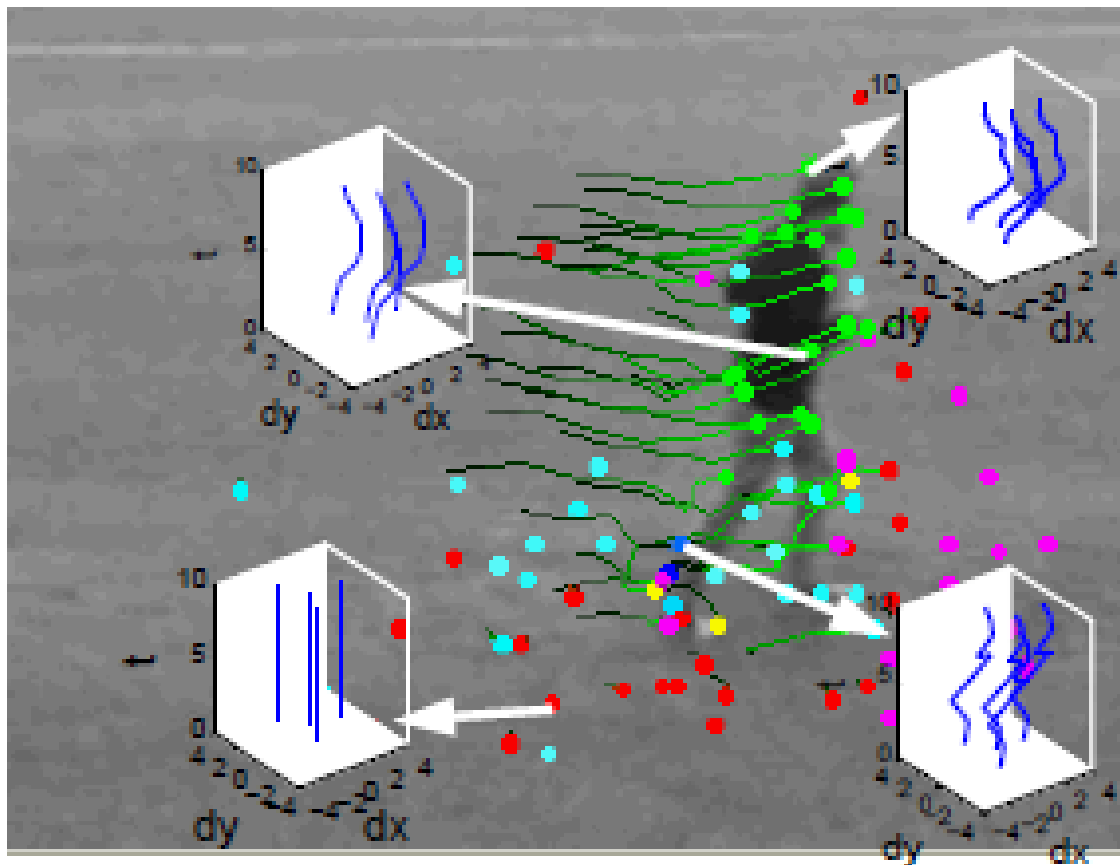
Representing Motion

Optical Flow with Split Channels



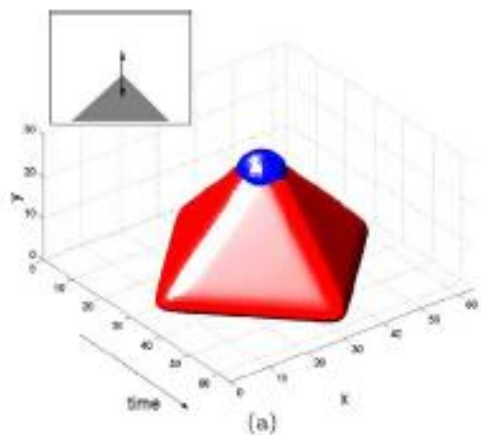
Representing Motion

Tracked Points

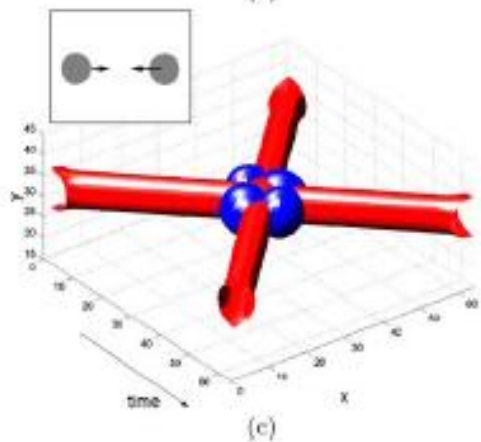
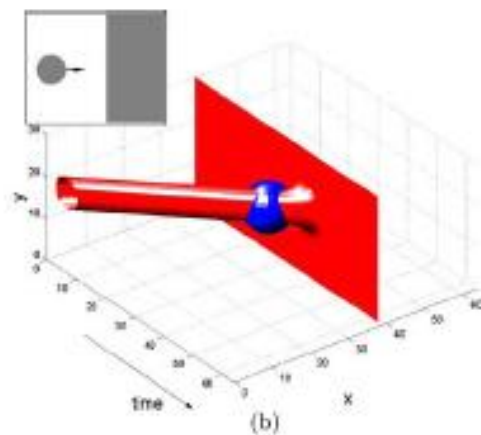


Representing Motion Space-Time Interest Points

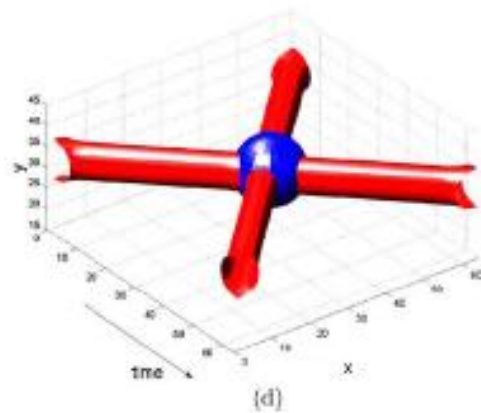
Moving corner



Ball hits wall



Balls collide



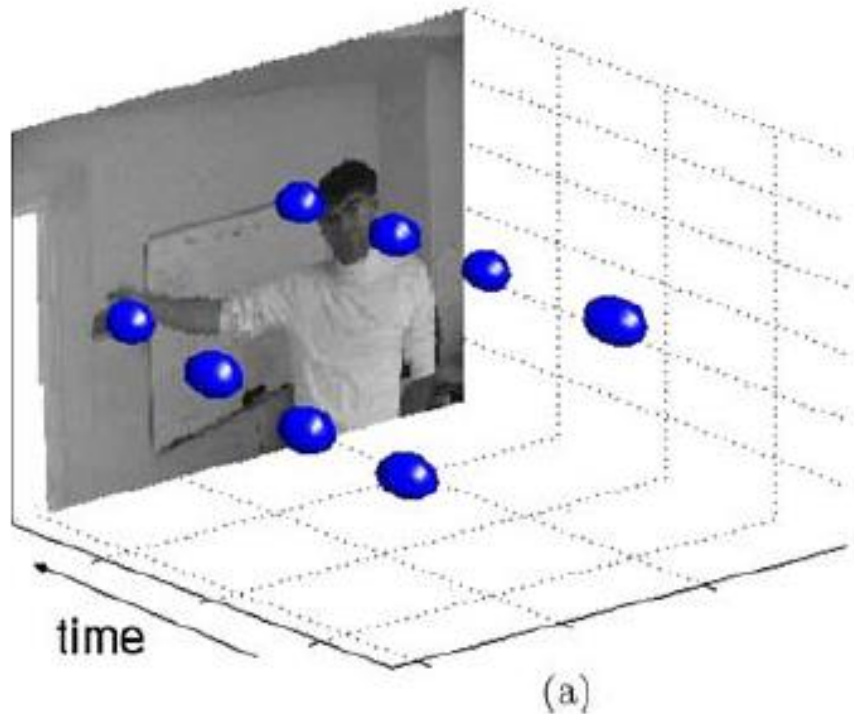
Balls collide (different scale)

Corner detectors in
space-time

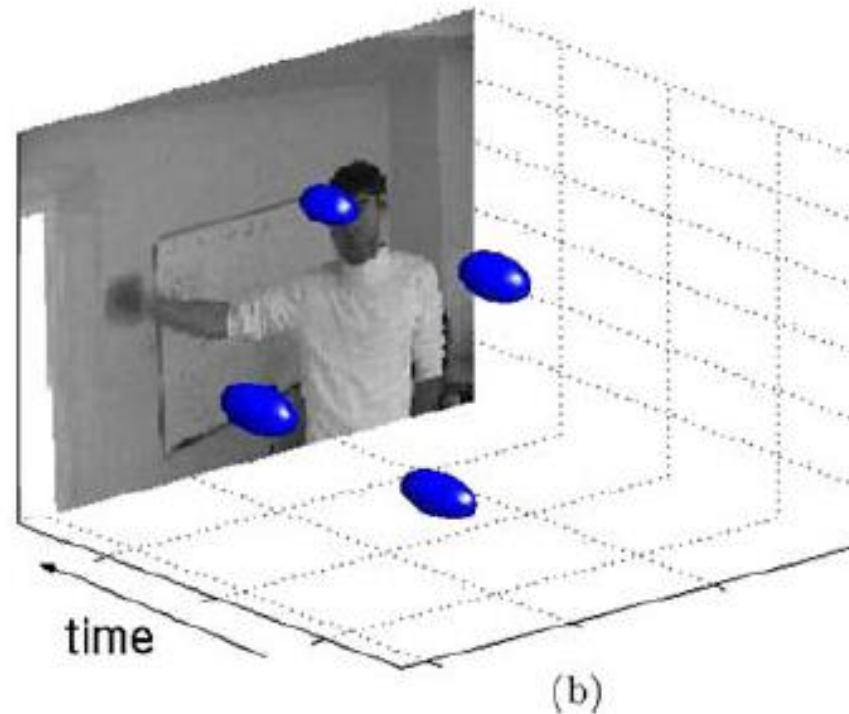
Representing Motion

Space-Time Interest Points

Hand waves with high frequency



Hand waves with low frequency



Examples of Action Recognition Systems

- Feature-based classification
- Recognition using pose and objects

Action recognition as classification

training samples



test samples



Remember image categorization...

Training

Training Labels

Training Images

Image Features

Classifier Training

Trained Classifier

Testing

Image Features

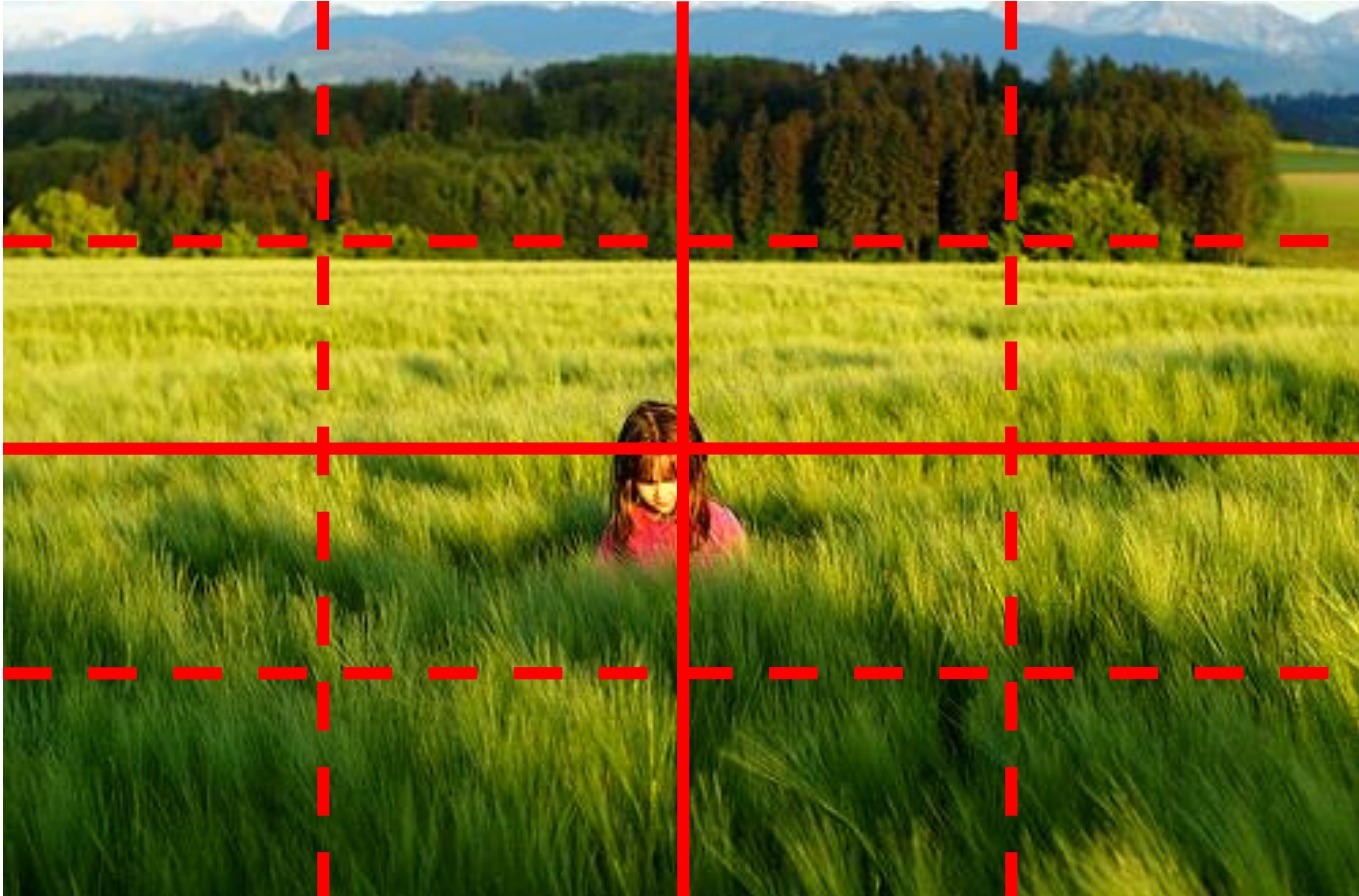
Trained Classifier

Prediction
Outdoor

Test Image



Remember spatial pyramids....

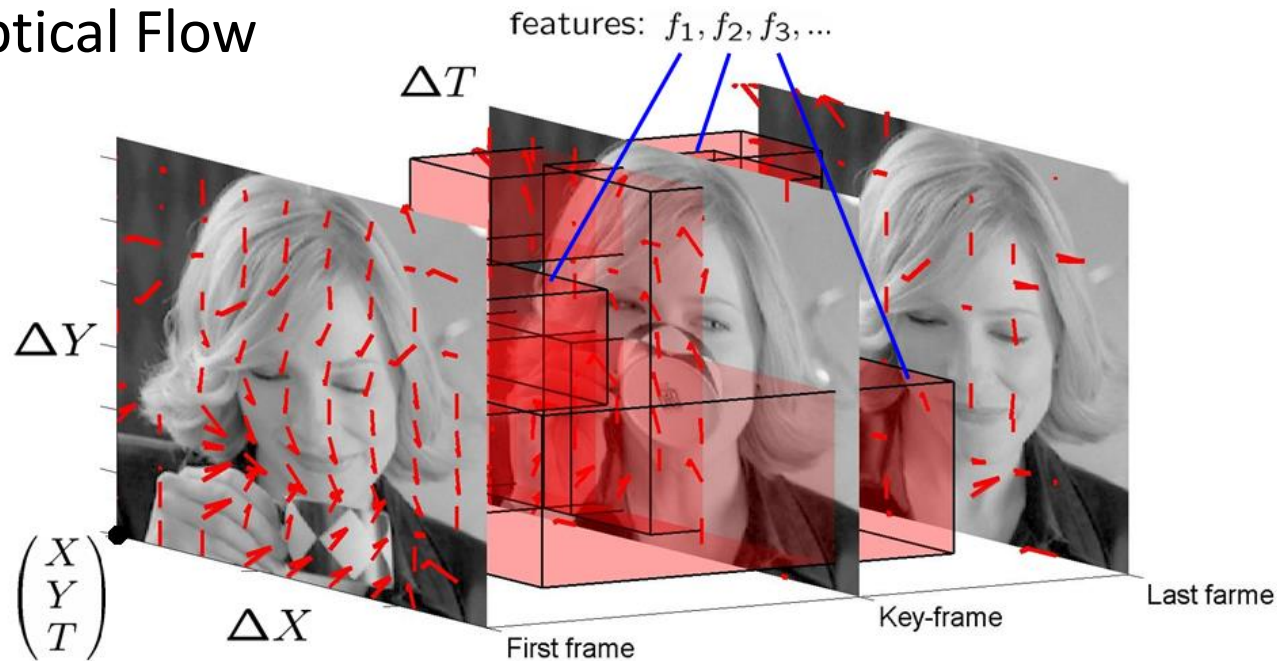


Compute histogram in each spatial bin

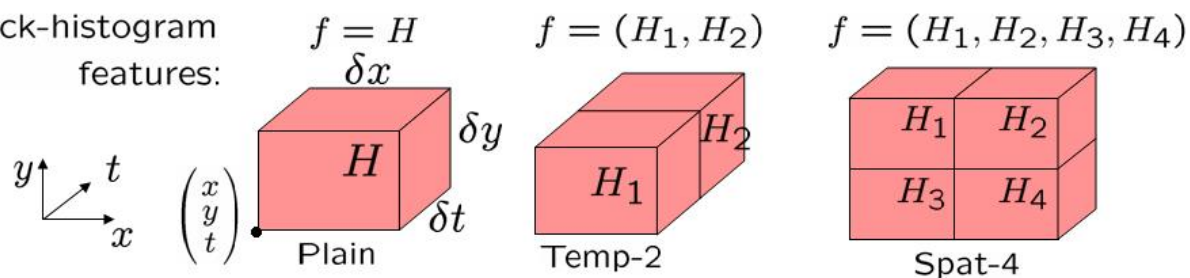
Features for Classifying Actions

1. Spatio-temporal pyramids

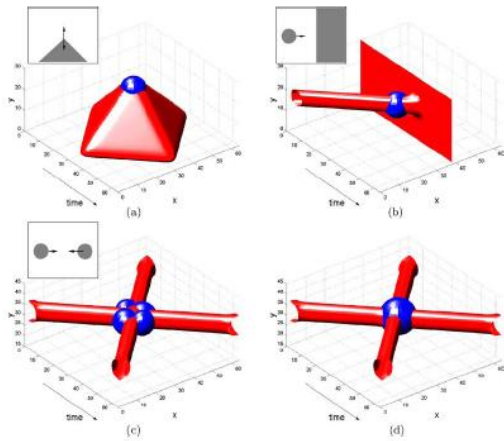
- Image Gradients
- Optical Flow



block-histogram
features:

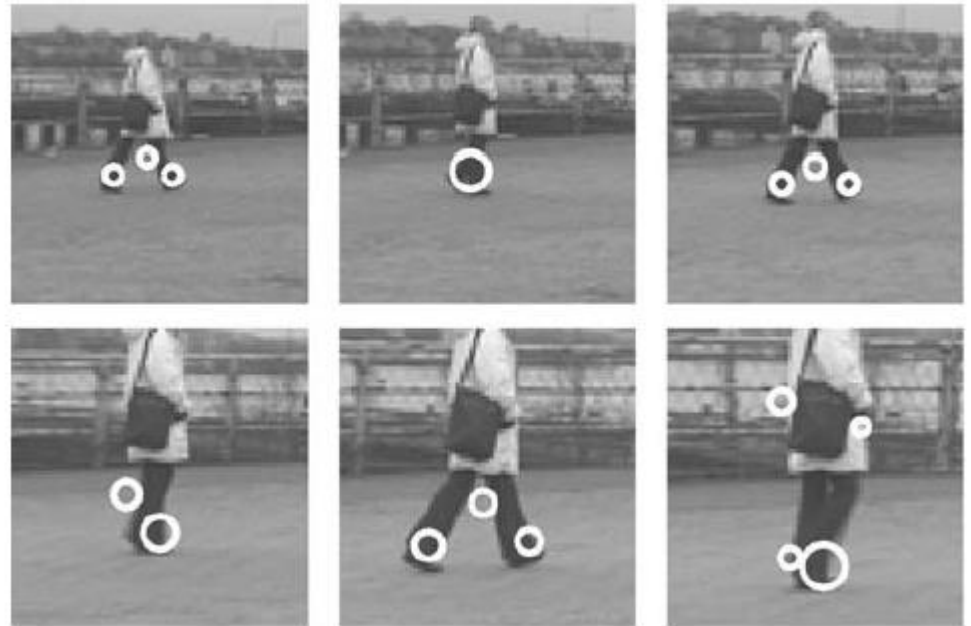


Features for Classifying Actions



Corner detectors in space-time

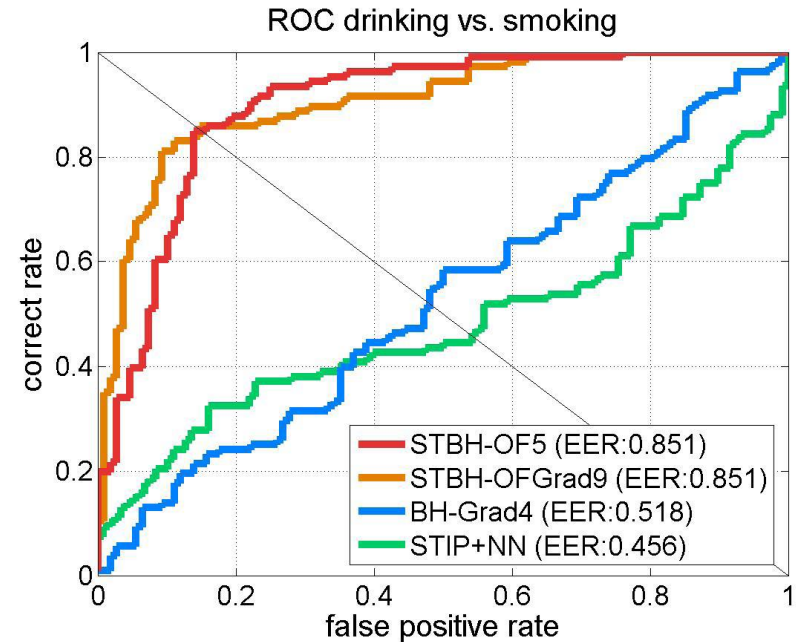
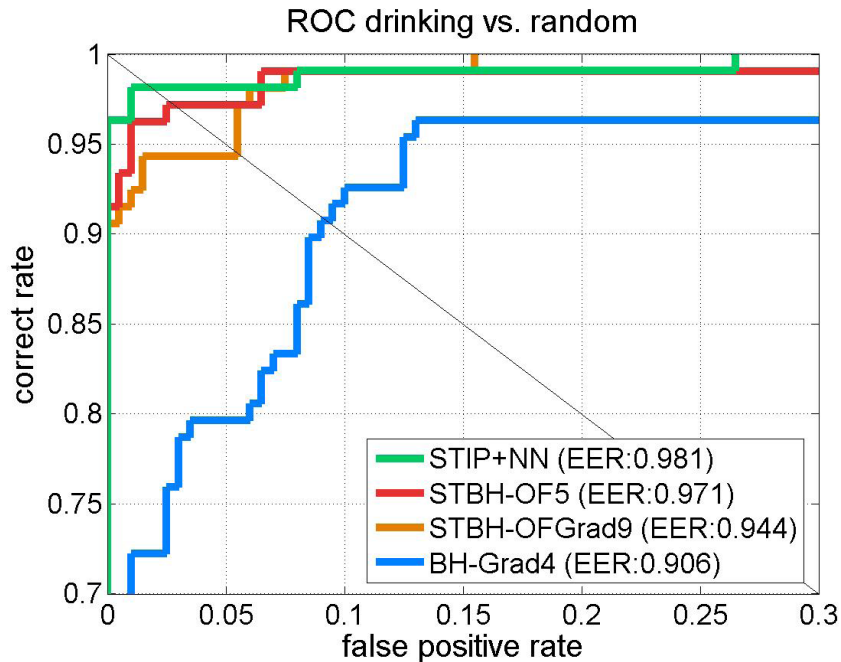
1 interest points



Descriptors based on Gaussian derivative filters over x , y , time

Classification

- Boosted stubs for pyramids of optical flow, gradient
- Nearest neighbor for STIP



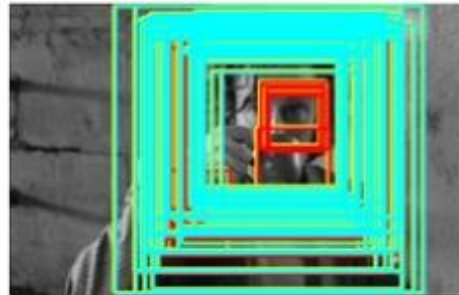
Searching the video for an action

1. Detect keyframes using a trained HOG detector in each frame
2. Classify detected keyframes as positive (e.g., “drinking”) or negative (“other”)

Test frame samples



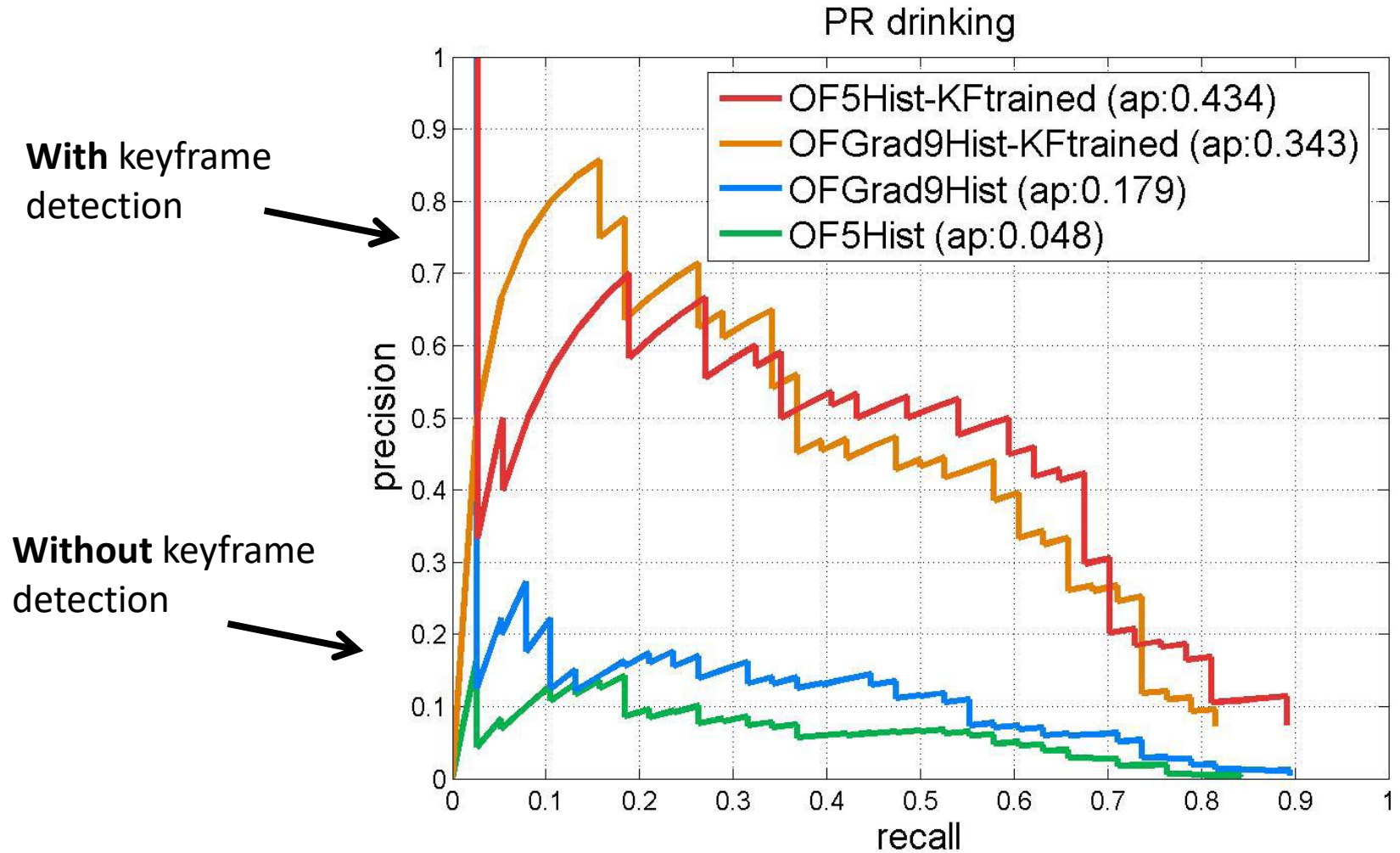
Keyframe priming



 Keyframe-primed event detection

 Keyframe detections

Accuracy in searching video





“Talk on phone”



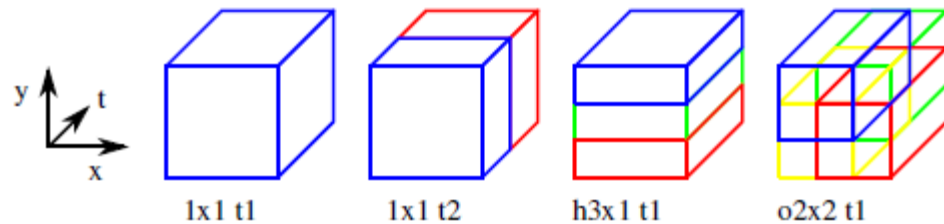
“Get out of car”

Approach

- Space-time interest point detectors
- Descriptors
 - HOG, HOF
- Pyramid histograms (3x3x2)
- SVMs with Chi-Squared Kernel

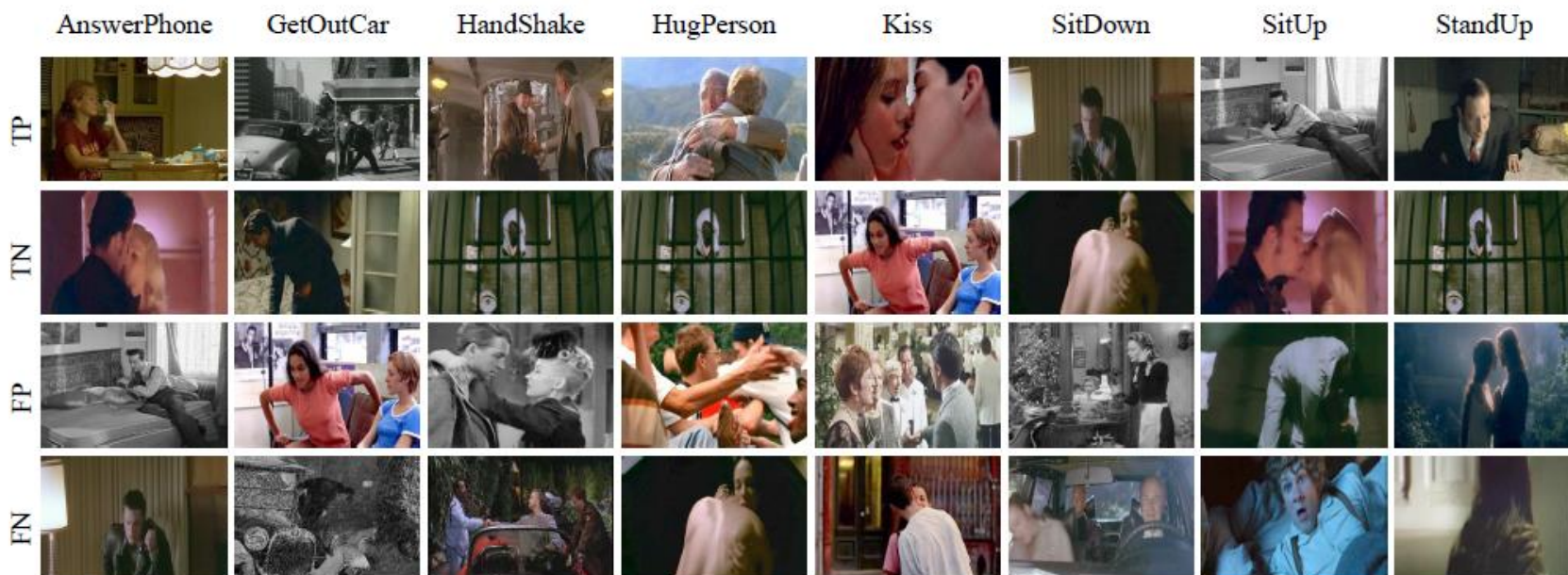


Interest Points



Spatio-Temporal Binning

Results



Task	HoG BoF	HoF BoF	Best channel	Best combination
KTH multi-class	81.6%	89.7%	91.1% (hof h3x1 t3)	91.8% (hof 1 t2, hog 1 t3)
Action AnswerPhone	13.4%	24.6%	26.7% (hof h3x1 t3)	32.1% (hof o2x2 t1, hof h3x1 t3)
Action GetOutCar	21.9%	14.9%	22.5% (hof o2x2 1)	41.5% (hof o2x2 t1, hog h3x1 t1)
Action HandShake	18.6%	12.1%	23.7% (hog h3x1 1)	32.3% (hog h3x1 t1, hog o2x2 t3)
Action HugPerson	29.1%	17.4%	34.9% (hog h3x1 t2)	40.6% (hog 1 t2, hog o2x2 t2, hog h3x1 t2)
Action Kiss	52.0%	36.5%	52.0% (hog 1 1)	53.3% (hog 1 t1, hof 1 t1, hof o2x2 t1)
Action SitDown	29.1%	20.7%	37.8% (hog 1 t2)	38.6% (hog 1 t2, hog 1 t3)
Action SitUp	6.5%	5.7%	15.2% (hog h3x1 t2)	18.2% (hog o2x2 t1, hog o2x2 t2, hog h3x1 t2)
Action StandUp	45.4%	40.0%	45.4% (hog 1 1)	50.5% (hog 1 t1, hof 1 t2)

Action Recognition using Pose and Objects



[Modeling Mutual Context of Object and Human Pose in Human-Object Interaction Activities](#), B. Yao and Li Fei-Fei, 2010

Human-Object Interaction

Holistic image based classification



Integrated reasoning

- **Human pose estimation**



Human-Object Interaction

Holistic image based classification



Integrated reasoning

- Human pose estimation
- **Object detection**



Human-Object Interaction

Holistic image based classification



Integrated reasoning

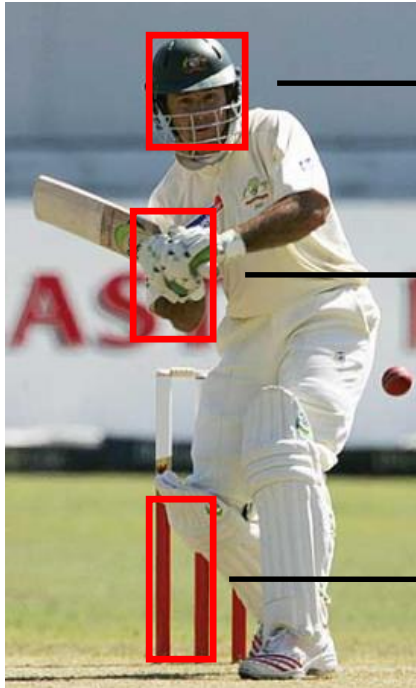
- **Human pose estimation**
- **Object detection**
- **Action categorization**



Activity: Tennis Forehand

Human pose estimation & Object detection

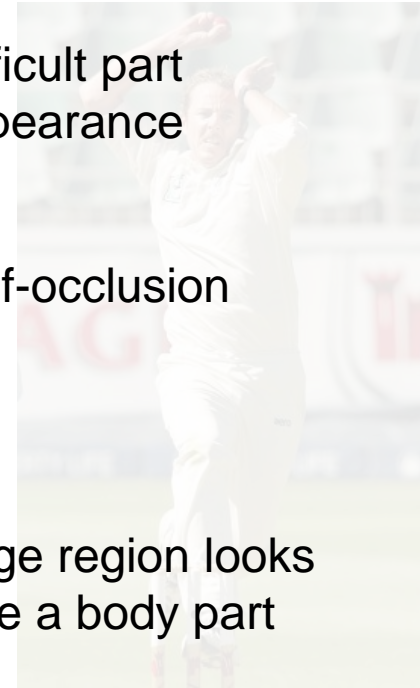
Human pose estimation is challenging.



Difficult part appearance

Self-occlusion

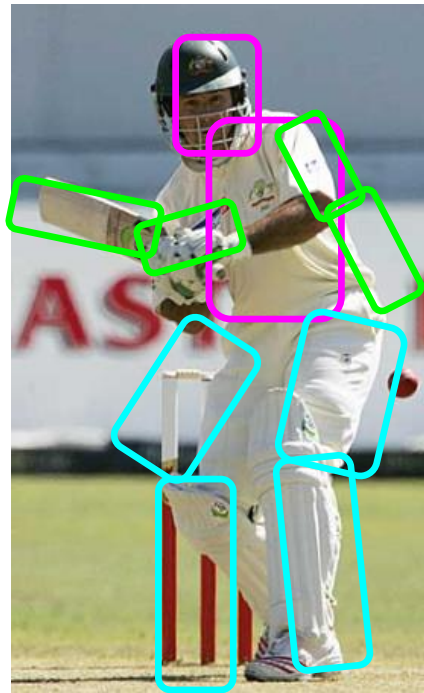
Image region looks like a body part



- Felzenszwalb & Huttenlocher, 2005
- Ren et al, 2005
- Ramanan, 2006
- Ferrari et al, 2008
- Yang & Mori, 2008
- Andriluka et al, 2009
- Eichner & Ferrari, 2009

Human pose estimation & Object detection

Human pose estimation is challenging.

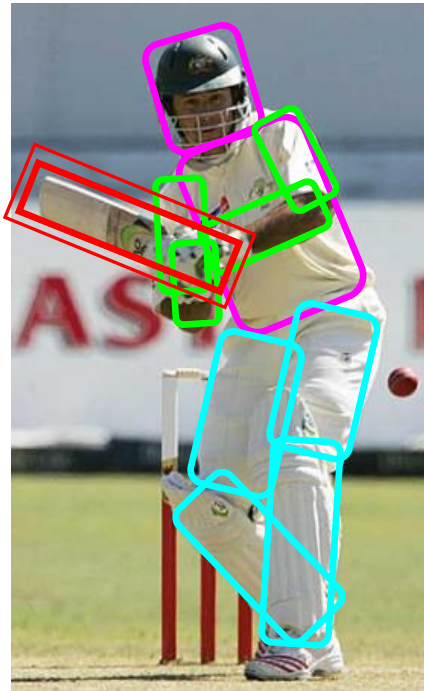


- Felzenszwalb & Huttenlocher, 2005
- Ren et al, 2005
- Ramanan, 2006
- Ferrari et al, 2008
- Yang & Mori, 2008
- Andriluka et al, 2009
- Eichner & Ferrari, 2009

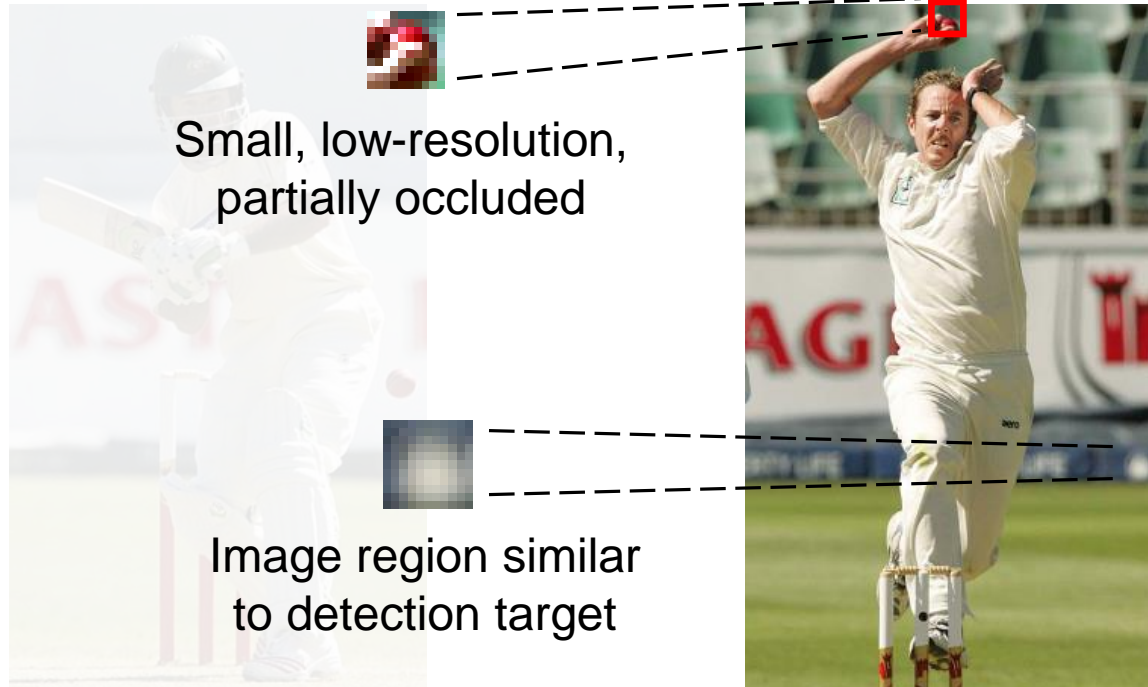
Human pose estimation & Object detection

Facilitate

Given the object is detected.



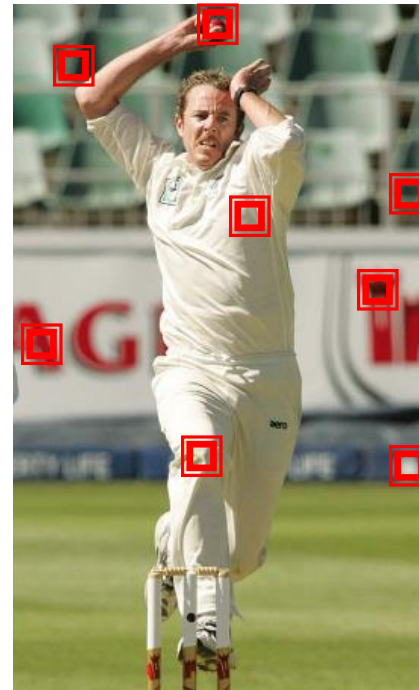
Human pose estimation & Object detection



Object
detection is
challenging

- Viola & Jones, 2001
- Lampert et al, 2008
- Divvala et al, 2009
- Vedaldi et al, 2009

Human pose estimation & Object detection

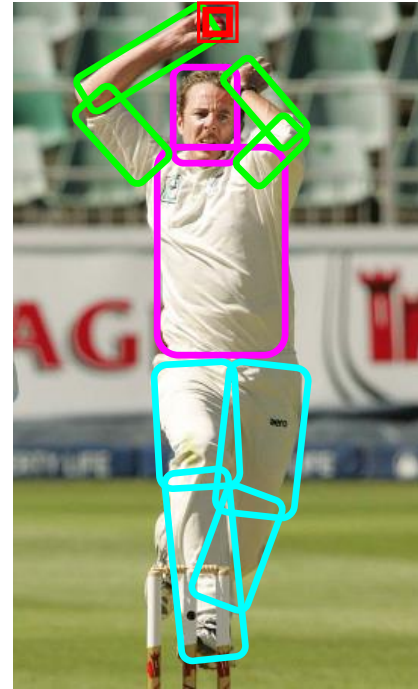


Object
detection is
challenging

- Viola & Jones, 2001
- Lampert et al, 2008
- Divvala et al, 2009
- Vedaldi et al, 2009

Human pose estimation & Object detection

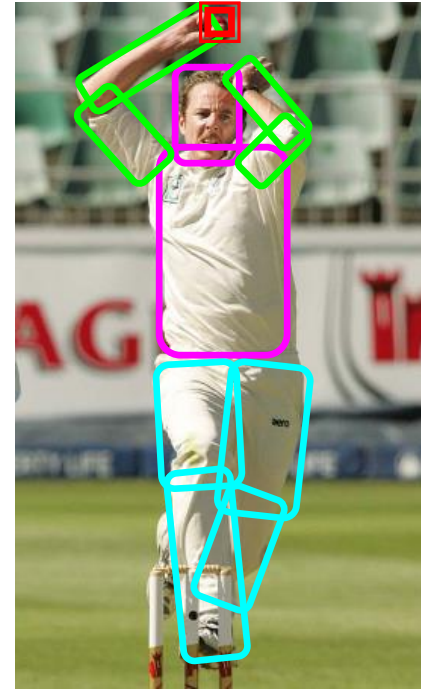
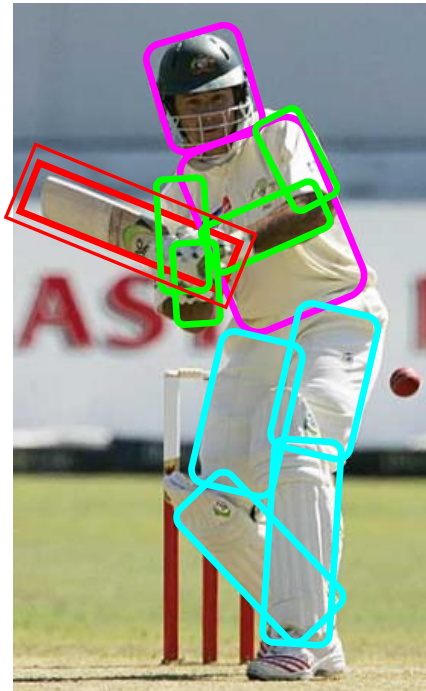
Facilitate



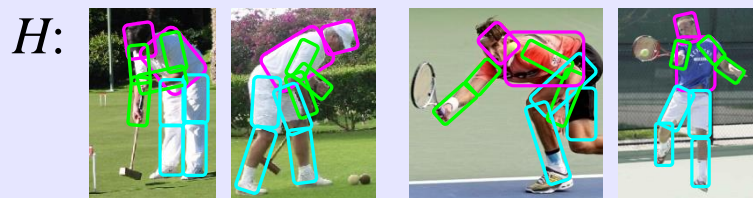
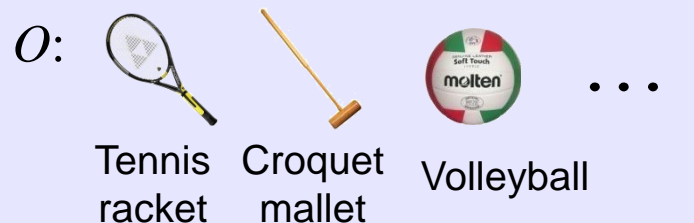
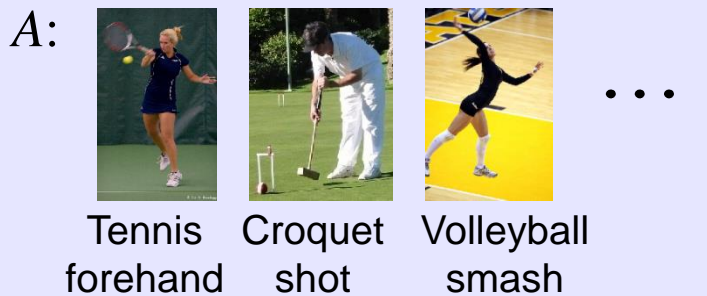
Given the pose is estimated.

Human pose estimation & Object detection

Mutual Context



Mutual Context Model Representation

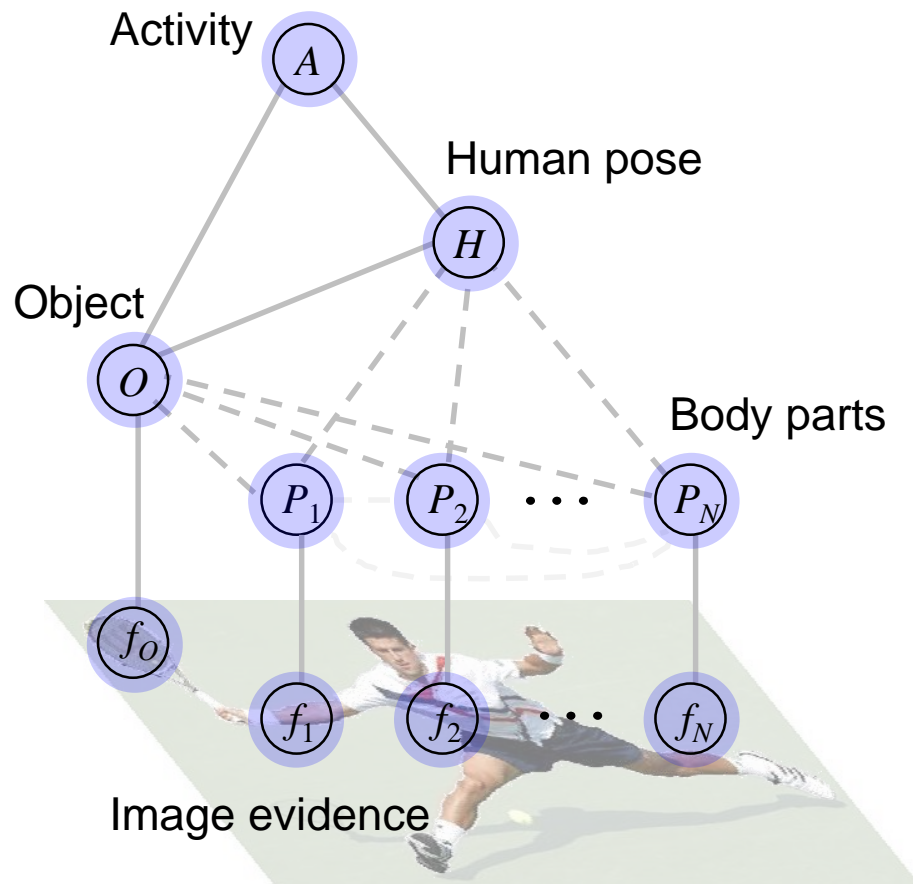


Intra-class variations

- More than one H for each A ;
- **Unobserved** during training.

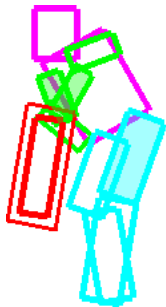
P : l_p : location; θ_p : orientation; s_p : scale.

f : Shape context. [Belongie et al, 2002]



Learning Results

Cricket defensive shot



Cricket bowling

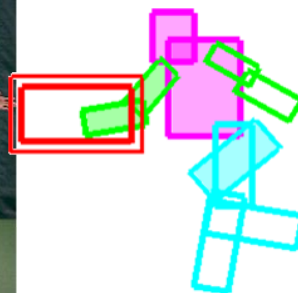


Croquet shot



Learning Results

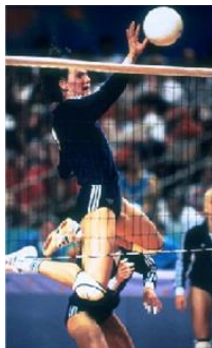
Tennis
forehand



Tennis
serve



Volleyball
smash

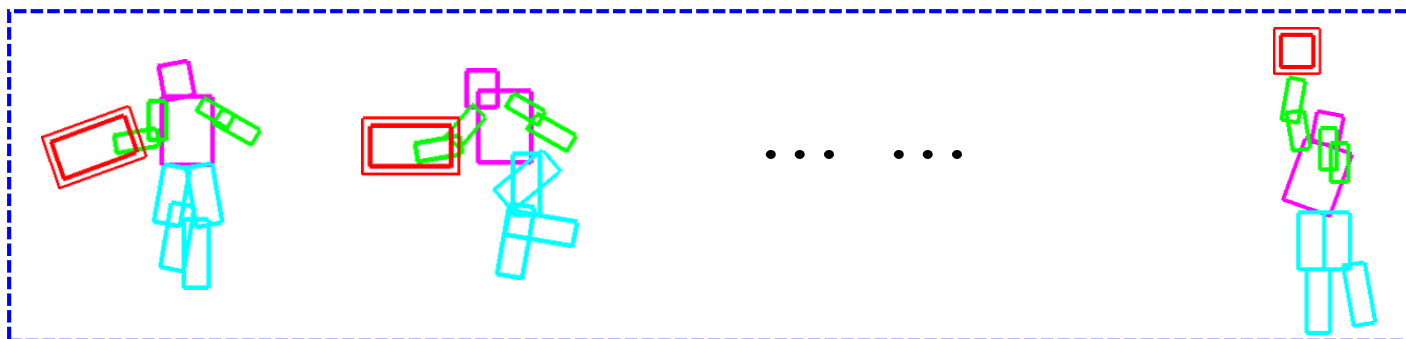


Model Inference

I



The learned models

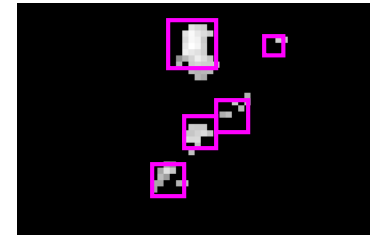
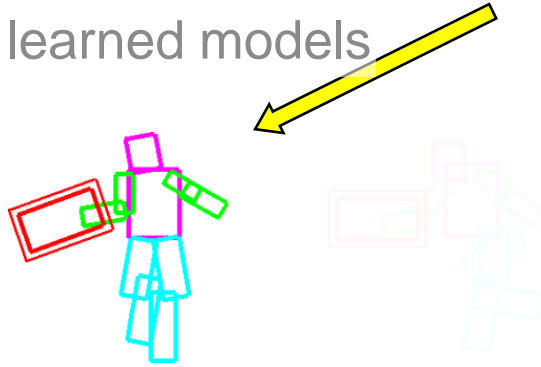


Model Inference

I



The learned models

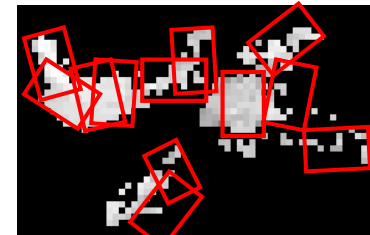


Head detection

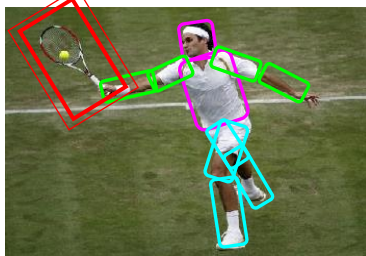


Torso detection

⋮



Tennis racket detection



$$\Psi\left(A_1, H_1, O_1^*, \{P_{1,n}^*\}_n\right)$$

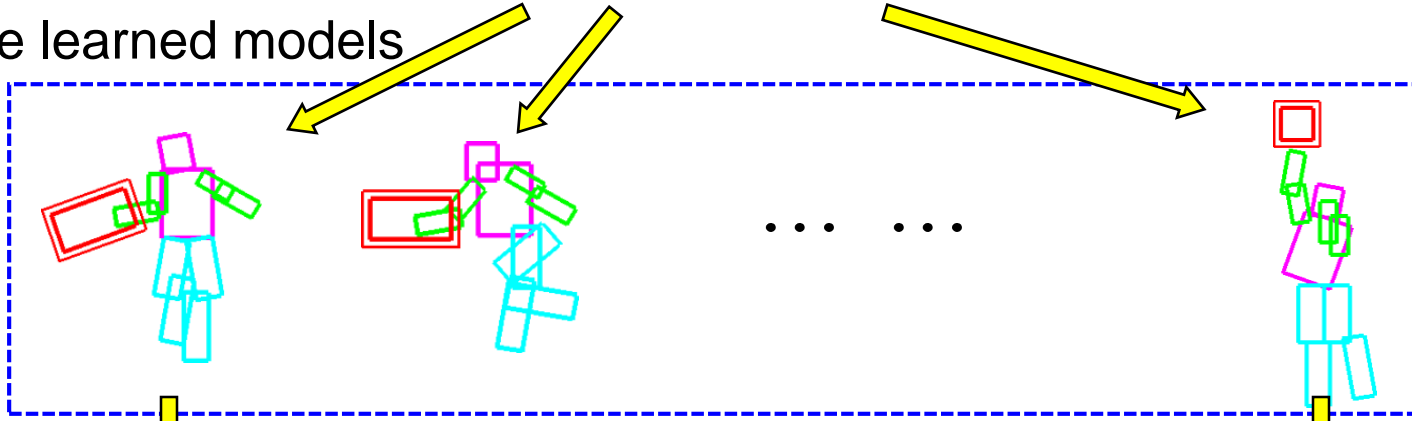
Layout of the **object** and **body parts**.

Model Inference

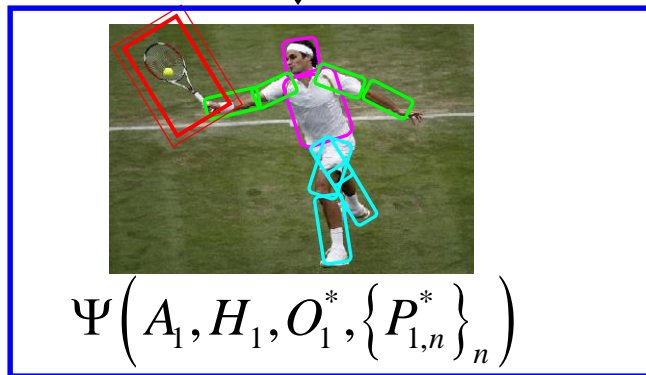
I



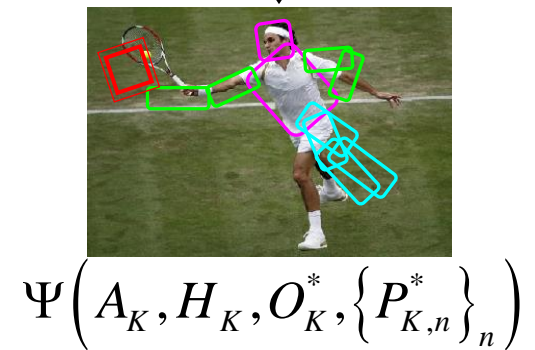
The learned models



Output



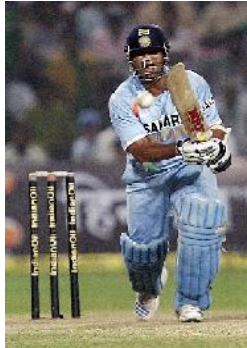
...



Dataset and Experiment Setup

Sport data set: 6 classes

180 training (supervised with object and part locations) & 120 testing images



Cricket
defensive shot



Cricket
bowling



Croquet
shot



Tennis
forehand



Tennis
serve



Volleyball
smash

Tasks:

- Object detection;
- Pose estimation;
- Activity classification.

[Gupta et al, 2009]

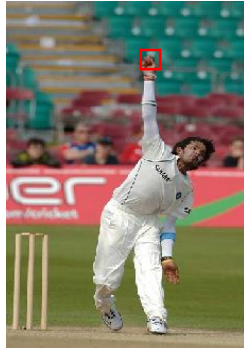
Dataset and Experiment Setup

Sport data set: 6 classes

180 training (supervised with object and part locations) & 120 testing images



Cricket
defensive shot



Cricket
bowling



Croquet
shot



Tennis
forehand



Tennis
serve



Volleyball
smash

Tasks:

- **Object detection;**
- Pose estimation;
- Activity classification.

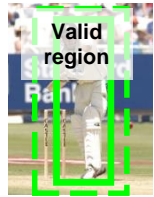
[Gupta et al, 2009]

Object Detection Results



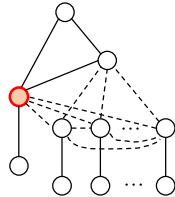
Sliding window

[Andriluka et al, 2009]



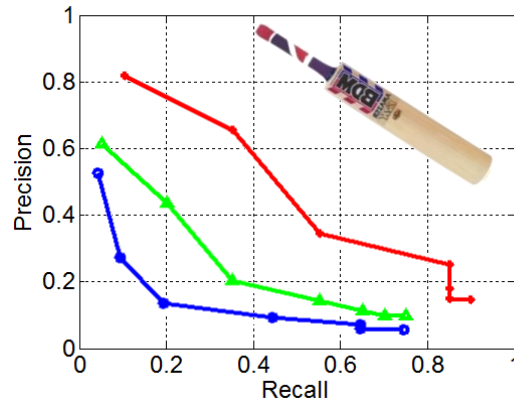
Pedestrian context

[Dalal & Triggs, 2006]

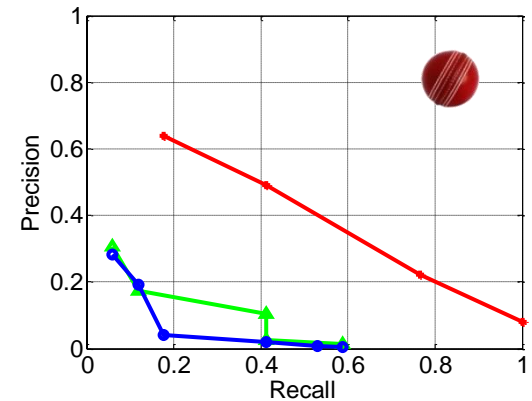


Our Method

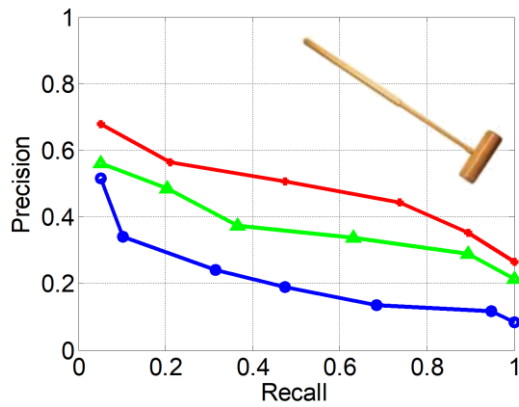
Cricket bat



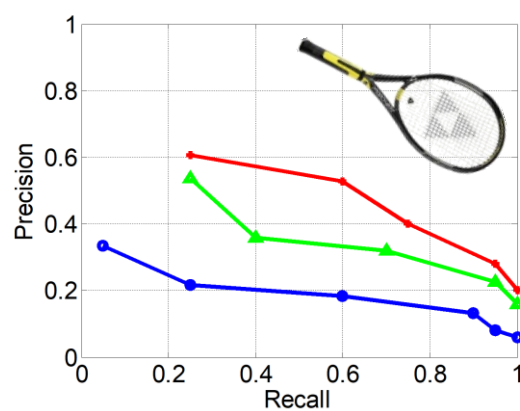
Cricket ball



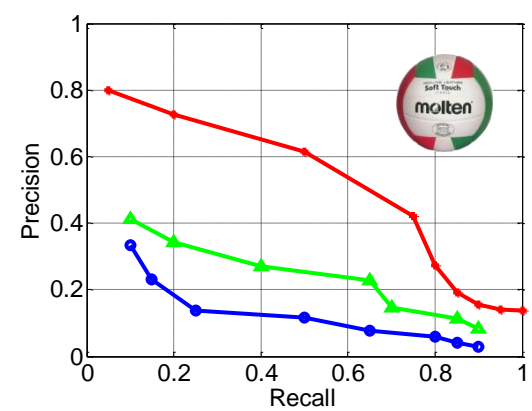
Croquet mallet



Tennis racket



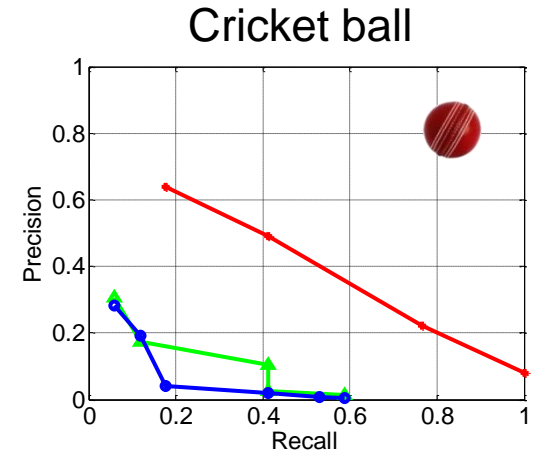
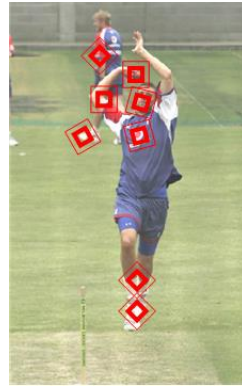
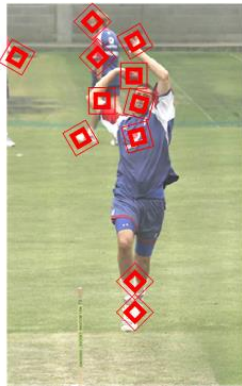
Volleyball



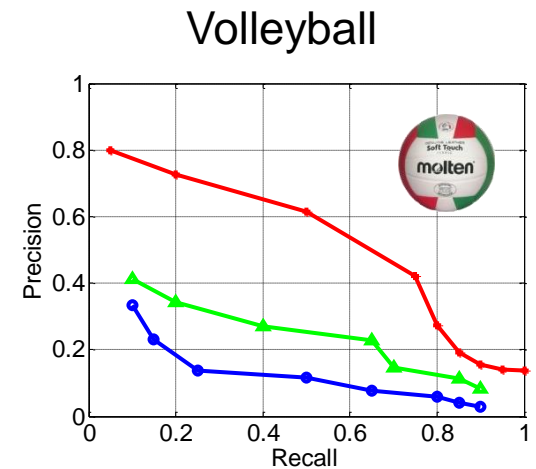
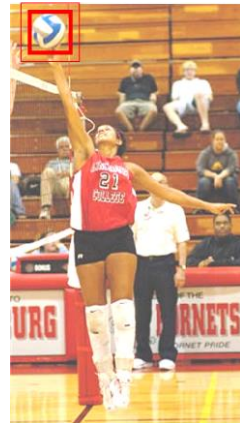
Object Detection Results

—●— Sliding window
 —▲— Pedestrian context
 —◆— Our method

Small object



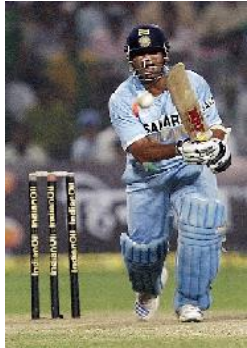
Background clutter



Dataset and Experiment Setup

Sport data set: 6 classes

180 training & 120 testing images



Cricket
defensive shot



Cricket
bowling



Croquet
shot



Tennis
forehand



Tennis
serve



Volleyball
smash

Tasks:

- Object detection;
- **Pose estimation;**
- Activity classification.

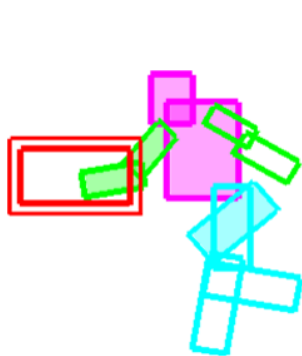
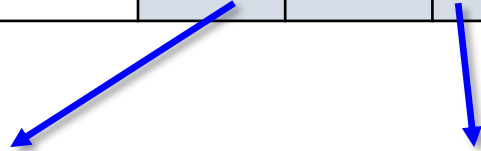
[Gupta et al, 2009]

Human Pose Estimation Results

Method	Torso	Upper Leg		Lower Leg		Upper Arm		Lower Arm		Head
Ramanan, 2006	.52	.22	.22	.21	.28	.24	.28	.17	.14	.42
Andriluka et al, 2009	.50	.31	.30	.31	.27	.18	.19	.11	.11	.45
Our full model	.66	.43	.39	.44	.34	.44	.40	.27	.29	.58

Human Pose Estimation Results

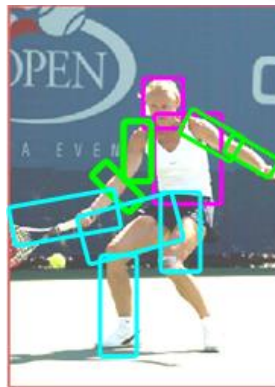
Method	Torso	Upper Leg		Lower Leg		Upper Arm		Lower Arm		Head
Ramanan, 2006	.52	.22	.22	.21	.28	.24	.28	.17	.14	.42
Andriluka et al, 2009	.50	.31	.30	.31	.27	.18	.19	.11	.11	.45
Our full model	.66	.43	.39	.44	.34	.44	.40	.27	.29	.58



Tennis serve model



Our estimation result



Andriluka et al, 2009



Volleyball smash model



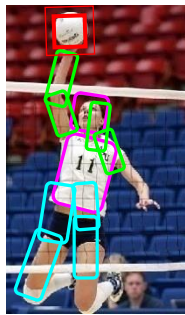
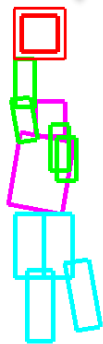
Our estimation result



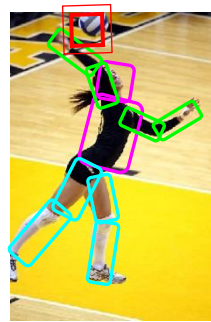
Andriluka et al, 2009

Human Pose Estimation Results

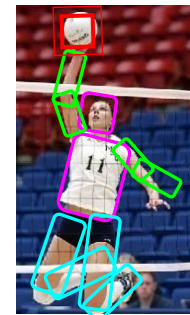
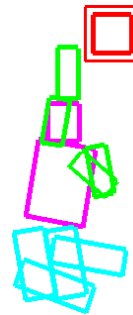
Method	Torso	Upper Leg	Lower Leg	Upper Arm	Lower Arm	Head				
Ramanan, 2006	.52	.22	.22	.21	.28	.24	.28	.17	.14	.42
Andriluka et al, 2009	.50	.31	.30	.31	.27	.18	.19	.11	.11	.45
Our full model	.66	.43	.39	.44	.34	.44	.40	.27	.29	.58
One pose per class	.63	.40	.36	.41	.31	.38	.35	.21	.23	.52



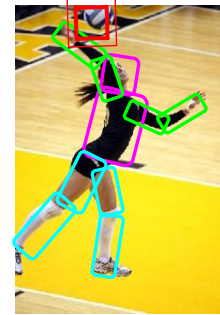
Estimation result



Estimation result



Estimation result



Estimation result

Dataset and Experiment Setup

Sport data set: 6 classes

180 training & 120 testing images



Cricket
defensive shot



Cricket
bowling



Croquet
shot



Tennis
forehand



Tennis
serve



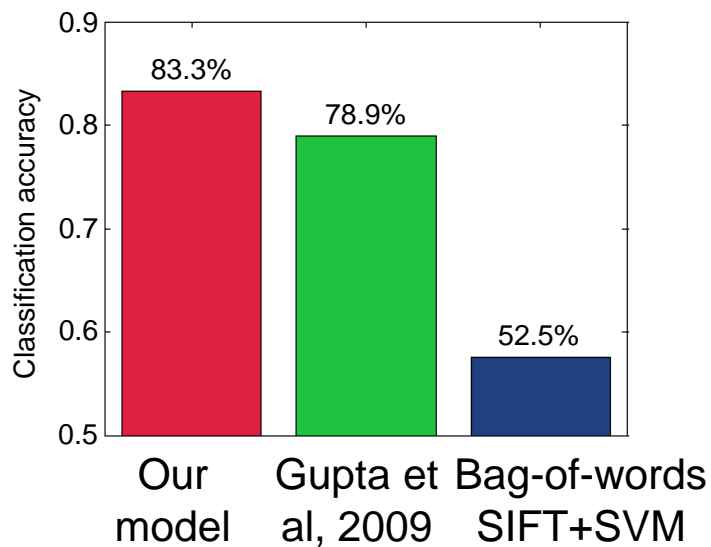
Volleyball
smash

Tasks:

- Object detection;
- Pose estimation;
- **Activity classification.**

[Gupta et al, 2009]

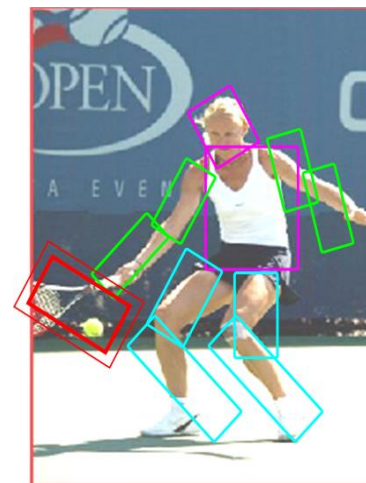
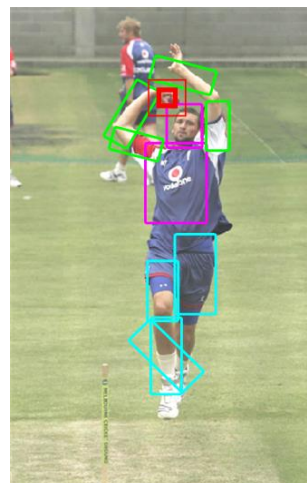
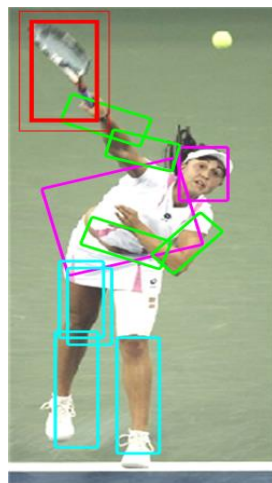
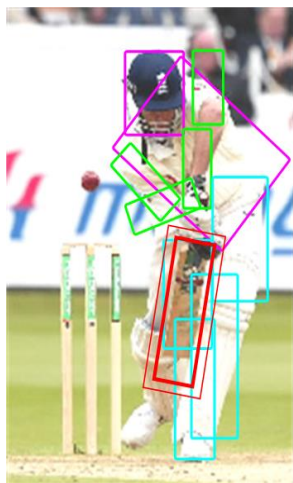
Activity Classification Results



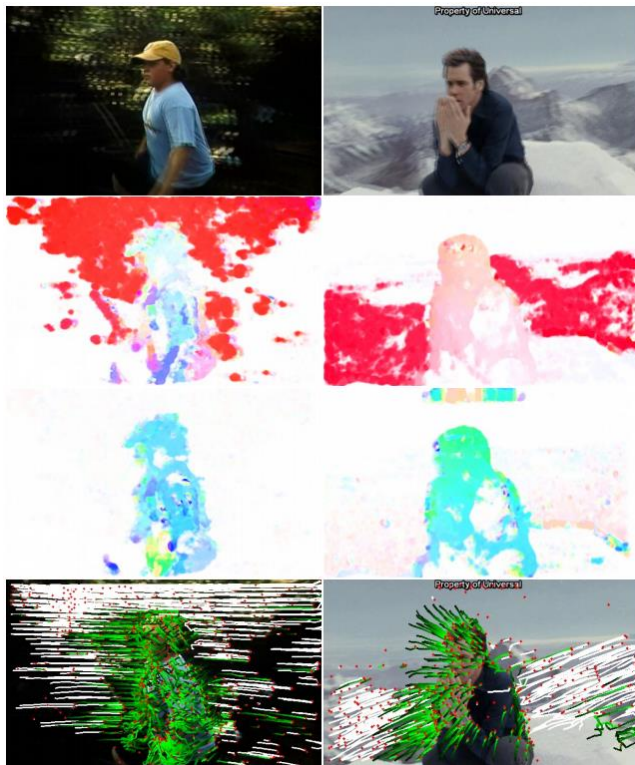
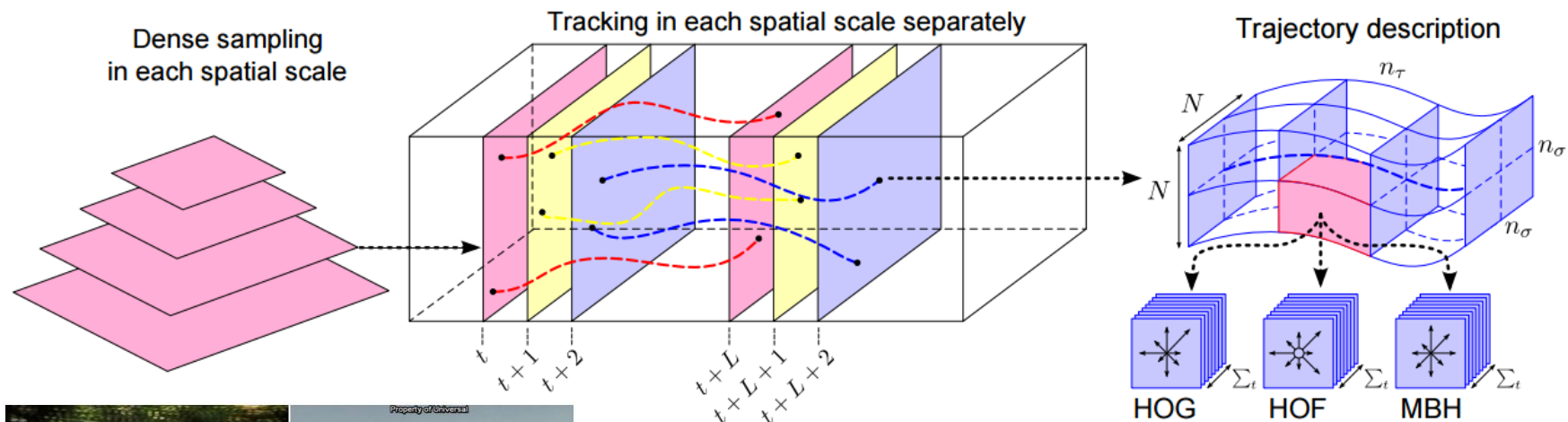
Cricket shot



Tennis forehand

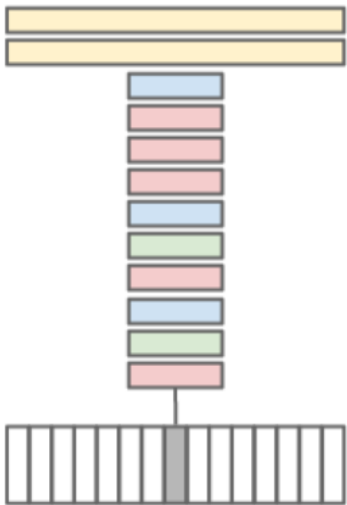


Motion features – Dense Trajectory

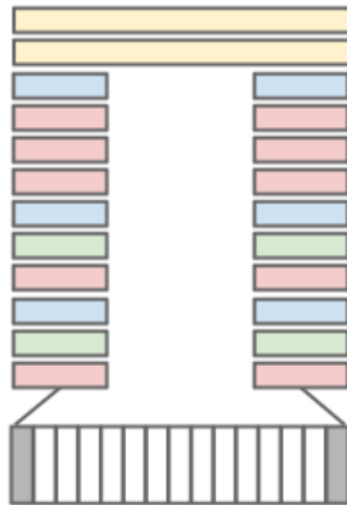


Video classification with CNNs

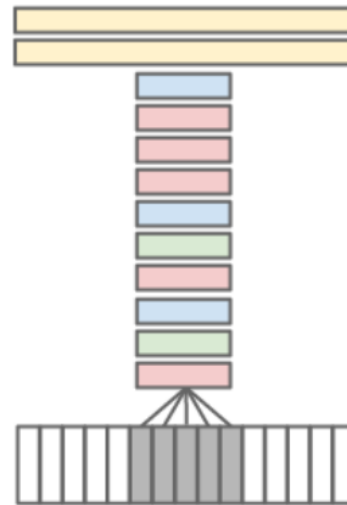
Single Frame



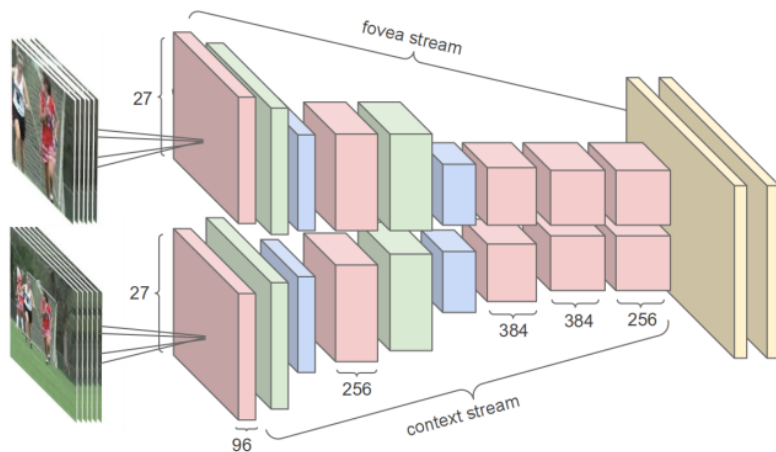
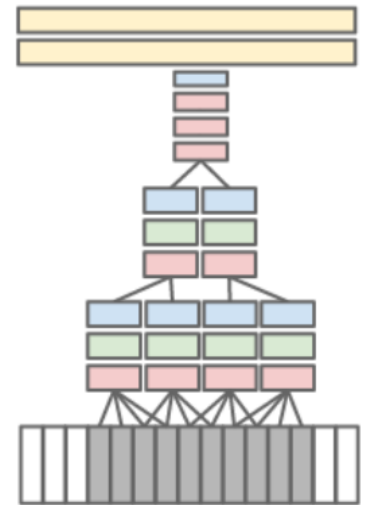
Late Fusion



Early Fusion



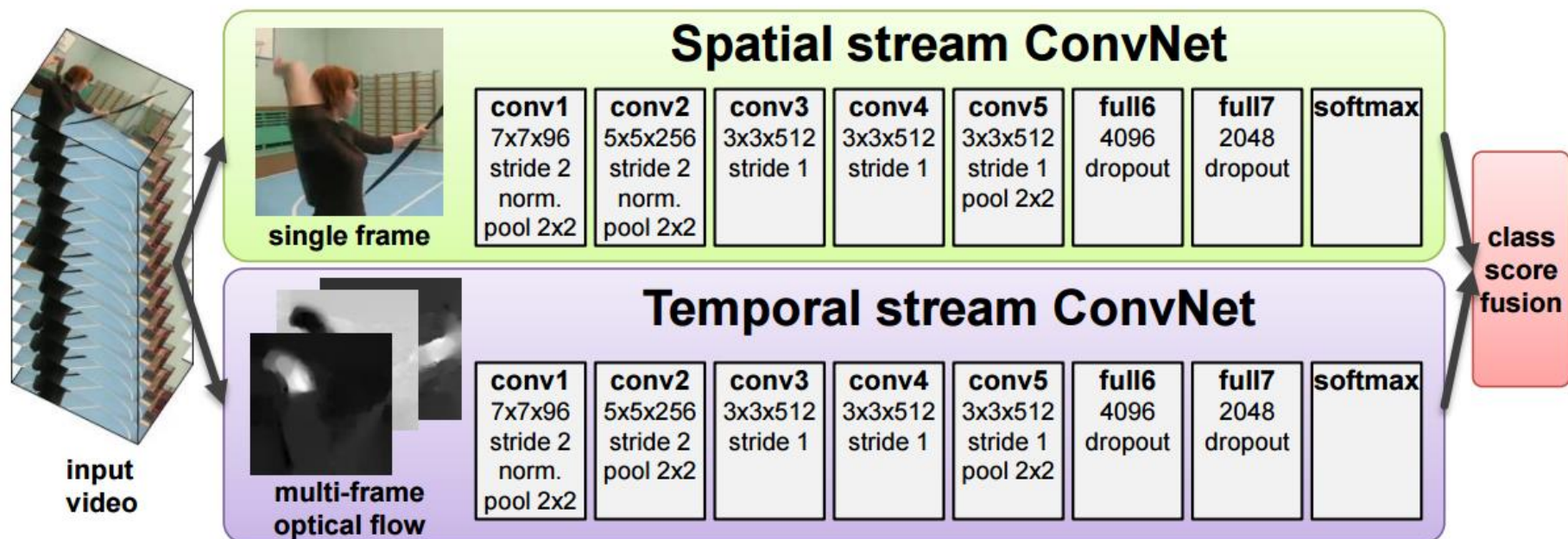
Slow Fusion



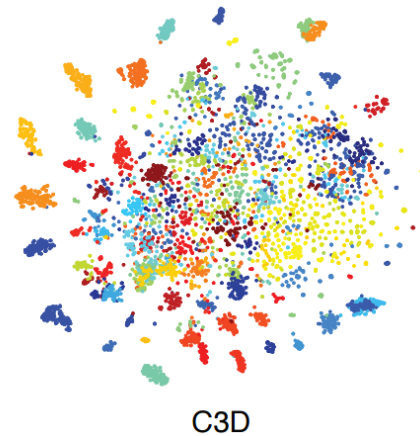
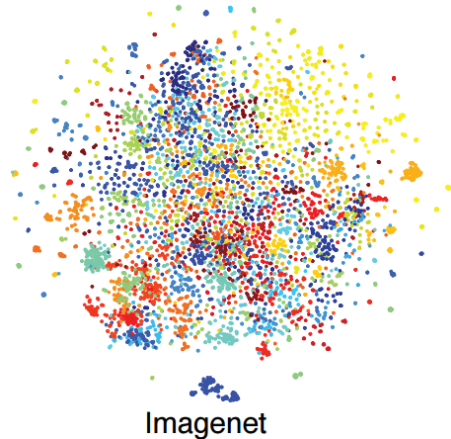
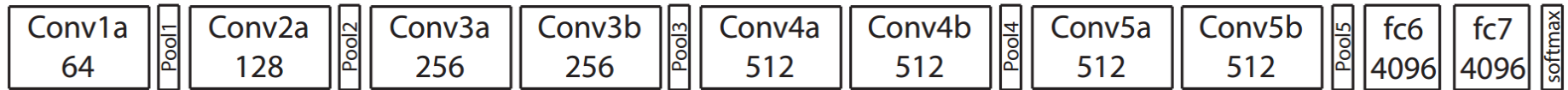
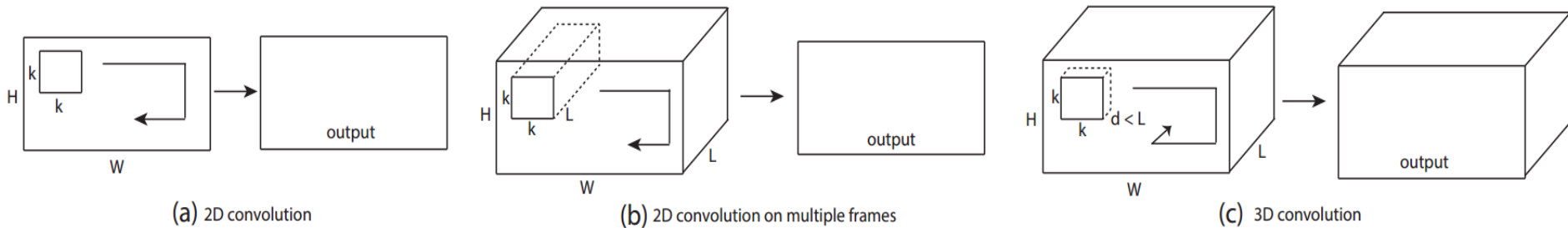
Video classification with CNNs

Sports Video Classification

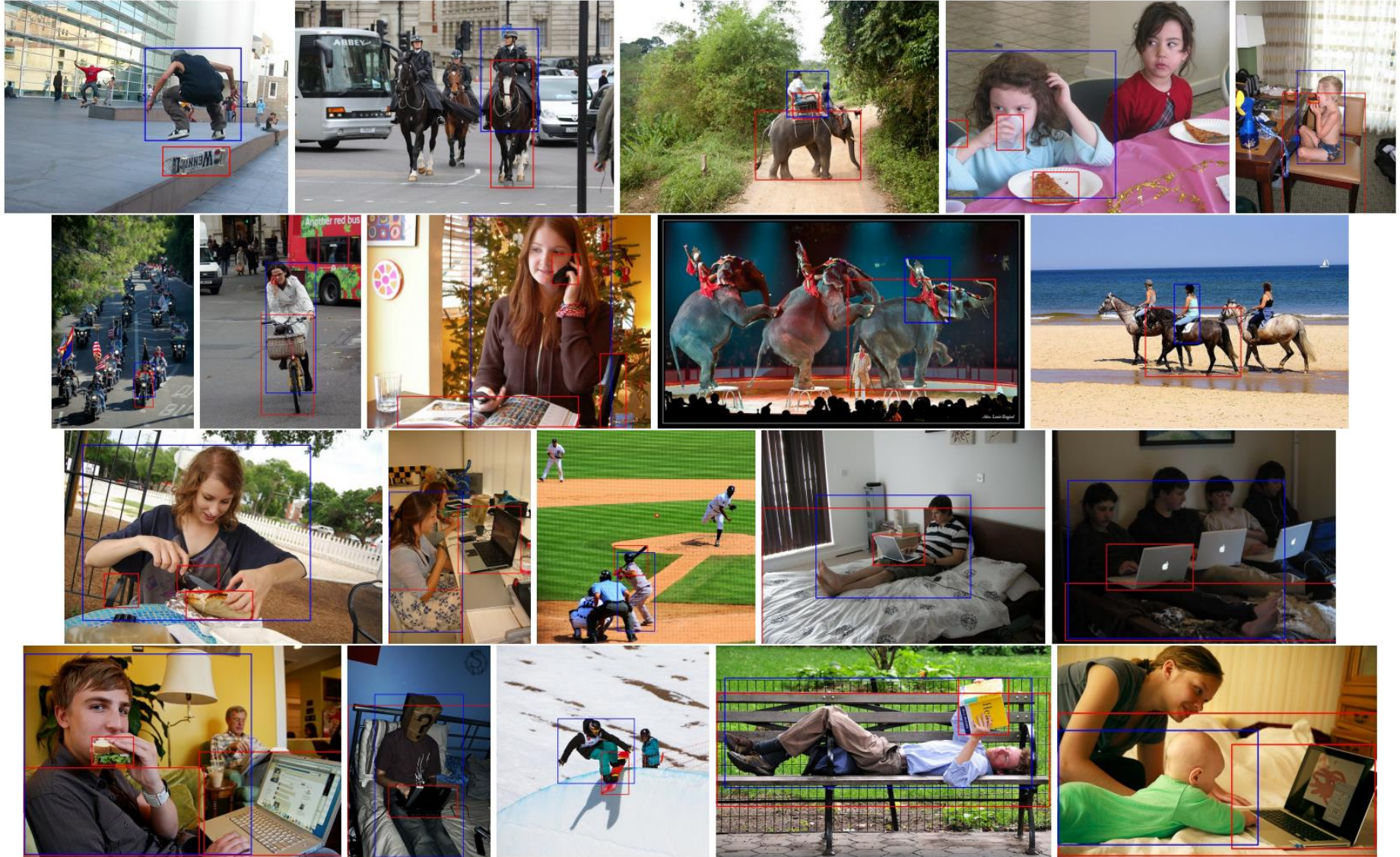
Two-stream CNN

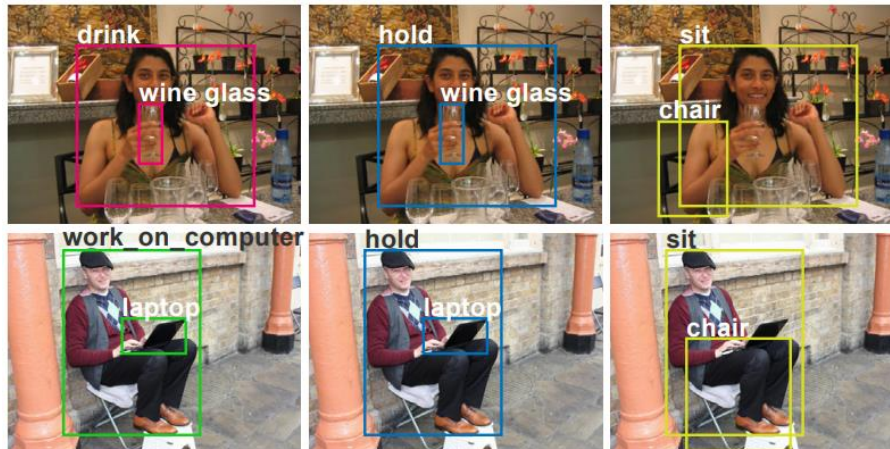
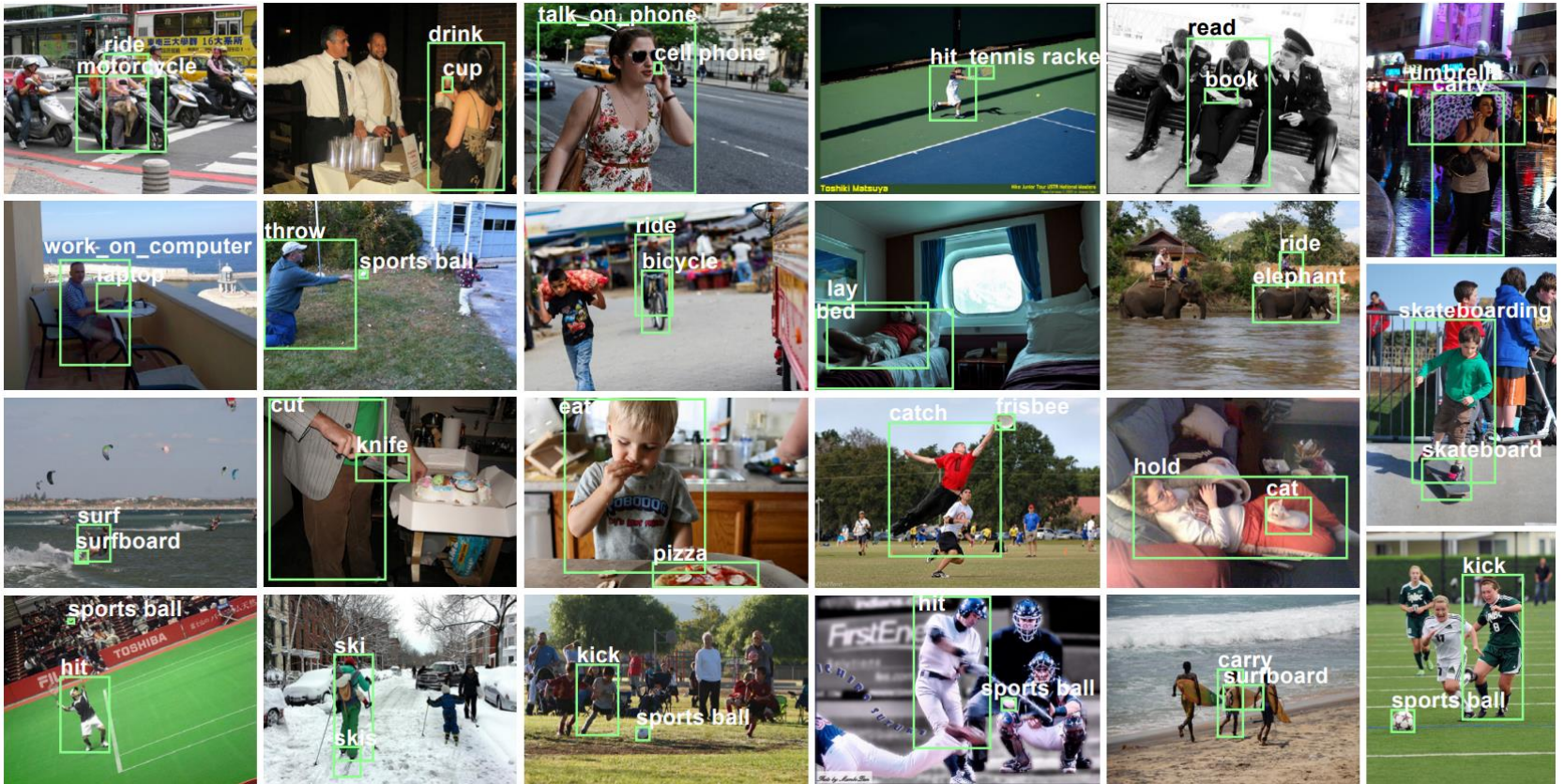


3D Convolutional Networks



Action recognition -> Semantic role Labeling





Take-home messages

- Action recognition is an open problem.
 - How to define actions?
 - How to infer them?
 - What are good visual cues?
 - How do we incorporate higher level reasoning?

Take-home messages

- Some work done, but it is just the beginning of exploring the problem. So far...
 - Actions are mainly categorical (could be framed in terms of effect or intent)
 - Most approaches are classification using simple features (spatial-temporal histograms of gradients or flow, s-t interest points, SIFT in images)
 - Just a couple works on how to incorporate pose and objects
 - Not much idea of how to reason about long-term activities or to describe video sequences